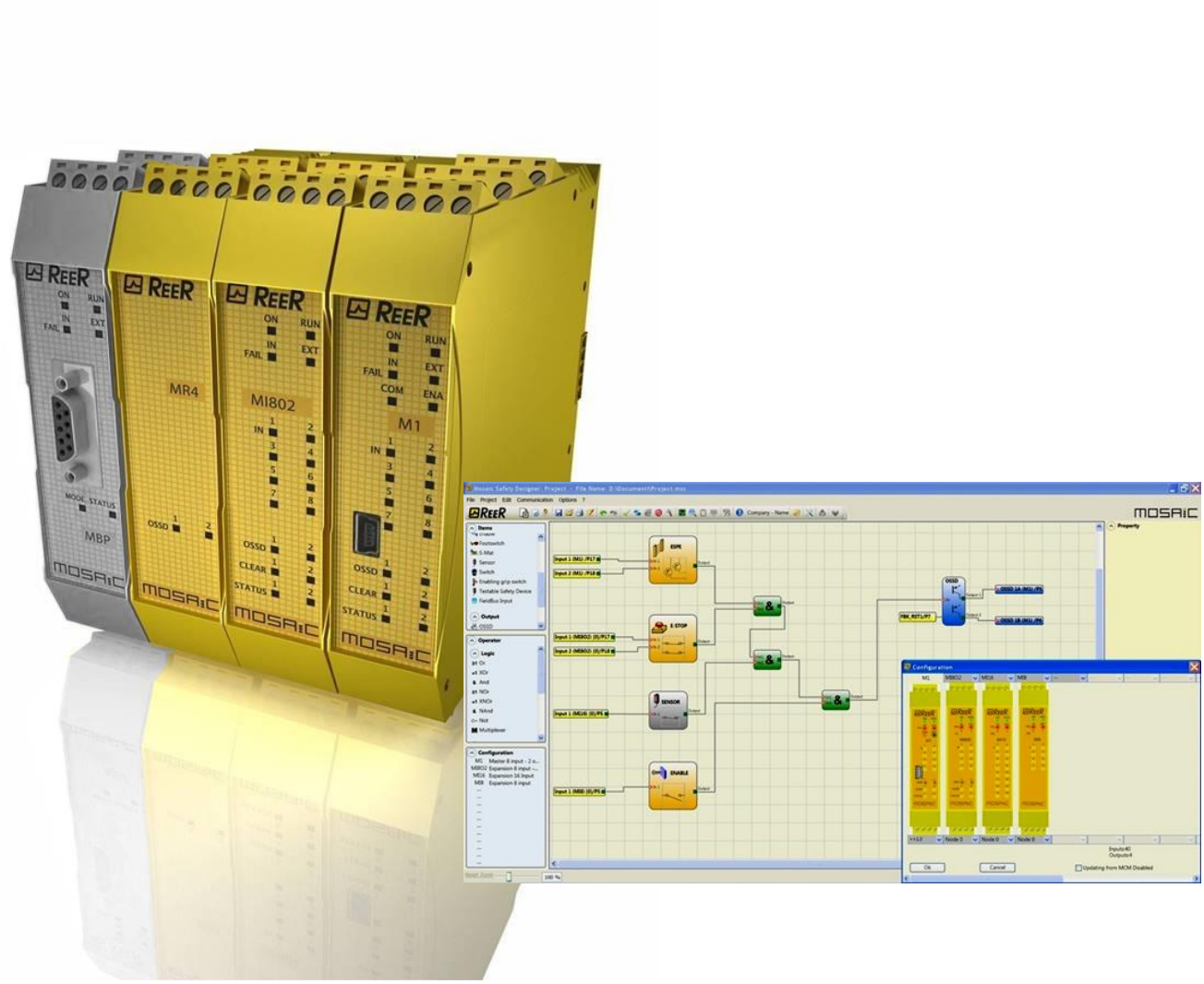
MOSAIC

MODULAR SAFETY INTEGRATED CONTROLLER



Installation and use

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(Copy of the original instructions)

MODULAR SAFETY INTEGRATED CONTROLLER

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INTRODUCTION

Contents of this handbook

This handbook describes how to use the MOSAIC programmable safety module and its expansion units ("SLAVES");

it includes:

- a description of the system
- method of installation
- connections
- signals
- troubleshooting
- use of the configuration SW

Important safety instructions

This safety alert symbol indicates a potential **personal safety hazard.** Failure to comply with instructions bearing this symbol could pose a very serious risk to personnel.

➔ This symbol indicates an important instruction.

- The MOSAIC is built to the following safety levels: SIL 3, SILCL 3, PL e, Cat. 4, Type 4 in accordance with the applicable standards. However, the definitive SIL and PL of the application will depend on the number of safety components, their parameters and the connections that are made, as per the risk analysis.
- Read the "Applicable Standards" section carefully.
- Perform an in-depth risk analysis to determine the appropriate safety level for your specific application, on the basis of all the applicable standards.
- Programming/configuration of the Mosaic is the sole responsibility of the installer or user.
- The device must be programmed/configured in accordance with the application-specific risk analysis and all the applicable standards.
- Once you have programmed/configured and installed the Mosaic and all the relative devices, run a complete application safety test (see "TESTING the system", page 76).
- Always test the complete system whenever new safety components are added (see the "TESTING the system" section, page 76).
- ReeR is not responsible for these operations or any risks in connection therewith.
- Reference should be made to the handbooks and the relative product and/or application standards to ensure correct use of devices connected to the Mosaic within the specific application.
- The ambient temperature in the place where the system is installed must be compatible with the operating temperature parameters stated on the product label and in the specifications.
- For all matters concerning safety, if necessary, contact your country's competent safety authorities or the competent trade association.

English

Abbreviations and symbols

MCM = MOSAIC Configuration Memory: *memory chip for MOSAIC M1 (accessory)*
MSC = MOSAIC Safety Communication: *proprietary bus for expansion units*
MSD = MOSAIC Safety Designer: *MOSAIC configuration SW running in Windows*
OSSD = Output Signal Switching Device: *solid state safety output*
MTTFd = Mean Time to Dangerous Failure
PL = Performance Level
PFH_d = Probability of a dangerous failure per Hour
SIL = Safety Integrity Level
SILCL = Safety Integrity Level Claim Limit
SW = Software

Applicable standards

MOSAIC complies with the following European Directives:

- **2006/42/EC** "Machinery Directive"
- **2014/30/EU** "Electromagnetic Compatibility Directive"
- **2014/35/EU** "Low Voltage Directive"

and is built to the following standards:

CEI EN 61131-2	Programmable controllers, part 2: Equipment requirements and tests
EN ISO 13489-1	Safety of machinery: Safety related parts of control systems. General principles for design
EN 61496-1	Safety of machinery: Electro-sensitive protective equipment. Part 1: General requirements and tests.
IEC 61508-1	Functional safety of electrical/electronic/programmable electronic safety-related systems: General requirements.
IEC 61508-2	Functional safety of electrical/electronic/programmable electronic safety-related systems: Requirements for electrical/electronic/programmable electronic safety-related systems.
IEC 61508-3	Functional safety of electrical/electronic/programmable electronic safety-related systems: Software requirements.
IEC 61508-4	Functional safety of electrical/electronic programmable electronic safety related systems: Definitions and abbreviations.
IEC 61784-3	Digital data communication for measurement and control: Functional safety fieldbuses.
IEC 62061	Safety of machinery. Functional safety of safety-related electrical, electronic and programmable electronic control systems

Table 1

English

OVERVIEW

MOSAIC is a modular safety controller. It consists of a master unit **(M1)**, which can be configured using the MSD graphic interface, and a number of expansion units connected to the M1 via the proprietary MSC bus.

The M1 can also be used as a stand-alone device. It has 8 safety inputs and 2 independent programmable dual channel outputs.

➔ The following expansions are available: I/O expansions **(MI8O2)**, input only expansions **(MI8, MI12T8, MI16, MV0, MV1 and MV2)**, output only expansions **(MO2 and MO4)**, signaling only expansions **(MOS8 and MOS16)**, guided contact safety relay output modules **(MR2, MR4, MOR4 and MOR4S8)** and diagnostic connections to the main fieldbuses: **MBP** (PROFIBUS), **MBC** (CanOpen), **MBD** (DeviceNet), **MBEI** (ETHERNET/IP), **MBEI2B** (ETHERNET/IP-2PORT), **MBEP** (Profinet), **MBEC** (ETHERCAT), **MBMR** (Modbus RTU), **MBEM** (Modbus/TCP).

MOSAIC is capable of monitoring the following safety sensors and commands:

optoelectronic sensors (safety light curtains, scanners, safety photocells), mechanical switches, safety mats, emergency stops, two-hand controls, all managed by a single flexible and expandable device.

The system must consist of just one Master M1 and a number of electronic expansions that can range from 0 to a maximum of 14, not more than 4 of which of the same type. There is no limit to the number of relay modules that can be installed.

With 14 expansions, the system can have up to 128 inputs, 16 dual channel safety outputs and 16 status outputs. The MASTER and its SLAVE units communicate via the 5-way MSC bus (ReeR proprietary bus), physically arranged on the rear panel of each unit.

Furthermore 8 inputs and 16 outputs probe controllable (by Fieldbus) are available.

With the **MI8, MI16** and **MI12T8** Mosaic expansion units, the number of inputs in the system can be increased to allow more external devices to be connected. The **MI12T8** also provides 8 OUT_TEST outputs.

The **MO2** and **MO4** Mosaic expansion units provide the system, respectively, with 2 and 4 OSSD (Output Signal Switching Device) pairs for controlling devices connected downstream of the **MOSAIC**.

The **MI802** has 8 inputs and 2 OSSD outputs.

The **MR2** and **MR4** Mosaic expansion units provide the system with 2 and 4 N.O. guided contact safety relay outputs, respectively, with the related external relay feedback (N.C. contact).

The expansion units in the **MB** series permit connection to the most commonly used industrial fieldbus systems for diagnostics and data transmission.

The **MBEI**, **MBEI2B, MBEP, MBEM** and **MBEC** also have an ethernet connection. The **MBU** permits connection to devices with a USB port.

English

The **MCT1** and **MCT2 Mosaic** units are used to connect the M1 to other slave units installed at a distance (< 50 m). Two MCT units installed at the required distance can be connected using a shielded cable (ReeR MC25, MC50 or other cable with the characteristics set out in the cable data sheet).

The **MV0**, **MV1** and **MV2** Mosaic expansion units can be used to control the following (up to PLe):

- Zero speed, Max. speed, Speed range;
- Direction of movement, rotation/translation;

Up to 4 speed thresholds can be set for each logic output (axis).

Each unit incorporates two logic outputs that can be configured using the MSD software and is thus capable of controlling up to two independent axes.

The **MOR4** and **MOR4S8** are safety units provided with 4 independent safety relay outputs and the corresponding 4 inputs for the external feedback contacts (EDM).

There are two possible output settings (configured using the MSD configuration software).

- Two pairs of connection contacts (2 N.O. contacts per output with 2 corresponding feedback inputs).
- Four independent single connection contacts (1 N.O. contact per output with 1 corresponding feedback input).

Only the MOR4S8 unit has 8 programmable signal outputs.

The **MOS8** and **MOS16** have 8 and 16 programmable signal outputs.

The MSD software is capable of creating complex logics, using logical operators and safety functions such as muting, timer, counters, etc.

All this is performed through an easy and intuitive graphic interface.

The configuration performed on the PC is sent to the M1 via USB connection; the file resides in the M1 and can also be saved on the proprietary MCM memory chip (accessory). The configuration can therefore quickly be copied to another M1 unit.

➔ The MOSAIC system is certified to the maximum safety level envisaged by the applicable industrial safety standards (SIL 3, SILCL 3, PL e, Cat. 4).

English

PRODUCT COMPOSITION

The MOSAIC M1 is supplied with:

- CD-ROM containing the free MSD SW, this PDF multi-language handbook and other product literature.
- Multi-language installation sheet.

➔ NB: the rear panel MSC connector and MCM memory can be ordered separately as accessories.

The expansion units are supplied with:

- Multilingual Installation sheet.
- Rear panel MSC connector (not present in the MR2 and MR4 which are connected via terminal blocks only).

➔ NB: to install an expansion unit (excluding relays) you will need the MSC connector supplied with the unit plus another MSC for the connection to the M1. This can be ordered separately as an accessory.

INSTALLATION

Mechanical fastening

Fix the MOSAIC system units to a 35mm DIN rail as follows:

1. Connect the same number of "MSC" 5-pole rear panel connectors as the number of units to be installed.
2. Fix the train of connectors thus obtained to the Omega DIN 35mm (EN 5022) rail (hooking them at the top first).
3. Fasten the units to the rail, arranging the contacts on the base of the unit on the respective connector. Press the unit gently until you feel it snap into place.
4. To remove a unit, use a screwdriver to pull down the locking latch on the back of the unit; then lift the unit upwards and pull.

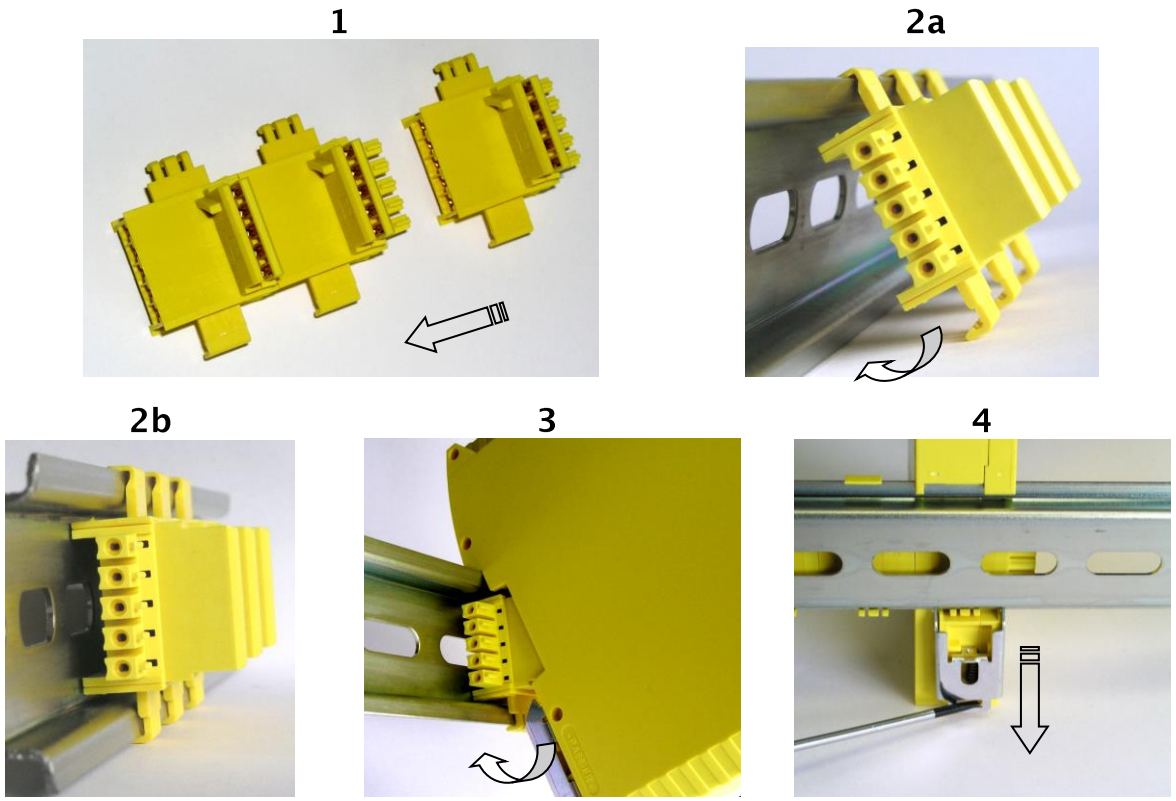


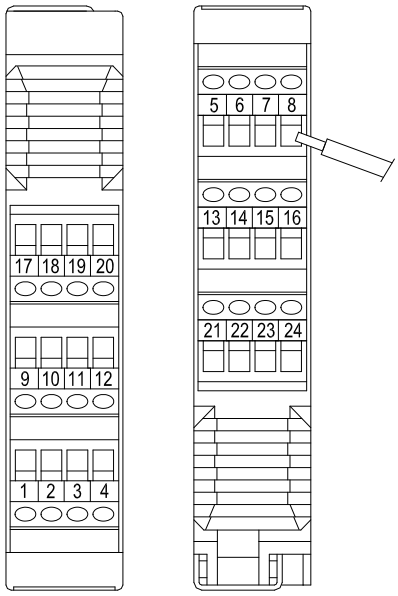
Figure 1

Calculation of safety distance of an ESPE connected to MOSAIC

Any Electro-sensitive Protective Equipment device connected to MOSAIC, must be positioned at a distance equal to or greater than the minimum safety distance **S** so that the dangerous point can be reached only after stopping the dangerous movement of the machine.

- The european standard:
  - ISO 13855:2010- (EN 999:2008) Safety of machinery - *Positioning of safeguards with respect to the approach speeds of parts of the human body.*[1]
  provides the elements to calculate the proper safety distance.
- Carefully read the installation manual of each device for specific information on the correct positioning.
- Remember that the total response time depends on:
  MOSAIC response time + ESPE response time + response time of the machine (i.e. the time taken by the machine to stop the dangerous movement from the moment in which the stop signal is transmitted).

Electrical connections



The MOSAIC system units are provided with terminal blocks for the electrical connections. Each unit can have 8, 16 or 24 terminals.
Each unit also has a rear panel plug-in connector (for communication with the master and with the other expansion units).

The MR2 and MR4 are connected via terminal blocks only.

➔ Terminal tightening torque: 5÷7lb-in (0,6÷0,7 Nm).

- Install safety units in an enclosure with a protection class of at least IP54.
- Connect the module when it is not powered.
- The supply voltage to the units must be 24Vdc ±20% (PELV, in compliance with the standard EN 60204-1 (Chapter 6.4)).
- Do not use the MOSAIC to supply external devices.
- The same ground connection (0VDC) must be used for all system components.

[1] "Describe the methods that designers can use to calculate the minimum safety distance from a specific dangerous point for the safety devices, particularly Electro-sensitive devices (eg. light curtains), safety-mats or pressure sensitive floors and bimanual control. It contains a rule to determine the placement of safety devices based on approach speed and the stopping time of the machine, which can reasonably be extrapolated so that it also includes the interlocking guards without guard locking."

English

Instructions concerning connection cables.

- ➔ Wire size range: AWG 12÷30, (solid/stranded) (UL).
- ➔ Use 60/75°C copper (Cu) conductor only.
- ➔ We recommend the use of separate power supplies for the safety module and for other electrical power equipment (electric motors, inverters, frequency converters) or other sources of disturbance.
- ➔ Cables used for connections of longer than 50m must have a cross-section of at least 1mm2 (AWG16).

Connections of each single MOSAIC system unit are listed in the table below:

Module Master M1

TERMINAL	SIGNAL	TYPE	DESCRIPTION	OPERATION
1	24VDC	-	24VDC power supply	-
2	MASTER_ENABLE1	Input	Master Enable 1	Input (*"type B"* according to EN 61131-2)
3	MASTER_ENABLE2	Input	Master Enable 2	Input (*"type B"* according to EN 61131-2)
4	0VDC	-	0VDC power supply	-
5	OSSD1_A	Output	Static output 1	PNP active high
6	OSSD1_B	Output		PNP active high
7	RESTART_FBK1	Input	Feedback/Restart 1	Input according to EN 61131-2
8	OUT_STATUS1	Output	Programmable signal output	PNP active high
9	OSSD2_A	Output	Static output 2	PNP active high
10	OSSD2_B	Output		PNP active high
11	RESTART_FBK2	Input	Feedback/Restart 2	Input according to EN 61131-2
12	OUT_STATUS2	Output	Programmable signal output	PNP active high
13	OUT_TEST1	Output	Short circuit detected output	PNP active high
14	OUT_TEST2	Output	Short circuit detected output	PNP active high
15	OUT_TEST3	Output	Short circuit detected output	PNP active high
16	OUT_TEST4	Output	Short circuit detected output	PNP active high
17	INPUT1	Input	Digital input 1	Input according to EN 61131-2
18	INPUT2	Input	Digital input 2	Input according to EN 61131-2
19	INPUT3	Input	Digital input 3	Input according to EN 61131-2
20	INPUT4	Input	Digital input 4	Input according to EN 61131-2
21	INPUT5	Input	Digital input 5	Input according to EN 61131-2
22	INPUT6	Input	Digital input 6	Input according to EN 61131-2
23	INPUT7	Input	Digital input 7	Input according to EN 61131-2
24	INPUT8	Input	Digital input 8	Input according to EN 61131-2

English

USB input

The MOSAIC master M1 includes a USB 2.0 connector for connection to a Personal Computer where the **MSD** (MOSAIC Safety Designer) configuration SW resides.

A USB cable of the correct size is available as an accessory (**CSU**).

Figure 2 - USB 2.0 front panel connector

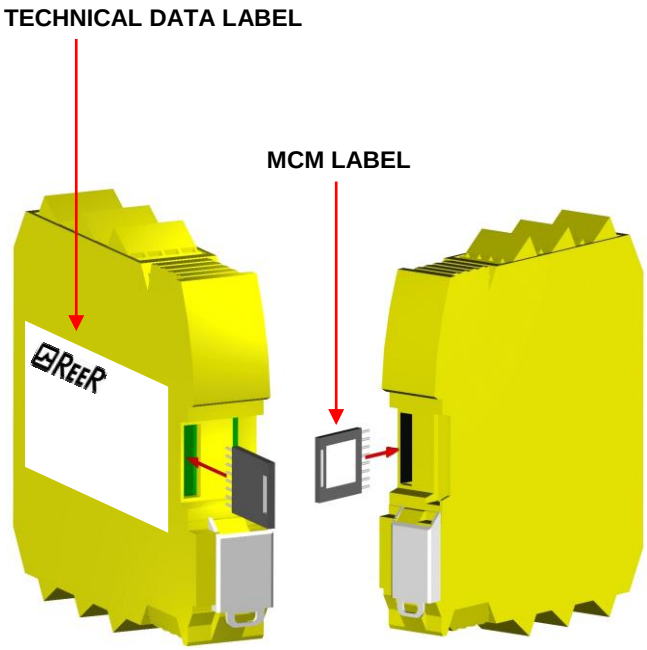


Figure 3 - MCM

MOSAIC Configuration Memory (MCM)

A backup memory, called **MCM** (optional) can be installed in the MOSAIC master M1 and used to save the SW configuration parameters.

The MCM is written **each time** a new project is sent from the PC to the M1.

➔ Always switch the M1 off before logging on to/logging off from the MCM.

Insert the card in the **slot in the rear panel of the M1** (in the direction shown in Figure 3 - MCM)**.**

MULTIPLE LOAD function

To perform the configuration of several M1 modules without using a PC and the USB connector, you can save the desired configuration on a single MCM and then use it to download data on the modules M1 to be configured.

If the file contained in the MCM is not identical to the one contained in M1, an overwrite operation that will permanently delete the configuration data contained in M1 will be performed.
WARNING: ALL DATA PREVIOUSLY CONTAINED IN M1 WILL BE LOST.

RESTORE function

If the M1 unit is damaged, you can replace it with a new one; having already saved all the configurations on the MCM, all you need to do is insert the MCM in the new M1 and

English

switch on the MOSAIC system, that will immediately load the backup configuration. In this way, the work interruptions will be minimized.

➔ The LOAD and RESTORE functions can be disabled via SW. (see Figure 40)

➔ In order to be used, the expansion units must be addressed at the time of installation (see the NODE SEL section).

✸ Each time MCM is used, carefully check that the chosen configuration is the one that was planned for that particular system. Try again a fully functional test of the system composed of Mosaic plus all devices connected to it (see the TESTING the system section).

Module MI8O2

TERMINAL	SIGNAL	TYPE	DESCRIPTION	OPERATION
1	24VDC	-	24VDC power supply	-
2	NODE_SEL0	Input	Node selection	Input (*"type B"* according to EN 61131-2)
3	NODE_SEL1	Input		Input (*"type B"* according to EN 61131-2)
4	0VDC	-	0VDC power supply	-
5	OSSD1_A	Output	Static output 1	PNP active high
6	OSSD1_B	Output		PNP active high
7	RESTART_FBK1	Input	Feedback/Restart 1	Input according to EN 61131-2
8	OUT_STATUS1	Output	Programmable signal output	PNP active high
9	OSSD2_A	Output	Static output 2	PNP active high
10	OSSD2_B	Output		PNP active high
11	RESTART_FBK2	Input	Feedback/Restart 2	Input according to EN 61131-2
12	OUT_STATUS2	Output	Programmable signal output	PNP active high
13	OUT_TEST1	Output	Short circuit detected output	PNP active high
14	OUT_TEST2	Output	Short circuit detected output	PNP active high
15	OUT_TEST3	Output	Short circuit detected output	PNP active high
16	OUT_TEST4	Output	Short circuit detected output	PNP active high
17	INPUT1	Input	Digital input 1	Input according to EN 61131-2
18	INPUT2	Input	Digital input 2	Input according to EN 61131-2
19	INPUT3	Input	Digital input 3	Input according to EN 61131-2
20	INPUT4	Input	Digital input 4	Input according to EN 61131-2
21	INPUT5	Input	Digital input 5	Input according to EN 61131-2
22	INPUT6	Input	Digital input 6	Input according to EN 61131-2
23	INPUT7	Input	Digital input 7	Input according to EN 61131-2
24	INPUT8	Input	Digital input 8	Input according to EN 61131-2

Table 2

English

Module MI8

TERMINAL	SIGNAL	TYPE	DESCRIPTION	OPERATION
1	24VDC	-	24VDC power supply	-
2	NODE_SEL0	Input	Node selection	Input (*"type B"* according to EN 61131-2)
3	NODE_SEL1	Input		Input (*"type B"* according to EN 61131-2)
4	0VDC	-	0VDC power supply	-
5	INPUT1	Input	Digital input 1	Input according to EN 61131-2
6	INPUT2	Input	Digital input 2	Input according to EN 61131-2
7	INPUT3	Input	Digital input 3	Input according to EN 61131-2
8	INPUT4	Input	Digital input 4	Input according to EN 61131-2
9	OUT_TEST1	Output	Short circuit detected output	PNP active high
10	OUT_TEST2	Output	Short circuit detected output	PNP active high
11	OUT_TEST3	Output	Short circuit detected output	PNP active high
12	OUT_TEST4	Output	Short circuit detected output	PNP active high
13	INPUT5	Input	Digital input 5	Input according to EN 61131-2
14	INPUT6	Input	Digital input 6	Input according to EN 61131-2
15	INPUT7	Input	Digital input 7	Input according to EN 61131-2
16	INPUT8	Input	Digital input 8	Input according to EN 61131-2

Table 3

Module MI12T8

TERMINAL	SIGNAL	TYPE	DESCRIPTION	OPERATION
1	24VDC	-	24VDC power supply	-
2	NODE_SEL0	Input	Node selection	Input (*"type B"* according to EN 61131-2)
3	NODE_SEL1	Input		Input (*"type B"* according to EN 61131-2)
4	0VDC	-	0VDC power supply	-
5	INPUT1	Input	Digital input 1	Input according to EN 61131-2
6	INPUT2	Input	Digital input 2	Input according to EN 61131-2
7	INPUT3	Input	Digital input 3	Input according to EN 61131-2
8	INPUT4	Input	Digital input 4	Input according to EN 61131-2
9	OUT_TEST1	Output	Short circuit detected output	PNP active high
10	OUT_TEST2	Output	Short circuit detected output	PNP active high
11	OUT_TEST3	Output	Short circuit detected output	PNP active high
12	OUT_TEST4	Output	Short circuit detected output	PNP active high
13	INPUT5	Input	Digital input 5	Input according to EN 61131-2
14	INPUT6	Input	Digital input 6	Input according to EN 61131-2
15	INPUT7	Input	Digital input 7	Input according to EN 61131-2
16	INPUT8	Input	Digital input 8	Input according to EN 61131-2
17	OUT_TEST5	Output	Short circuit detected output	PNP active high
18	OUT_TEST6	Output	Short circuit detected output	PNP active high
19	OUT_TEST7	Output	Short circuit detected output	PNP active high
20	OUT_TEST8	Output	Short circuit detected output	PNP active high
21	INPUT9	Input	Digital input 9	Input according to EN 61131-2
22	INPUT10	Input	Digital input 10	Input according to EN 61131-2
23	INPUT11	Input	Digital input 11	Input according to EN 61131-2
24	INPUT12	Input	Digital input 12	Input according to EN 61131-2

Table 4

English

Module MI16

TERMINAL	SIGNAL	TYPE	DESCRIPTION	OPERATION
1	24VDC	-	24VDC power supply	-
2	NODE_SEL0	Input	Node selection	Input (*"type B"* according to EN 61131-2)
3	NODE_SEL1	Input		Input (*"type B"* according to EN 61131-2)
4	0VDC	-	0VDC power supply	-
5	INPUT1	Input	Digital input 1	Input according to EN 61131-2
6	INPUT2	Input	Digital input 2	Input according to EN 61131-2
7	INPUT3	Input	Digital input 3	Input according to EN 61131-2
8	INPUT4	Input	Digital input 4	Input according to EN 61131-2
9	OUT_TEST1	Output	Short circuit detected output	PNP active high
10	OUT_TEST2	Output	Short circuit detected output	PNP active high
11	OUT_TEST3	Output	Short circuit detected output	PNP active high
12	OUT_TEST4	Output	Short circuit detected output	PNP active high
13	INPUT5	Input	Digital input 5	Input according to EN 61131-2
14	INPUT6	Input	Digital input 6	Input according to EN 61131-2
15	INPUT7	Input	Digital input 7	Input according to EN 61131-2
16	INPUT8	Input	Digital input 8	Input according to EN 61131-2
17	INPUT9	Input	Digital input 9	Input according to EN 61131-2
18	INPUT10	Input	Digital input 10	Input according to EN 61131-2
19	INPUT11	Input	Digital input 11	Input according to EN 61131-2
20	INPUT12	Input	Digital input 12	Input according to EN 61131-2
21	INPUT13	Input	Digital input 13	Input according to EN 61131-2
22	INPUT14	Input	Digital input 14	Input according to EN 61131-2
23	INPUT15	Input	Digital input 15	Input according to EN 61131-2
24	INPUT16	Input	Digital input 16	Input according to EN 61131-2

Table 5

Module MO4

TERMINAL	SIGNAL	TYPE	DESCRIPTION	OPERATION
1	24VDC	-	24VDC power supply	-
2	NODE_SEL0	Input	Node selection	Input (*"type B"* according to EN 61131-2)
3	NODE_SEL1	Input		Input (*"type B"* according to EN 61131-2)
4	0VDC	-	0VDC power supply	-
5	OSSD1_A	Output	Static output 1	PNP active high
6	OSSD1_B	Output		PNP active high
7	RESTART_FBK1	Input	Feedback/Restart 1	Input according to EN 61131-2
8	OUT_STATUS1	Output	Programmable signal output	PNP active high
9	OSSD2_A	Output	Static output 2	PNP active high
10	OSSD2_B	Output		PNP active high
11	RESTART_FBK2	Input	Feedback/Restart 2	Input according to EN 61131-2
12	OUT_STATUS2	Output	Programmable signal output	PNP active high
13	24VDC	-	24VDC power supply	24VDC outputs power supply *
14	24VDC	-	24VDC power supply	-
15	0VDC	-	0VDC power supply	0VDC outputs *
16	0VDC	-	0VDC power supply	-
17	OSSD4_A	Output	Static output 4	PNP active high
18	OSSD4_B	Output		PNP active high
19	RESTART_FBK4	Input	Feedback/Restart 4	Input according to EN 61131-2
20	OUT_STATUS4	Output	Programmable signal output	PNP active high
21	OSSD3_A	Output	Static output 3	PNP active high
22	OSSD3_B	Output		PNP active high
23	RESTART_FBK3	Input	Feedback/Restart 3	Input according to EN 61131-2
24	OUT_STATUS3	Output	Programmable signal output	PNP active high

Table 6

English

Module MO2

TERMINAL	SIGNAL	TYPE	DESCRIPTION	OPERATION
1	24VDC	-	24VDC power supply	-
2	NODE_SEL0	Input	Node selection	Input (*"type B"* according to EN 61131-2)
3	NODE_SEL1	Input		Input (*"type B"* according to EN 61131-2)
4	0VDC	-	0VDC power supply	-
5	OSSD1_A	Output	Static output 1	PNP active high
6	OSSD1_B	Output		PNP active high
7	RESTART_FBK1	Input	Feedback/Restart 1	Input according to EN 61131-2
8	OUT_STATUS1	Output	Programmable signal output	PNP active high
9	OSSD2_A	Output	Static output 2	PNP active high
10	OSSD2_B	Output		PNP active high
11	RESTART_FBK2	Input	Feedback/Restart 2	Input according to EN 61131-2
12	OUT_STATUS2	Output	Programmable signal output	PNP active high
13	24VDC	-	24VDC power supply	24VDC output power supply *
14	n.c.	-	-	-
15	0VDC	-	0VDC power supply	0VDC output *
16	n.c.	-	-	-

Table 7

* This terminal must be connected to the power supply for the unit to work properly.

Module MR4

TERMINAL	SIGNAL	TYPE	DESCRIPTION	OPERATION
1	24VDC	-	24VDC power supply	-
4	0VDC	-	0VDC power supply	-
5	OSSD1_A	Input	Control **ZONE 1**	PNP active high
6	OSSD1_B	Input		
7	FBK_K1_K2_1	Output	Feedback K1K2 **ZONE 1**	
9	A_NC1	Output	NC contact **ZONE 1**	
10	B_NC1	Output		
13	A_NO11	Output	NO1 contact **ZONE 1**	
14	B_NO11	Output		
15	A_NO12	Output	NO2 contact **ZONE 1**	
16	B_NO12	Output		
11	A_NC2	Output	NC contact **ZONE 2**	
12	B_NC2	Output		
17	OSSD2_A	Input	Control **ZONE 2**	PNP active high
18	OSSD2_B	Input		
19	FBK_K1_K2_2	Output	Feedback K1K2 **ZONE 2**	
21	A_NO21	Output	NO1 contact **ZONE 2**	
22	B_NO21	Output		
23	A_NO22	Output	NO2 contact **ZONE 2**	
24	B_NO22	Output		

Table 8

English

Module MR2

TERMINAL	SIGNAL	TYPE	DESCRIPTION	OPERATION
1	24VDC	-	24VDC power supply	-
4	0VDC	-	0VDC power supply	-
5	OSSD1_A	Input	Control **ZONE 1**	PNP active high
6	OSSD1_B	Input		
7	FBK_K1_K2_1	Output	Feedback K1K2 **ZONE 1**	
9	A_NC1	Output	NC contact **ZONE 1**	
10	B_NC1	Output		
13	A_NO11	Output	NO1 contact **ZONE** 1	
14	B_NO11	Output		
15	A_NO12	Output	NO2 contact **ZONE 1**	
16	B_NO12	Output		

Table 9

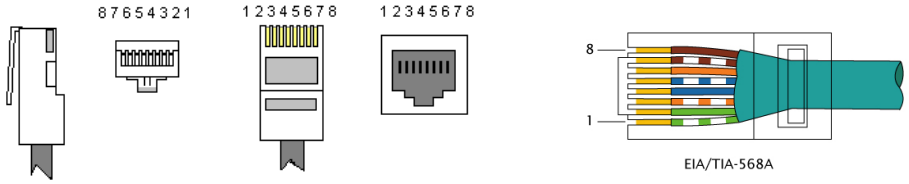
Modules MV0 - MV1 - MV2

TERMINAL	SIGNAL	TYPE	DESCRIPTION	OPERATION
1	24VDC	-	24VDC power supply	-
2	NODE_SEL0	Input	Node selection	Input (***"type B"*** according to EN 61131-2)
3	NODE_SEL1	Input		Input (***"type B"*** according to EN 61131-2)
4	0VDC	-	0VDC power supply	-
5	PROXI1_24V	Output	PROXIMITY 1 connections (ref. "PROXIMITY INPUT FOR SPEED CONTROLLER MV2" -> 27)	Power supply 24VDC to PROXI1
6	PROXI1_REF	Output		Power supply 0VDC to PROXI1
7	PROXI1 IN1 (3 WIRES)	Input		PROXI1 NO input
8	PROXI1 IN2 (4 WIRES)	Input		PROXI1 NC input
9	PROXI2_24V	Output	PROXIMITY 2 connections (ref. "PROXIMITY INPUT FOR SPEED CONTROLLER MV2" -> 27)	Power supply 24VDC to PROXI2
10	PROXI2_REF	Output		Power supply 0VDC to PROXI2
11	PROXI2 IN1 (3 WIRES)	Input		PROXI2 NO input
12	PROXI2 IN2 (4 WIRES)	Input		PROXI2 NC input
13	N.C.	-	Not connected	-
14	N.C.	-		-
15	N.C.	-		-
16	N.C.	-		-

Table 10

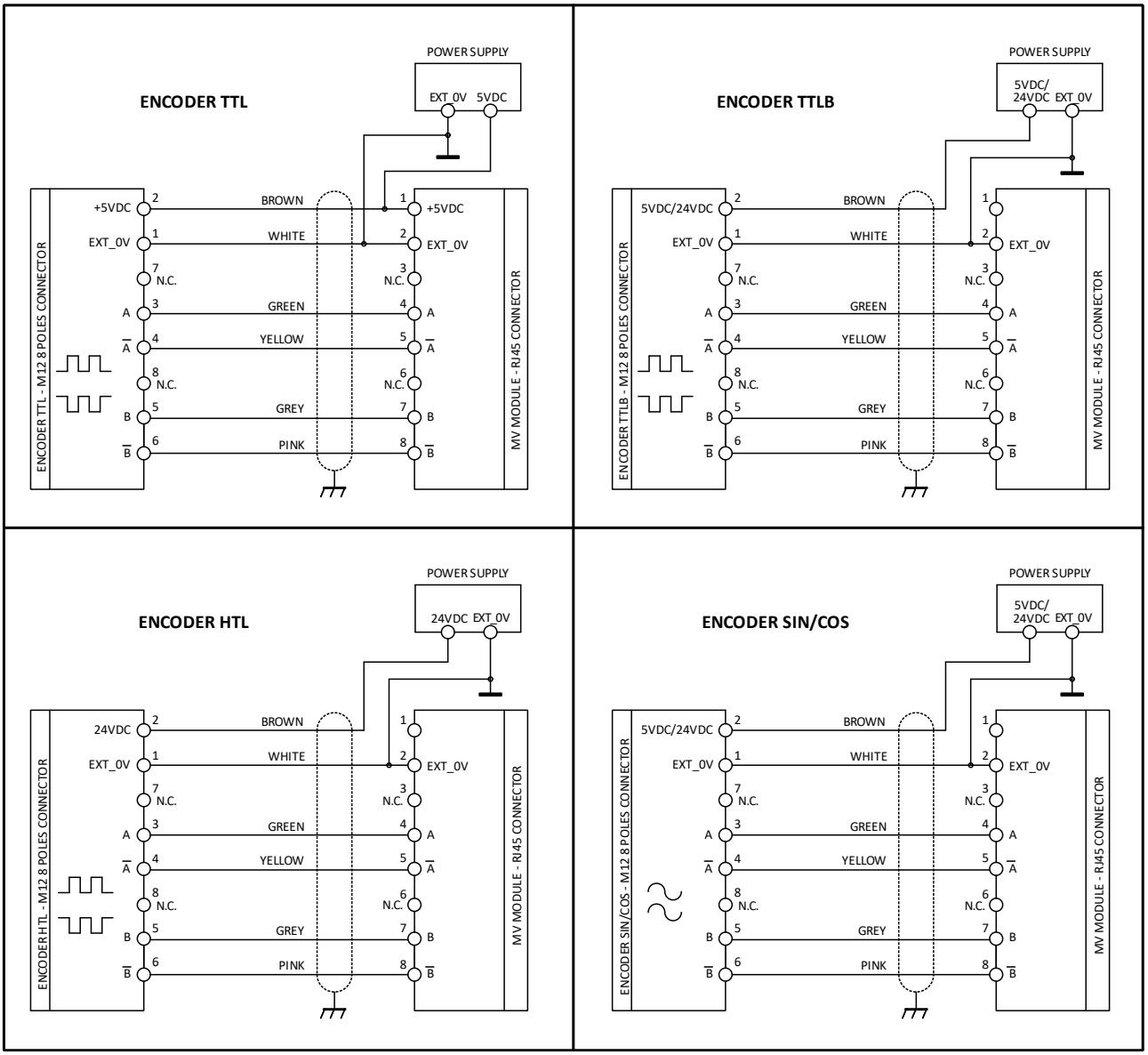
English

ENCODER CONNECTIONS WITH RJ45 CONNECTOR (MV1, MV2)



PIN			MVT	MVTB	MVH	MVS
TWISTED *	1	INPUT	5VDC	N.C.	N.C.	N.C.
	2		EXT_0V	EXT_0V	EXT_0V	EXT_0V
	3		N.C.	N.C.	N.C.	N.C.
TWISTED *	4		A	A	A	A
	5		$\bar{A}$	$\bar{A}$	$\bar{A}$	$\bar{A}$
	6		N.C.	N.C.	N.C.	N.C.
TWISTED *	7		B	B	B	B
	8		$\bar{B}$	$\bar{B}$	$\bar{B}$	$\bar{B}$

* IN CASE OF UTILIZATION OF TWISTED CABLE



English

Module MOR4

TERMINAL	SIGNAL	TYPE	DESCRIPTION	OPERATION
1	24VDC	-	24VDC power supply	-
2	NODE_SEL0	Input	Node selection	Input (*"type B"* according to EN 61131-2)
3	NODE_SEL1	Input		Input (*"type B"* according to EN 61131-2)
4	0VDC	-	0VDC power supply	-
5	REST_FBK1	Input	Feedback/Restart 1	Input (secondo EN 61131-2)
6	REST_FBK2	Input	Feedback/Restart 2	Input (secondo EN 61131-2)
7	REST_FBK3	Input	Feedback/Restart 3	Input (secondo EN 61131-2)
8	REST_FBK4	Input	Feedback/Restart 4	Input (secondo EN 61131-2)
9	A_NO1	Output	N.O. contact Channel 1	
10	B_NO1	Output		
11	A_NO2	Output	N.O. contact Channel 2	
12	B_NO2	Output		
13	A_NO3	Output	N.O. contact Channel 3	
14	B_NO3	Output		
15	A_NO4	Output	N.O. contact Channel 4	
16	B_NO4	Output		

Table 11

Module MOR4S8

TERMINAL	SIGNAL	TYPE	DESCRIPTION	OPERATION
1	24VDC	-	24VDC power supply	-
2	NODE_SEL0	Input	Node selection	Input (*"type B"* according to EN 61131-2)
3	NODE_SEL1	Input		Input (*"type B"* according to EN 61131-2)
4	0VDC	-	0VDC power supply	-
5	REST_FBK1	Input	Feedback/Restart 1	Input (secondo EN 61131-2)
6	REST_FBK2	Input	Feedback/Restart 2	Input (secondo EN 61131-2)
7	REST_FBK3	Input	Feedback/Restart 3	Input (secondo EN 61131-2)
8	REST_FBK4	Input	Feedback/Restart 4	Input (secondo EN 61131-2)
9	A_NO1	Output	N.O. contact Channel 1	
10	B_NO1	Output		
11	A_NO2	Output	N.O. contact Channel 2	
12	B_NO2	Output		
13	A_NO3	Output	N.O. contact Channel 3	
14	B_NO3	Output		
15	A_NO4	Output	N.O. contact Channel 4	
16	B_NO4	Output		
17	OUT_STATUS1	Output	Programmable signal output 1	PNP active high
18	OUT_STATUS2	Output	Programmable signal output 2	PNP active high
19	OUT_STATUS3	Output	Programmable signal output 3	PNP active high
20	OUT_STATUS4	Output	Programmable signal output 4	PNP active high
21	OUT_STATUS5	Output	Programmable signal output 5	PNP active high
22	OUT_STATUS6	Output	Programmable signal output 6	PNP active high
23	OUT_STATUS7	Output	Programmable signal output 7	PNP active high
24	OUT_STATUS8	Output	Programmable signal output 8	PNP active high

Table 12

English

Module MOS8

PIN	SIGNAL	TYPE	DESCRIPTION	OPERATION
1	24VDC	-	24VDC power supply	-
2	NODE_SEL0	Input	Node selection	Input ("*type B*" according to EN 61131-2)
3	NODE_SEL1	Input		Input ("*type B*" according to EN 61131-2)
4	0VDC	-	0VDC power supply	-
5	24VDC STATUS 1-8	-	24VDC power supply OUTPUT STATUS 1-8	-
6	-	-	-	-
7	-	-	-	-
8	-	-	-	-
9	OUT_STATUS1	Output	Programmable signal output 1	PNP active high
10	OUT_STATUS2	Output	Programmable signal output 2	PNP active high
11	OUT_STATUS3	Output	Programmable signal output 3	PNP active high
12	OUT_STATUS4	Output	Programmable signal output 4	PNP active high
13	OUT_STATUS5	Output	Programmable signal output 5	PNP active high
14	OUT_STATUS6	Output	Programmable signal output 6	PNP active high
15	OUT_STATUS7	Output	Programmable signal output 7	PNP active high
16	OUT_STATUS8	Output	Programmable signal output 8	PNP active high

Table 13

Module MOS16

PIN	SIGNAL	TYPE	DESCRIPTION	OPERATION
1	24VDC	-	24VDC power supply	-
2	NODE_SEL0	Input	Node selection	Input ("type B" according to EN 61131-2)
3	NODE_SEL1	Input		Input ("type B" according to EN 61131-2)
4	0VDC	-	0VDC power supply	-
5	24VDC STATUS 1-8	-	24VDC power supply OUTPUT STATUS 1-8	-
6	24VDC STATUS 9-16	-	24VDC power supply OUTPUT STATUS 9-16	-
7	-	-	-	-
8	-	-	-	-
9	OUT_STATUS1	Output	Programmable signal output 1	PNP active high
10	OUT_STATUS2	Output	Programmable signal output 2	PNP active high
11	OUT_STATUS3	Output	Programmable signal output 3	PNP active high
12	OUT_STATUS4	Output	Programmable signal output 4	PNP active high
13	OUT_STATUS5	Output	Programmable signal output 5	PNP active high
14	OUT_STATUS6	Output	Programmable signal output 6	PNP active high
15	OUT_STATUS7	Output	Programmable signal output 7	PNP active high
16	OUT_STATUS8	Output	Programmable signal output 8	PNP active high
17	OUT_STATUS9	Output	Programmable signal output 9	PNP active high
18	OUT_STATUS10	Output	Programmable signal output 10	PNP active high
19	OUT_STATUS11	Output	Programmable signal output 11	PNP active high
20	OUT_STATUS12	Output	Programmable signal output 12	PNP active high
21	OUT_STATUS13	Output	Programmable signal output 13	PNP active high
22	OUT_STATUS14	Output	Programmable signal output 14	PNP active high
23	OUT_STATUS15	Output	Programmable signal output 15	PNP active high
24	OUT_STATUS16	Output	Programmable signal output 16	PNP active high

Table 14

English

Example of connection of Mosaic to the machine control system

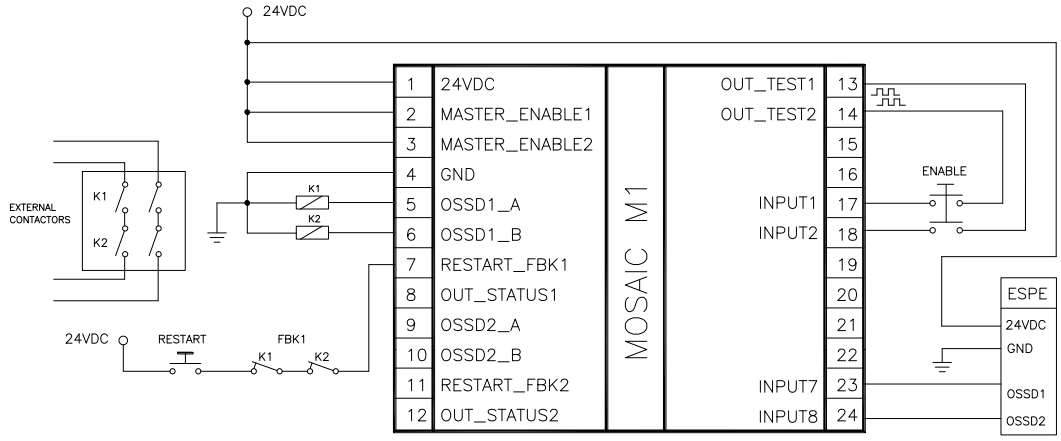


Figure 4

CHECKLIST AFTER INSTALLATION

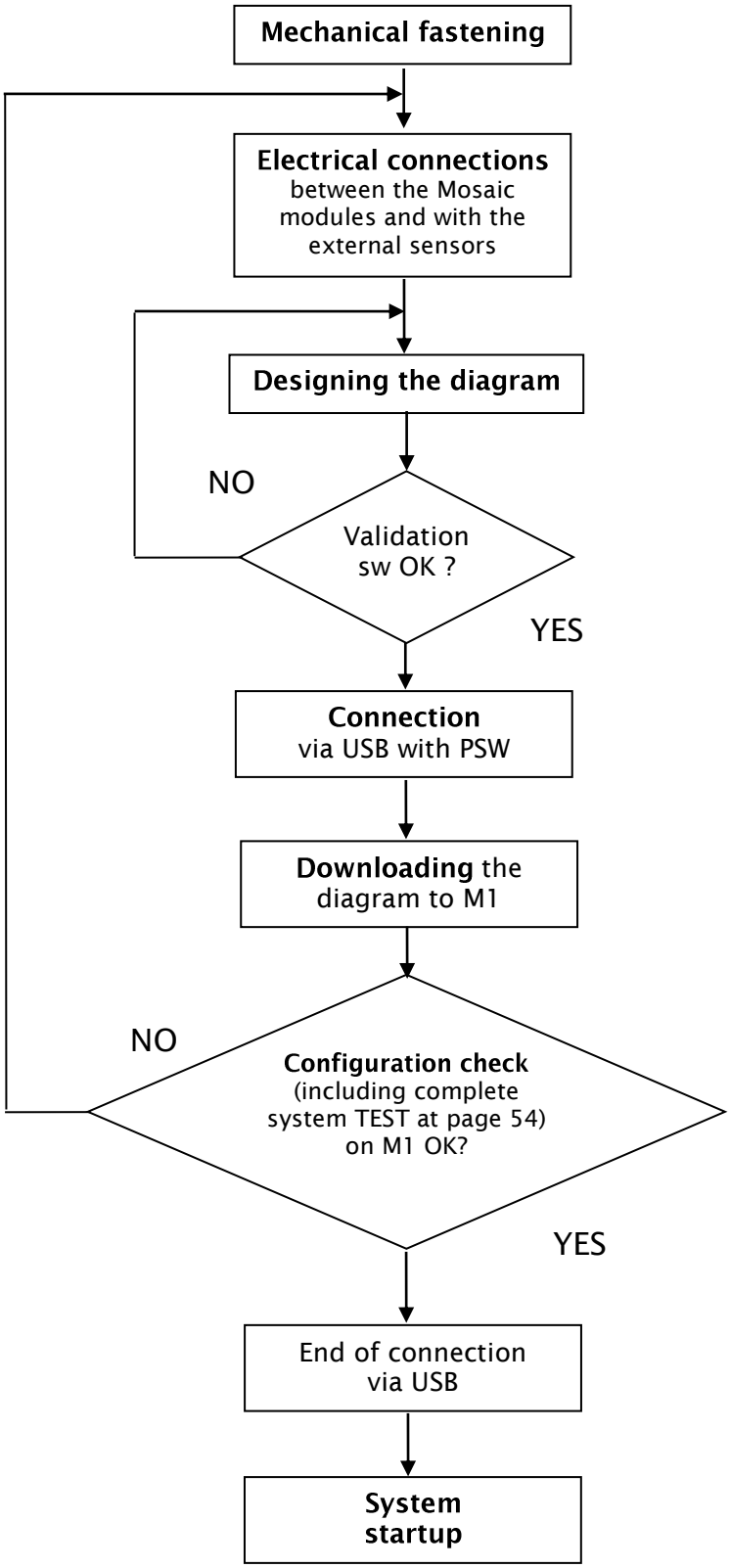
The MOSAIC system is able to detect the faults that occurs in each own module.
Anyway to have the system perfect operation perform the following checks at start up and at least every one year:

1. *Operate a complete system TEST (see "TESTING the system")*
2. *Verify that all the cables are correctly inserted and the terminal blocks well screwed.*
3. *Verify that all the leds (indicators) light on correctly.*
4. *Verify the positioning of all the sensors connected to MOSAIC.*
5. *Verify the correct fixing of MOSAIC to the Omega rail.*
6. *Verify that all the external indicators (lamps) work properly.*

➔ After installation, maintenance and after any eventual configuration change perform a System TEST as described in the paragraph *"TESTING the system" at page 76.*

English

OPERATING DIAGRAM



SIGNALS

INPUTS

MASTER ENABLE

The MOSAIC M1 master has two inputs: MASTER_ENABLE1 and MASTER_ENABLE2.

➔ These signals must both be permanently set to logic level 1 (24VDC) for the MOSAIC to operate. If the user needs to disable the MOSAIC simply lower these inputs to logic level 0 (0VDC).

NODE SEL

The NODE_SEL0 and NODE_SEL1 inputs (on the SLAVE units) are used to attribute a physical address to the slave units with the connections shown in Table 15:

	NODE_SEL1 (Terminal 3)	NODE_SEL0 (Terminal 2)
NODE 0	0 (or not connected)	0 (or not connected)
NODE 1	0 (or not connected)	24VDC
NODE 2	24VDC	0 (or not connected)
NODE 3	24VDC	24VDC

Table 15

➔ It is not allowed to use the same physical address on two units of the same type.

English

PROXIMITY INPUT FOR SPEED CONTROLLER MV

Configuration With Interleaved Proximity (Figure 5)

When an axis of the MV modules is configured for a measurement with two proximity switches, these can be configured in interleaved mode. Under the conditions listed below the system reaches a Performance Level = PLe:

- Proximity switches must be fitted such that the recorded signals overlap.
- Proximity switches must be fitted such that at least one is always activated.

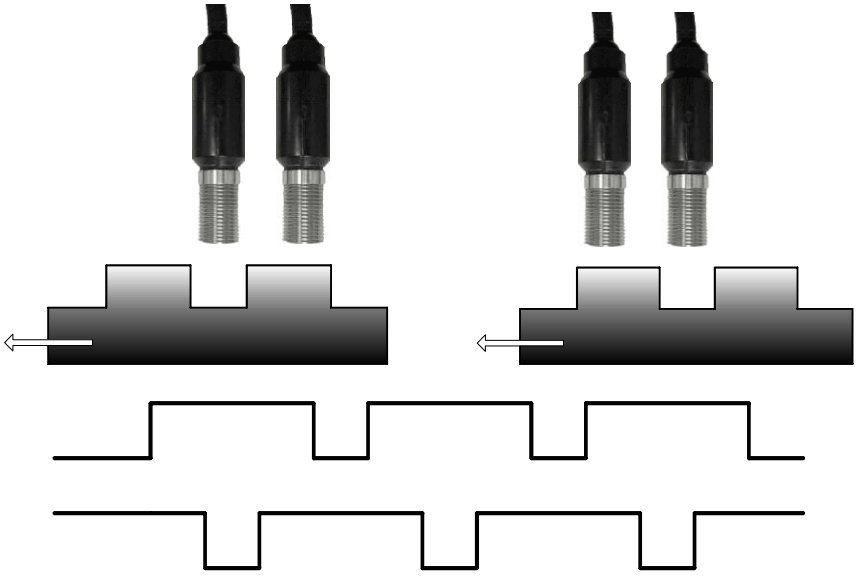


Figure 5

In addition:

- The proximity switches must be PNP type.
- The proximity switches must be NO type (Output ON when detecting metal).
- With the above conditions fulfilled, the DC value is equal to 90%.
- The two proximity switches must be of the same model, with MTTF > 70 years.

English

RESTART_FBK

The RESTART_FBK signal input allows the MOSAIC to verify an EDM (External Device Monitoring) feedback signal (series of contacts) from the external contactors, and to monitor Manual/Automatic operation (See the list of possible connections in Table 16).

- If the application requires it, the response time of the external contactors must be verified by an additional device.
- The RESTART command must be installed outside the danger area in a position where the danger area and the entire work area concerned are clearly visible.
- It must not be possible to reach the control from inside the danger area.

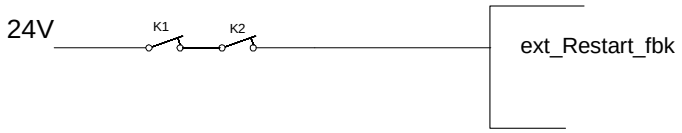
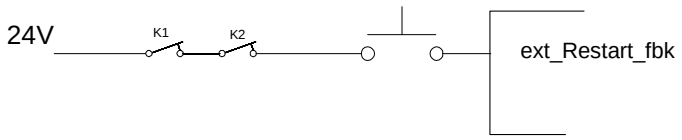
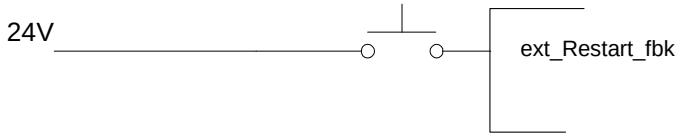
MODE OF OPERATION	EDM	RESTART_FBK
AUTOMATIC	With K1_K2 control	
	Without K1_K2 control	
MANUAL	With K1_K2 control	
	Without K1_K2 control	

Table 16

English

OUTPUTS

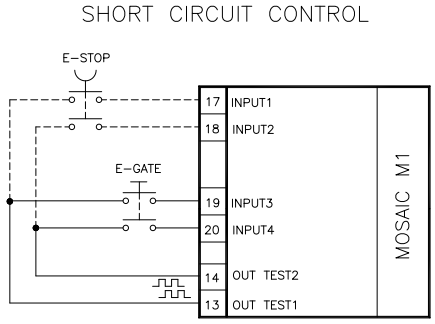
OUT STATUS

The OUT STATUS signal is a Programmable signal output that can indicate the status of:

- An input.
- An output.
- A node of the logic diagram designed using the MSD.

OUT TEST

The OUT TEST signals must be used to monitor the presence of short-circuits or overloads on the inputs (Figure 6).



➔ The maximum number of controllable inputs for each output OUT TEST is:
- 2 INPUT (parallel connection) **(M1, MI802, MI8, MI12T8)**
- 4 INPUT (parallel connection) **(MI16)**

➔ The maximum allowed length for OUT TEST signal connections is = 100m.

Figure 6

OSSD (M1, MI8O2)

The OSSD *(static semiconductor safety outputs)* are short circuit protected, cross circuit monitored and supply:

- In the ON condition: **Uv-0,75V ÷ Uv** *(where Uv is 24V ± 20%)*
- In the OFF condition: **0V ÷ 2V r.m.s.**

The maximum load of 400mA@24V corresponds to a minimum resistive load of 60Ω.

The maximum capacitive load is 0.82μF. The maximum inductive load is 2 mH.

OSSD (MO2, MO4)

The OSSD *(static semiconductor safety outputs)* are short circuit protected, cross circuit monitored and supply:

- In the ON condition: **Uv-0,75V ÷ Uv** *(where Uv is 24V ± 20%)*
- In the OFF condition: **0V ÷ 2V r.m.s.**

The maximum load of 400mA@24V corresponds to a minimum resistive load of 60Ω.

The maximum capacitive load is 0.82μF. The maximum inductive load is 2 mH.

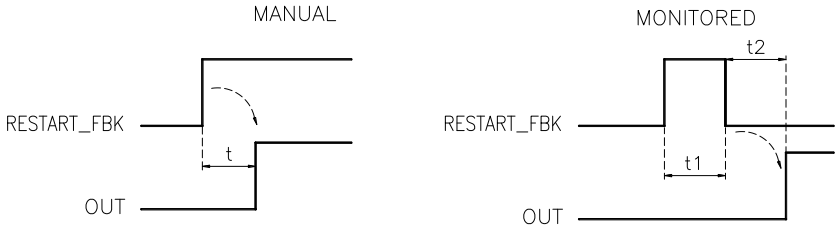
➔ It is not allowed the connection of external devices to the outputs, except as expected in the configuration performed with the MSD software.

Each OSSD output can be configured as shown in Table 17:

Automatic	The output is activated according to le configurations set by the MSD SW only if the corresponding RESTART_FBK input is conected to 24VDC.
Manual	The output is activated according to le configurations set by the MSD SW only if corresponding RESTART_FBK input FOLLOWS A LOGIC TRANSITION OF **0-->1.**
Monitored	The output is activated according to le configurations set by the MSD SW only if the corresponding RESTART_FBK input FOLLOWS A LOGIC TRANSITION OF **0-->1-->0.**

Table 17

English



t = 250ms

250ms < t1< 5s
t2 = 250ms

SAFETY RELAYS (MR2, MR4, MOR4, MOR4S8)

Characteristics of the output circuit.

The MR2/MR4 units use guided contact safety relays, each of which provides **two N.O. contacts and one N.C contact in addition to the N.C. feedback contact**.
The MR2 unit uses two safety relays and the MR4 uses four.
The MOR4/MOR4S8 units use four guided-contact safety relays. Each relay provides one NO contact monitored by the module logic through internal FBK contact.

➔ Refer to the "RELAY" section to check the possible MOR4/MOR4S8 operation modes configurable with MSD software.

Excitation voltage	**17...31 VDC**
Minimum switchable voltage	**10 VDC**
Minimum switchable current	**20 mA**
Maximum switchable voltage (DC)	**250VDC**
Maximum switchable voltage (AC)	**400VAC**
Maximum switchable current	**6A**
Response time	**12ms**
Mechanical life of contacts	**> 20 x 10^6**

Table 18

➔ To guarantee correct isolation and avoid the risk of premature ageing of or damage to the relays, each output line must be protected using a fast acting 4A fuse and the load characteristics must be consistent with those specified in Table 12.

➔ See the "MR2/MR4" section (for further details on these relays).

MR2/MR4 internal contacts diagram

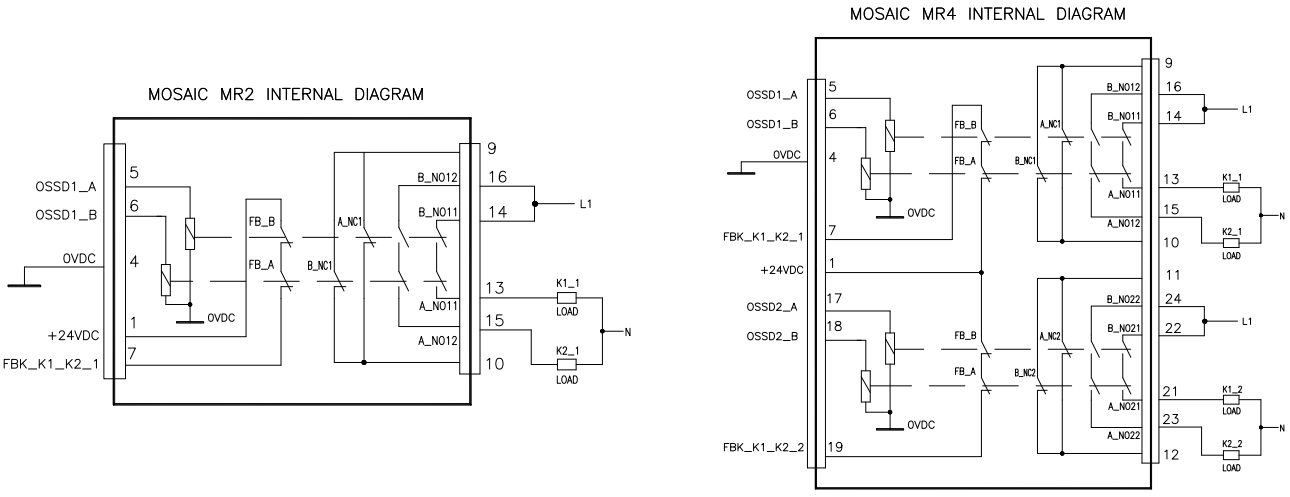


Figure 7

English

Example of MR2 module connection with static OSSD outputs of a module M1[2]

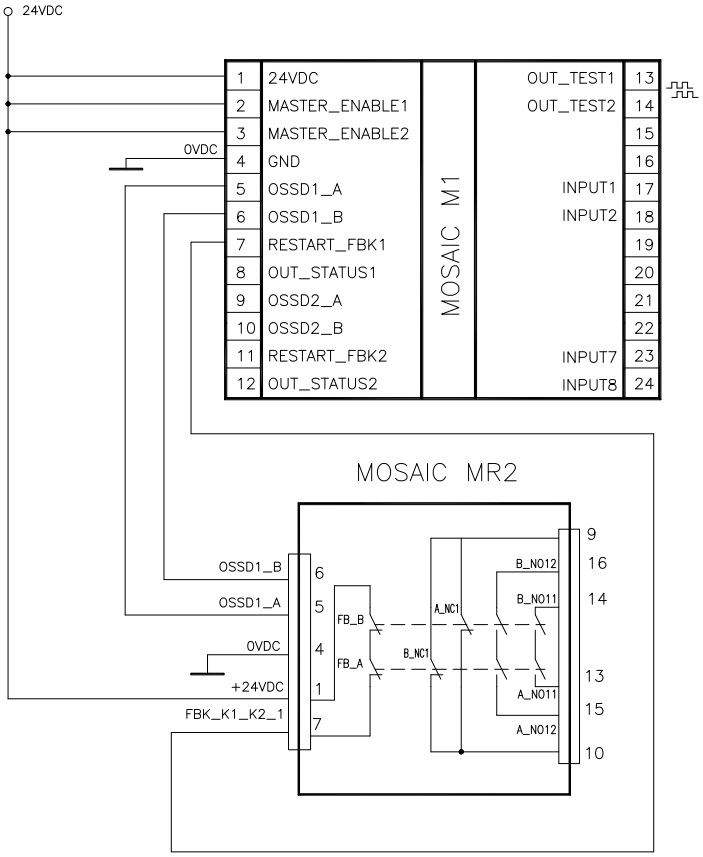


Figure 8

Switching operation timing diagram.

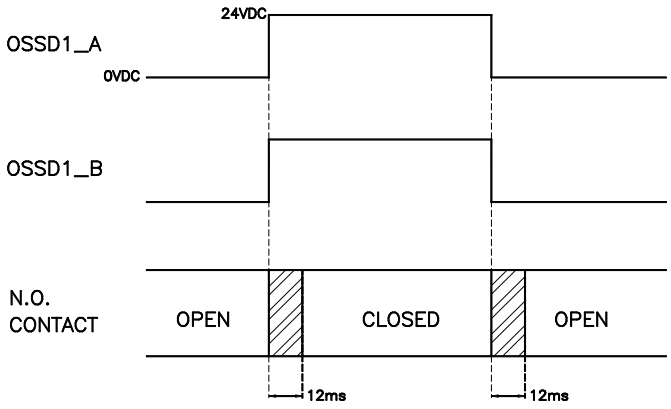


Figure 9

English

[2] If a relay module is connected, the response time of the OSSD linked, must be increased of 12ms.

TECHNICAL FEATURES

GENERAL SYSTEM CHARACTERISTICS

Safety level parameters

Parameter	Value	Standard
PFH_d	See the technical data tables for each module	IEC 61508:2010
SIL	3	
SFF	99,8%	
HFT	1	
Safety standard	Type B	
SILCL	3	IEC 62061:2005
Type	4	EN 61496-1:2013
PL	e	EN ISO 13849-1:2008 EN 62061:2005
Dc_{avg}	High	
MTTFd (years)	30 ÷ 100	
Category	4	
Device lifetime	20 years	
Pollution degree	2	

General data

Max number of inputs	128	
Max number of outputs	16	
Max number of slave units (excluding MR2-MR4)	14	
Max number of slave units of the same type (excluding MR2-MR4)	4	
Rated voltage	24VDC ± 20% / Supply from class II (LVLE)	
Over voltage category	II	
Digital INPUTS	PNP active high (EN 61131-2) - Max. applicable resistance 1,2kΩ	
OSSD (M1, MI8O2, MO2, MO4)	PNP active high - 400mA@24VDC max (each OSSD)	
Signaling OUTPUTS (M1, MI8O2, MO2, MO4, MOS8, MOS16)	PNP active high - 100mA@24VDC max	
Response time (ms) *This response times depends on the following parameters:* *1) Number of Slave modules installed* *2) Number of Operators* *3) Number of OSSD outputs* *For the right response time refer to the one calculated by the DSD software (see Project report)* **Failure Response time (ms)** *This parameter corresponds to the response time, with the exception of MV modules with Encoder/Proximity interface where is 2s*	Master	10,6 ÷ 12,6 + T_{Input_filter}
	M1 + 1 Slave	11,8 ÷ 26,5 + T_{Input_filter}
	M1 + 2 Slaves	12,8 ÷ 28,7 + T_{Input_filter}
	M1 + 3 Slaves	13,9 ÷ 30,8 + T_{Input_filter}
	M1 + 4 Slaves	15 ÷ 33 + T_{Input_filter}
	M1 + 5 Slaves	16 ÷ 35 + T_{Input_filter}
	M1 + 6 Slaves	17 ÷ 37,3 + T_{Input_filter}
	M1 + 7 Slaves	18,2 ÷ 39,5 + T_{Input_filter}
	M1 + 8 Slaves	19,3 ÷ 41,7 + T_{Input_filter}
	M1 + 9 Slaves	20,4 ÷ 43,8 + T_{Input_filter}
	M1 + 10 Slaves	21,5 ÷ 46 + T_{Input_filter}
	M1 + 11 Slaves	22,5 ÷ 48,1 + T_{Input_filter}
	M1 + 12 Slaves	23,6 ÷ 50,3 + T_{Input_filter}
	M1 + 13 Slaves	24,7 ÷ 52,5 + T_{Input_filter}
	M1 + 14 Slaves	25,8 ÷ 54,6 + T_{Input_filter}
M1> module connection	ReeR proprietary 5-pole bus (MSC)	
Connection cable cross-section	0,5 ÷ 2,5 mm^2 / AWG 12÷30 (solid/stranded)	
Max length of connections	100m	
Operating temperature	-10 ÷ 55°C	
Max surrounding air temperature	55°C (UL)	
Storage temperature	-20 ÷ 85°C	
Relative humidity	10% ÷ 95%	
Max. altitude (above sea level)	2000 m	

English

➔ T_{Input_filter} = max filtering time from among those set on project inputs (see "INPUTS" section").

Enclosure

Description	Electronic housing max 24 pole, with locking latch mounting
Enclosure material	Polyamide
Enclosure protection class	IP 20
Terminal blocks protection class	IP 2X
Fastening	Quick coupling to rail according to EN 60715
Dimensions (h x l x d)	108 x 22.5 x 114.5

M1 module

PFH_d (IEC 61508:2010)	6.86E-9
Rated voltage	24VDC ± 20%
Dissipated power	3W max
Unit enable (No./description)	2 / PNP active high *"type B"* according to EN 61131-2
Digital INPUTS (No./description)	8 / PNP active high according to EN 61131-2
INPUT FBK/RESTART (No./description)	2 / EDM control / possible Automatic or Manual operation with RESTART button
Test OUTPUT (No./description)	4 / to check for short-circuits - overloads
Signaling OUTPUTS (No./description)	2 / programmable - PNP active high
OSSD (No./description)	2 pairs / solid state safety outputs PNP active high 400mA@24VDC max
SLOT for MCM card	Available
Connection to PC	USB 2.0 (Hi Speed) - Max cable length: 3m
Connection to slave units	via MSC 5-way ReeR proprietary bus

MI8O2 module

PFH_d (IEC 61508:2010)	5.68E-9
Rated voltage	24VDC ± 20%
Dissipated power	3W max
Digital INPUTS (No./description)	8 / PNP active high according to EN 61131-2
Test OUTPUT (No./description)	8 / to check for short-circuits - overloads
Signaling OUTPUTS (No./description)	2 / programmable - PNP active high
OSSD (No./description)	2 pairs / solid state safety outputs: PNP active high – 400mA@24VDC max
Connection to M1	via MSC 5-way ReeR proprietary bus

MI8 - MI16 modules

Model	**MI8**	**MI16**
PFH_d (IEC 61508:2010)	4.45E-9	4.94E-9
Rated voltage	24VDC ± 20%	
Dissipated power	3W max	
Digital INPUTS (No./description)	8	16

English

	PNP active high according to EN 61131-2
Test OUTPUT (No./description)	4 / to check for short-circuits - overloads
Connection to M1	via MSC 5-way ReeR proprietary bus

MI12T8 module

PFH_d (IEC 61508:2010)	5.56E-9
Rated voltage	24VDC ± 20%
Dissipated power	3W max
Digital INPUTS (No./description)	12
	PNP active high according to EN 61131-2
Test OUTPUT (No./description)	8 / to check for short-circuits - overloads
Connection to M1	via MSC 5-way ReeR proprietary bus

MO2 - MO4 modules

Model	**MO2**	**MO4**
PFHd (IEC 61508:2010)	4.09E-9	5.84E-9
Rated voltage	24VDC ± 20%	
Dissipated power	3W max	
Signaling OUTPUTS (No./description)	2	4
	programmable - PNP active high	
OSSD (No./description)	2	4
	Solid state safety outputs: PNP active high 400mA@24VDC max	
Connection to M1	via MSC 5-way ReeR proprietary bus	

MOS8 – MOS16 modules

Model	**MOS8**	**MOS16**
Rated voltage	24VDC ± 20%	
Dissipated power	3W max	
Signaling OUTPUT (No./description)	8	16
	programmable - PNP active high	
Connection to M1	through 5-way MSC proprietary bus	

MR2 - MR4 modules

Model	**MR2**	**MR4**
Rated voltage	24VDC ± 20%	
Dissipated power	3W max	
Switching voltage	240 VAC	
Switching current	6A max	
N.O. contacts	2 N.O. + 1 N.C.	4 N.O. + 2 N.C.
FEEDBACK contacts	1	2
Response time	12ms	
Mechanical life of contacts	> 20 x 10^6	
Connection to output module	Via front-panel terminal strip (no connection via MSC bus)	

MR2 – MR4: TECHNICAL DATA CONCERNING SAFETY	
FEEDBACK CONTACT PRESENT	**FEEDBACK CONTACT MISSING**

English

PFHd	SFF	MTTFd	DCavg			PFHd	SFF	MTTFd	DCavg		
3,09E-10	99,6%	2335,94	98,9%	tcycle1		9,46E-10	60%	2335,93	0	tcycle1	
8,53E-11	99,7%	24453,47	97,7%	tcycle2	DC13 (2A)	1,08E-10	87%	24453,47	0	tcycle2	DC13 (2A)
6,63E-11	99,8%	126678,49	92,5%	tcycle3		6,75E-11	97%	126678,5	0	tcycle3	
8,23E-09	99,5%	70,99	99,0%	tcycle1		4,60E-07	50%	70,99	0	tcycle1	
7,42E-10	99,5%	848,16	99,0%	tcycle2	AC15 (3A)	4,49E-09	54%	848,15	0	tcycle2	AC15 (3A)
1,07E-10	99,7%	12653,85	98,4%	tcycle3		1,61E-10	79%	12653,85	0	tcycle3	
3,32E-09	99,5%	177,38	99,0%	tcycle1		7,75E-08	51%	177,37	0	tcycle1	
3,36E-10	99,6%	2105,14	98,9%	tcycle2	AC15 (1A)	1,09E-09	60%	2105,14	0	tcycle2	AC15 (1A)
8,19E-11	99,7%	28549,13	97,5%	tcycle3		1,00E-10	88%	28549,13	0	tcycle3	

t_{cycle1}: 300s (1 commutation every 5 minutes)
t_{cycle2}: 3600s (1 commutation every hour)
t_{cycle3}: 1 commutation every day
(PFHd according IEC61508, MTTFd and DCavg according ISO13849-1)

MOR4 – MOR4S8 module

Model	MOR4	MOR4S8
PFHd (IEC 61508:2010)	2,9E-9	2,94E-9
Rated voltage	24VDC ± 20%	
Dissipated power max	3W max	
Switching voltage	240 VAC	
Switching current	6A max	
N.O. contacts	4	
INPUT FBK/RESTART (No./description)	4 / EDM control / possible Automatic or Manual operation with RESTART button	
Digital OUTPUT (No./description)	-	8 / Programmable output PNP active high
Response time	12ms	
Mechanical life of contacts	> 40 x 10^6	
Connessione per utilizzatore	Terminal blocks	
Connection to M1	via MSC 5-way ReeR proprietary bus	

MV0 - MV1 - MV2 modules

Condition *(-> SPEED CONTROL TYPE FUNCTION BLOCKS)*	**Overspeed**	**Stand still**	**Window speed**
Safe state	Overspeed	NO Stand still	Out of Window speed

Model	MV0	MV1	MV2
PFHd	5,98E-09	-	-
PFHd (TTL)	-	7,08E-09 (MV1T)	8,18E-09 (MV2T)
PFHd (sin/cos)	-	7,94E-09 (MV1S)	9,89E-09 (MV2S)
PFHd (HTL24)	-	6,70E-09 (MV1H)	7,42E-09 (MV2H)
PFHd (TTL internal power supply)	-	7,82E-09 (MV1TB)	9,66E-09 (MV2TB)
Rated Voltage	24VDC ± 20%		
Dissipated power max	3W		
Input impedance	-	120 ohm (MV1T – MV1TB / MV2T – MV2TB models) 120 ohm (MV1S - MV2S models)	
Encoder Interface	-	TTL (MV1T – MV1TB / MV2T – MV2TB models) HTL (MV1H - MV2H models) sin/cos (MV1S - MV2S models)	
Encoder connections	-	RJ45 connector	
Encoder input signals electrically	-	Rated insulation voltage 250V	

English

insulated in accordance with EN 61800-5		Overvoltage category II Rated impulse withstand voltage 4.00 kV	
Max number of encoders	-	1	2
Max encoder frequency	-	500KHz (HTL: 300KHz)	
Encoder adjustable threshold range	-	1Hz ÷ 450KHz	
Proximity type	PNP/NPN - 3/4 wires		
Proximity connections	Terminal blocks		
Proximity adjustable threshold range	1Hz ÷ 4KHz		
Max number of proximity	2		
Max proximity frequency	5KHz		
Max number of axes	2		
Stand-still/overspeed frequency gap	>10Hz		
Min. gap between tresholds (with tresholds >1)	> 5%		
M1 connections	via MSC 5-way ReeR proprietary bus		

English

MECHANICAL DIMENSIONS

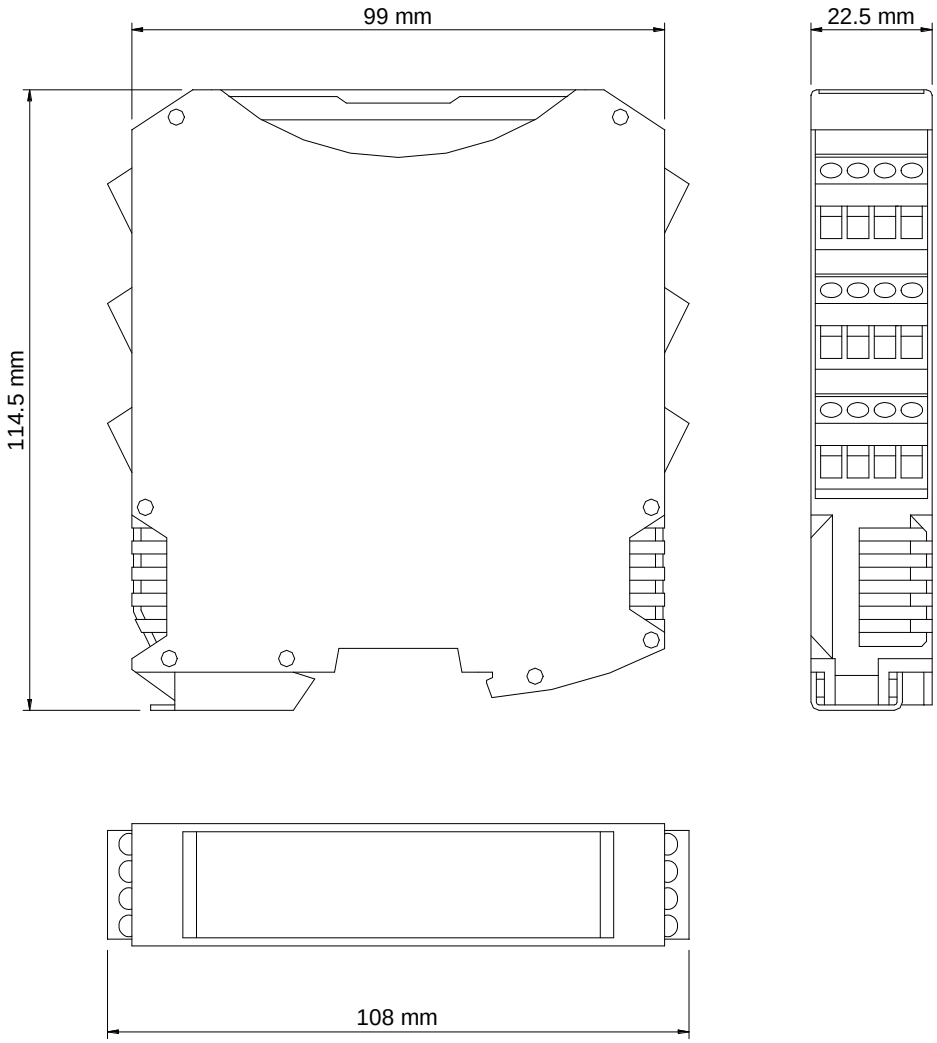


Figure 10

SIGNALS

Master M1 (Figure 11)

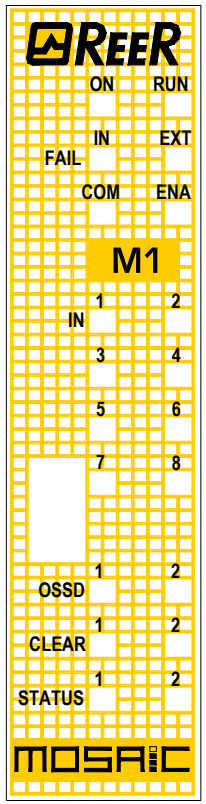


Figure 11 - M1

MEANING	LED								
	RUN GREEN	IN FAIL RED	EXT FAIL RED	COM ORANGE	ENA BLUE	IN1÷8 YELLOW	OSSD1/2 RED/GREEN	CLEAR1/2 YELLOW	STATUS1/2 YELLOW
Power on – initial TEST	ON	ON	ON	ON	ON	ON	Red	ON	ON
MCM recognised	OFF	OFF	OFF	ON (max 1s)	ON (max 1s)	OFF	Red	OFF	OFF
Writing/loading/ diagram to/from MCM card	OFF	OFF	OFF	5 flashes	5 flashes	OFF	Red	OFF	OFF
MSD requesting connection: internal configuration not present	OFF	OFF	OFF	Flashes slowly	OFF	OFF	Red	OFF	OFF
MSD requesting connection: (slave module or node number not correct) (ref. System composition)	OFF	OFF	OFF	Flashes quickly	OFF	OFF	Red	OFF	OFF
MSD requesting connection: (slave module missing or not ready) (ref. System composition)	Flashes quickly	OFF	OFF	Flashes quickly	OFF	OFF	Red	OFF	OFF
MSD connected M1 stopped	OFF	OFF	OFF	ON	OFF	OFF	Red	OFF	OFF

Table 19 - Opening Screen

MEANING	LED								
	RUN GREEN	IN FAIL RED	EXT FAIL RED	COM ORANGE	IN1÷8 YELLOW	ENA BLUE	OSSD1/2 RED/GREEN	CLEAR1/2 YELLOW	STATUS1/2 YELLOW
NORMAL OPERATION	**ON**	**OFF**	**OFF** op. OK	**ON** = M1 connected to PC **OFF**=otherwise	INPUT condition	**ON** MASTER_ENABLE1 and MASTER_ENABLE2 active **OFF** otherwise	**RED** with output OFF **GREEN** with output ON	**ON** waiting for RESTART **Flashing** NO feedback	OUTPUT condition
EXTERNAL FAULT DETECTED	**ON**	**OFF**	**ON** incorrect external connection detected	**ON** = M1 connected to PC **OFF**=otherwise	only the number of the INPUT with the incorrect connection **flashes**				

Table 20 - Dynamic Screen

English

MI8O2 (Figure 12)

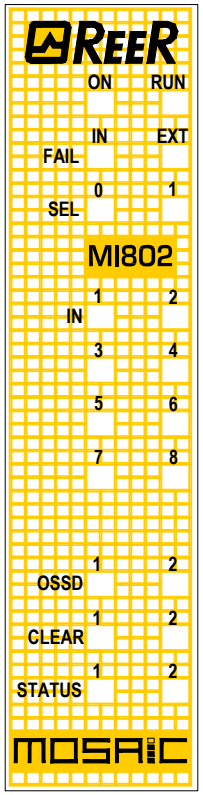


Figure 12 - MI8O2

MEANING	LED							
	RUN GREEN	IN FAIL RED	EXT FAIL RED	SEL ORANGE	IN1÷8 YELLOW	OSSD1/2 RED/GREEN	CLEAR1/2 YELLOW	STATUS1/2 YELLOW
Power on – initial TEST	ON	ON	ON	ON	ON	Red	ON	ON

Table 21 - Opening Screen

MEANING	LED							
	RUN GREEN	IN FAIL RED	EXT FAIL RED	IN1÷8 YELLOW	SEL ORANGE	OSSD1/2 RED/GREEN	CLEAR1/2 YELLOW	STATUS1/2 YELLOW
NORMAL OPERATION	**OFF** if the unit is waiting for the first communication from the MASTER **FLASHES** if no INPUT or OUTPUT requested by the configuration **ON** if INPUT or OUTPUT requested by the configuration	**OFF**	**OFF**	INPUT condition	Shows the NODE_SEL0/1 signal table	**RED** with output OFF **GREEN** with output ON	**ON** waiting for RESTART **Flashes** NO feedback	OUTPUT condition
			ON incorrect external connection detected	only the number of the INPUT with the incorrect connection **flashes**				

Table 22 - Dynamic Screen

English

MI8 (Figure 13)

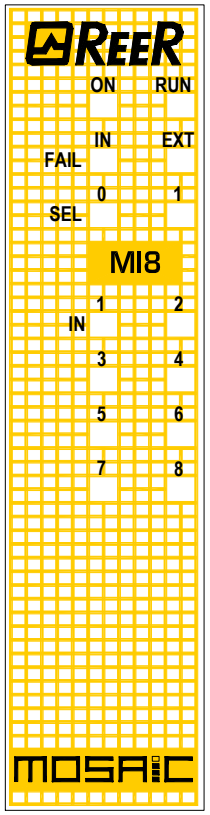


Figure 13 - MI8

MEANING	LED				
	RUN GREEN	IN FAIL RED	EXT FAIL RED	SEL ORANGE	IN1÷8 YELLOW
Power on – initial TEST	ON	ON	ON	ON	ON

Table 23 - Opening Screen

MEANING	LED				
	RUN GREEN	IN FAIL RED	EXT FAIL RED	SEL ORANGE	IN1÷8 YELLOW
NORMAL OPERATION	**OFF** if the unit is waiting for the first communication from the MASTER **FLASHES** if no INPUT or OUTPUT requested by the configuration **ON** if INPUT or OUTPUT requested by the configuration	**OFF**	**OFF**	**Shows the NODE_SEL0/1 signal table**	INPUT condition
			ON incorrect external connection detected		only the number of the INPUT with the incorrect connection **flashes**

Table 24 - Dynamic Screen

English

MI12T8 (Figure 15)

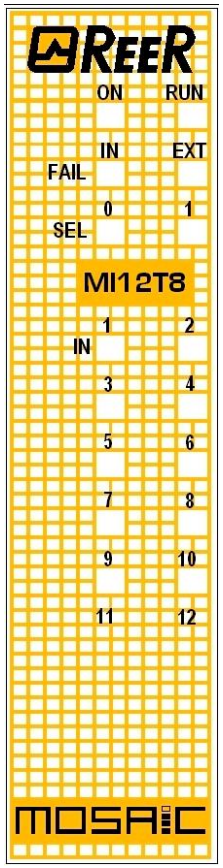


Figure 14
MI12T8

MEANING	LED				
	RUN GREEN	IN FAIL RED	EXT FAIL RED	SEL ORANGE	IN1÷12 YELLOW
Power on – initial TEST	ON	ON	ON	ON	ON

Table 25 - Opening Screen

MEANING	LED				
	RUN GREEN	IN FAIL RED	EXT FAIL RED	SEL ORANGE	IN1÷12 YELLOW
NORMAL OPERATION	**OFF** if the unit is waiting for the first communication from the MASTER **FLASHES** if no INPUT or OUTPUT requested by the configuration **ON** if INPUT or OUTPUT requested by the configuration	**OFF**	**OFF**	**Shows the NODE_SEL0/1 signal table**	INPUT condition
			ON incorrect external connection detected		only the number of the INPUT with the incorrect connection **flashes**

Table 26 - Dynamic Screen

English

MI16 (Figure 15)

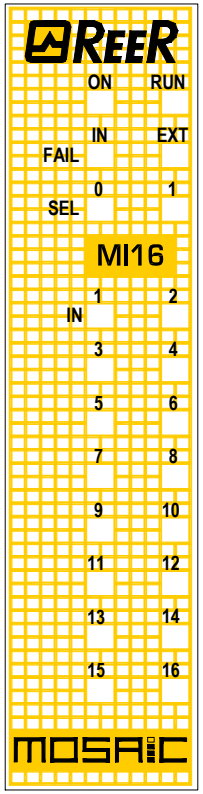


Figure 15 - MI16

MEANING	LED				
	RUN GREEN	IN FAIL RED	EXT FAIL RED	SEL ORANGE	IN1÷16 YELLOW
Power on – initial TEST	ON	ON	ON	ON	ON

Table 27 - Opening Screen

MEANING	LED				
	RUN GREEN	IN FAIL RED	EXT FAIL RED	SEL ORANGE	IN1÷16 YELLOW
NORMAL OPERATION	**OFF** if the unit is waiting for the first communication from the MASTER **FLASHES** if no INPUT or OUTPUT requested by the configuration **ON** if INPUT or OUTPUT requested by the configuration	**OFF**	**OFF**	**Shows the NODE_SEL0/1 signal table**	INPUT condition
			ON incorrect external connection detected		only the number of the INPUT with the incorrect connection **flashes**

Table 28 - Dynamic Screen

English

MO2 (Figure 16)

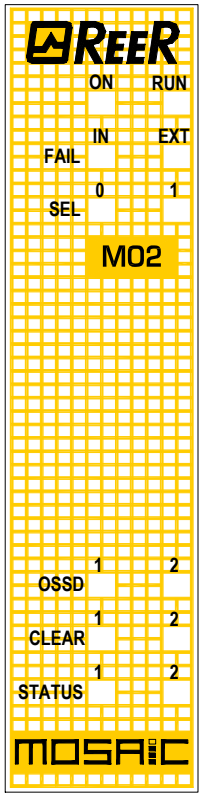


Figure 16 - MO2

MEANING	LED						
	RUN GREEN	IN FAIL RED	EXT FAIL RED	SEL ORANGE	OSDD1/2 RED/GREEN	CLEAR1/2 YELLOW	STATUS1/2 YELLOW
Power on – initial TEST	ON	ON	ON	ON	Red	ON	ON

Table 29 - Opening screen

MEANING	LED						
	RUN GREEN	IN FAIL RED	EXT FAIL RED	SEL ORANGE	OSSD1/2 RED/GREEN	CLEAR1/2 YELLOW	STATUS1/2 YELLOW
NORMAL OPERATION	**OFF** if the unit is waiting for the first communication from the MASTER **FLASHES** if no INPUT or OUTPUT requested by the configuration **ON** if INPUT or OUTPUT requested by the configuration	**OFF** op. OK	**OFF** op. OK	Shows the NODE_SEL0/1 signal table	**RED** with output OFF	**ON** waiting for RESTART	OUTPUT condition
					GREEN with output ON	**Flashes** NO feedback	

Table 30 - Dynamic screen

English

MO4 (Figure 17)

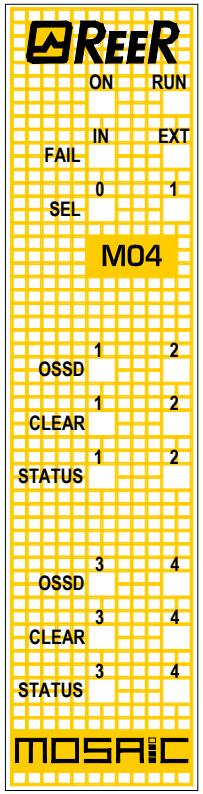


Figure 17 - MO4

MEANING	LED						
	RUN GREEN	IN FAIL RED	EXT FAIL RED	SEL ORANGE	OSDD1/4 RED/GREEN	CLEAR1/4 YELLOW	STATUS1/4 YELLOW
Power on – initial TEST	ON	ON	ON	ON	Red	ON	ON

Table 31 - Opening screen

MEANING	LED						
	RUN GREEN	IN FAIL RED	EXT FAIL RED	SEL ORANGE	OSDD1/4 RED/GREEN	CLEAR1/4 YELLOW	STATUS1/4 YELLOW
NORMAL OPERATION	**OFF** if the unit is waiting for the first communication from the MASTER **FLASHES** if no INPUT or OUTPUT requested by the configuration **ON** if INPUT or OUTPUT requested by the configuration	**OFF** op. OK	**OFF** op. OK	Shows the NODE_SEL0/1 signal table	**RED** with output OFF **GREEN** with output ON	**ON** waiting for RESTART **Flashes** NO feedback	OUTPUT condition

Table 32 - Dynamic screen

English

MOR4 (Figure 18)

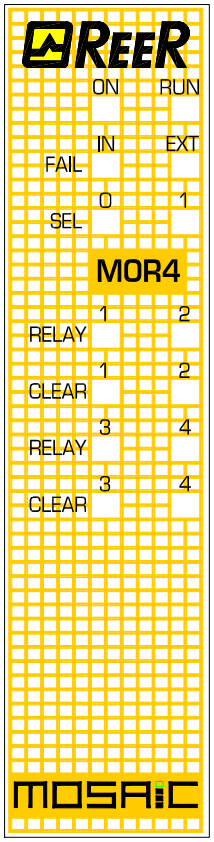


Figure 18 - MOR4

MEANING	LED					
	RUN	IN FAIL	EXT FAIL	SEL 0/1	RELAY 1/4	CLEAR1/4
	GREEN	RED	RED	ORANGE	RED / GREEN	YELLOW
Power on – initial TEST	ON	ON	ON	ON	Red	ON

Table 33 - Opening screen

MEANING	LED					
	RUN	IN FAIL	EXT FAIL	SEL 0/1	RELAY 1/4	CLEAR1/4
	GREEN	RED	RED	ORANGE	RED / GREEN	YELLOW
NORMAL OPERATION	**OFF** if the unit is waiting for the first communication from the MASTER **FLASHES** if no INPUT or OUTPUT requested by the configuration **ON** if INPUT or OUTPUT requested by the configuration	**OFF** operation OK	**OFF** operation OK	Shows the NODE_SEL0/1 signal table	**RED** with contact opened	**ON** waiting for RESTART
					GREEN with contact closed	**FLASHES** External contactors feedback error

Table 34 - Dynamic screen

English

MOR4S8 (Figure 19)

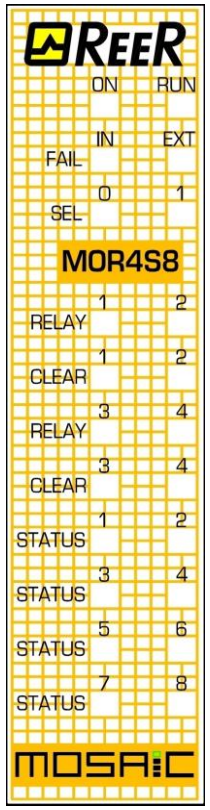


Figure 19 - MOR4S8

MEANING	LED							
	RUN	IN FAIL	EXT FAIL	SEL 0/1	RELAY 1/4		CLEAR1/4	STATUS1/8
	GREEN	RED	RED	ORANGE	RED	GREEN	YELLOW	YELLOW
Power on – initial TEST	ON	ON	ON	ON	Red		ON	ON

Table 35 - Opening screen

MEANING	LED							
	RUN	IN FAIL	EXT FAIL	SEL 0/1	RELAY 1/4		CLEAR1/4	STATUS1/8
	GREEN	RED	RED	ORANGE	RED	GREEN	YELLOW	YELLOW
NORMAL OPERATION	**OFF** if the unit is waiting for the first communication from the MASTER **FLASHES** if no INPUT or OUTPUT requested by the configuration **ON** if INPUT or OUTPUT requested by the configuration	**OFF** operation OK	**OFF** operation OK	Shows the NODE_SEL0/1 signal table	**RED** with contact opened		**ON** waiting for RESTART	OUTPUT condition
					GREEN with contact closed		**FLASHES** wrong feedback external contactors	

Table 36 - Dynamic screen

English

MOS8 (Figure 20)

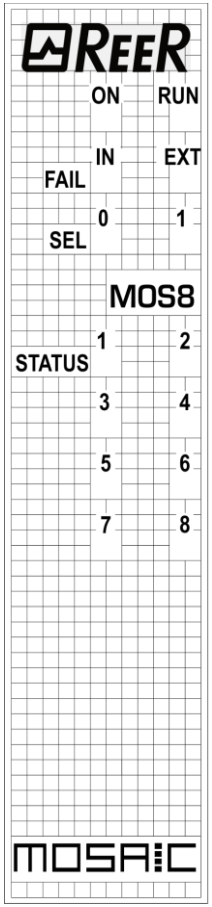


Figure 20 - MOS8

LED					
MEANING	RUN	IN FAIL	EXT FAIL	SEL 0/1	STATUS1/8
	GREEN	RED	RED	ORANGE	YELLOW
Power on - initial TEST	ON	ON	ON	ON	ON

Table 37 - Opening screen

LED					
MEANING	RUN	IN FAIL	EXT FAIL	SEL 0/1	STATUS1/8
	GREEN	RED	RED	ORANGE	YELLOW
NORMAL OPERATION	**OFF** if the unit is waiting for the first communication from the MASTER **FLASHES** if no INPUT or OUTPUT requested by the configuration **ON** if INPUT or OUTPUT requested by the configuration	**OFF** operation OK	**OFF** operation OK	Shows the NODE_SEL0/1 signal table	OUTPUT condition

Table 38 - Dynamic screen

English

MOS16 (Figure 21)

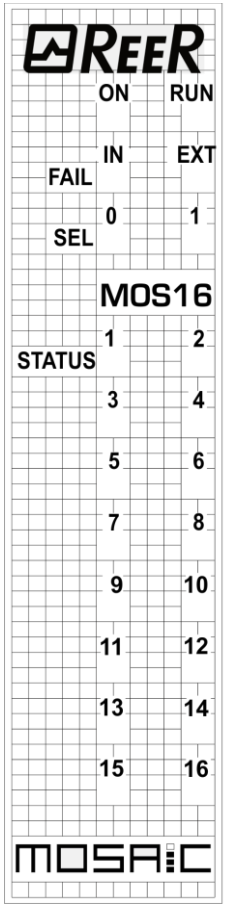


Figure 21 - MOS16

LED					
MEANING	RUN	IN FAIL	EXT FAIL	SEL 0/1	STATUS1/16
	GREEN	RED	RED	ORANGE	YELLOW
Power on - initial TEST	ON	ON	ON	ON	ON

Table 39 - Opening screen

LED					
MEANING	RUN	IN FAIL	EXT FAIL	SEL 0/1	STATUS1/16
	GREEN	RED	RED	ORANGE	YELLOW
NORMAL OPERATION	**OFF** if the unit is waiting for the first communication from the MASTER **FLASHES** if no INPUT or OUTPUT requested by the configuration **ON** if INPUT or OUTPUT requested by the configuration	**OFF** operation OK	**OFF** operation OK	Shows the NODE_SEL0/1 signal table	OUTPUT condition

Table 40 - Dynamic screen

English

MV1, MV2 (Figure 22)

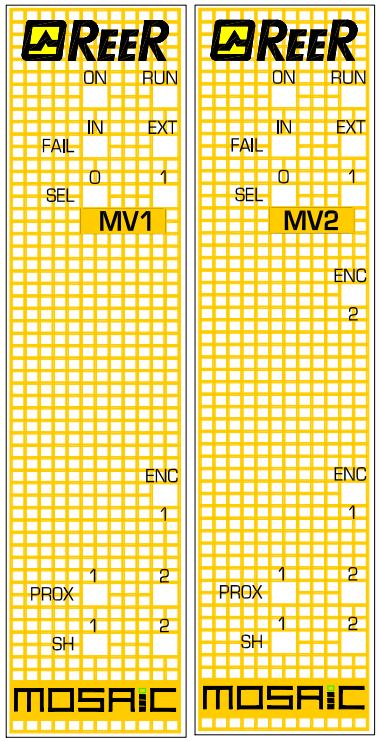


Figure 22 - MV1, MV2

MEANING	LED						
	RUN	IN FAIL	EXT FAIL	SEL	ENC*	PROX	SH
	GREEN	RED	RED	ORANGE	YELLOW	YELLOW	YELLOW
Power on – initial TEST	**ON**	**ON**	**ON**	**ON**	**ON**	**ON**	**ON**

Table 41 - Opening screen

MEANING	LED						
	RUN	IN FAIL	EXT FAIL	SEL	ENC*	PROX	SH
	GREEN	RED	RED	ORANGE	YELLOW	YELLOW	YELLOW
NORMAL OPERATION	**OFF** if the unit is waiting for the first communication from the MASTER **FLASHES** if no INPUT or OUTPUT requested by the configuration **ON** if INPUT or OUTPUT requested by the configuration	**OFF** operation OK	**OFF** operation OK	Shows the NODE_SEL0/1 signal table	**ON** Encoder connected and operative	**ON** Proximity connected and operative	**OFF** Axis in normal speed range **ON** Axis in stand still **BLINKING** Axis in overspeed

Table 42 - Dynamic screen

* NOT PRESENT ON MV0 MODULE

English

MR2 (Figure 23) / MR4 (Figure 24)

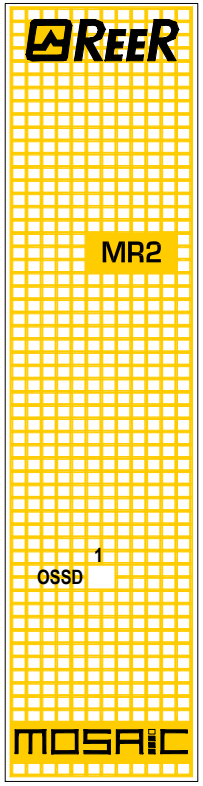


Figure 23 - MR2

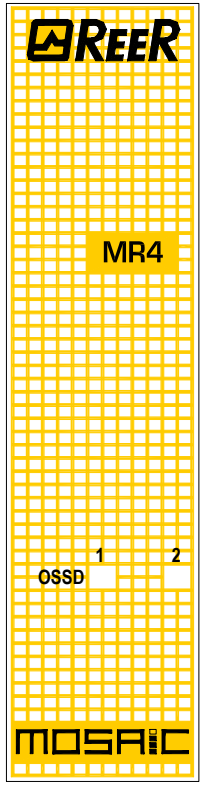


Figure 24 - MR4

MEANING	LED
	OSSD1 GREEN
NORMAL OPERATION	**ON** with output activated

Table 43 - MR2 - Dynamic screen

MEANING	LED	
	OSSD1 GREEN	OSSD2 GREEN
NORMAL OPERATION	**ON** with output activated	

Table 44 - MR4 - Dynamic screen

English

TROUBLESHOOTING

Master M1 (Figure 25)

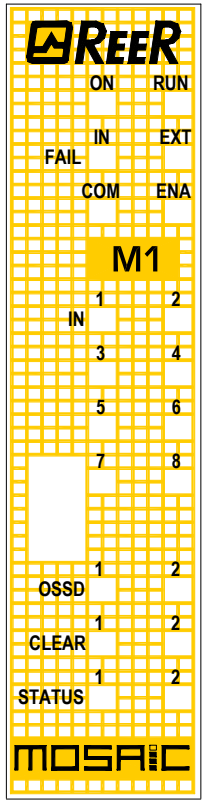


Figure 25 - M1

MEANING	LED									REMEDY
	RUN GREEN	IN FAIL RED	EXT FAIL RED	COM ORANGE	IN1÷8 YELLOW	ENA BLUE	OSSD1/2 RED/GREEN	CLEAR1/2 YELLOW	STATUS1/2 YELLOW	
Internal fault	OFF	**2 or 3 flashes**	OFF	OFF	OFF	OFF	Red	OFF	OFF	Return the unit to ReeR to be repaired
OSSD output error	OFF	**4 flashes**	OFF	OFF	OFF	OFF	**4 flashes (only the LED corresponding to the output in FAIL mode)**	OFF	OFF	• Check the OSSD1/2 connections • If the problem persists return the M1 to ReeR to be repaired
Error in communication with slave	OFF	**5 flashes**	OFF	OFF	OFF	OFF	OFF	OFF	OFF	• Restart the system. • If the problem persists return the M1 to ReeR to be repaired
Slave unit error	OFF	**ON**	OFF	OFF	OFF	OFF	OFF	OFF	OFF	• Restart the system • Check which unit is in FAIL mode
MCM error	OFF	**6 flashes**	OFF	**6 flashes**	OFF	OFF	OFF	OFF	OFF	Replace the MCM

Table 45 - Troubleshooting M1

English

MI8O2 (Figure 26)

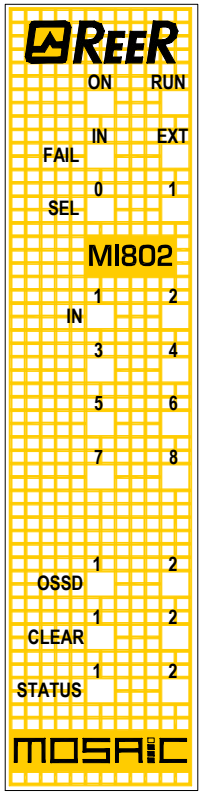


Figure 26 - MI8O2

MEANING	LED								REMEDY
	RUN	IN FAIL	EXT FAIL	SEL	IN1÷8	OSSD1/2	CLEAR1/2	STATUS1/2	
	GREEN	RED	RED	ORANGE	YELLOW	RED/GREEN	YELLOW	YELLOW	
Internal fault	OFF	**2 or 3 flashes**	OFF	Shows the physical address of the unit	OFF	Red	OFF	OFF	• Return the unit to ReeR to be repaired
Compatibility error	OFF	**5 flashes**	OFF		**5 flashes**	**5 flashes**	**5 flashes**	**5 flashes**	• Firmware version not compatible with M1, return to ReeR for FW upgrade.
OSSD output error	OFF	**4 flashes**	OFF		OFF	**4 flashes (only the LED corresponding to the output in FAIL mode)**	OFF	OFF	• Check OSSD1/2 connections • If the problem persists, return the MI8O2 to ReeR to be repaired
Error in communication with master	OFF	**5 flashes**	OFF		OFF	OFF	OFF	OFF	• Restart the system • If the problem persists, return the MI8O2 to ReeR to be repaired
Error on other slave or M1	OFF	**ON**	OFF		OFF	OFF	OFF	OFF	• Restart the system • Check which unit is in FAIL mode
Same type of slave with same address detected	OFF	**5 flashes**	**5 flashes**		OFF	OFF	OFF	OFF	• Change the unit's address (see **NODE SEL**)
Node detection circuit error	OFF	**3 flashes**	OFF	**3 flashes**	OFF	OFF	OFF	OFF	• Return the unit to ReeR to be repaired

Table 46 - Troubleshooting MI8O2

English

MI8 (Figure 27)

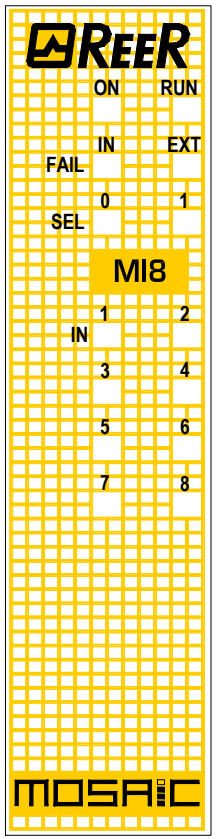


Figure 27 - MI8

MEANING	LED					REMEDY
	RUN	IN FAIL	EXT FAIL	SEL	IN1÷8	
	GREEN	RED	RED	ORANGE	YELLOW	
Internal fault	OFF	**2 or 3 flashes**	OFF	Shows the physical address of the unit	OFF	• Return the unit to ReeR to be repaired
Compatibility error	OFF	**5 flashes**	OFF		**5 flashes**	• Firmware version not compatible with M1, return to ReeR for FW upgrade.
Error in communication with master	OFF	**5 flashes**	OFF		OFF	• Restart the system • If the problem persists, return the MI8 to ReeR to be repaired
Error on other slave or M1	OFF	**ON**	OFF		OFF	• Restart the system • Check which unit is in FAIL mode
Same type of slave with same address detected	OFF	**5 flashes**	**5 flashes**		OFF	• Change the unit's address (see **NODE SEL**)
Node detection circuit error	OFF	**3 flashes**	OFF	**3 flashes**	OFF	• Return the unit to ReeR to be repaired

Table 47 - Troubleshooting MI8

English

MI12T8 (Figure 28)

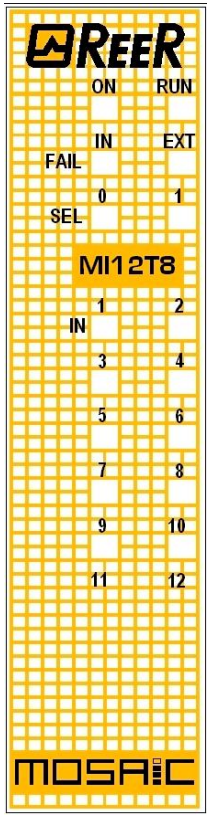


Figure 28 - MI12T8

LED						
MEANING	RUN	IN FAIL	EXT FAIL	SEL	IN1÷12	REMEDY
	GREEN	RED	RED	ORANGE	YELLOW	
Internal fault	OFF	**2 or 3 flashes**	OFF	Shows the physical address of the unit	OFF	Return the unit to ReeR to be repaired
Compatibility error	OFF	**5 flashes**	OFF		**5 flashes**	• Firmware version not compatible with M1, return to ReeR for FW upgrade.
Error in communication with master	OFF	**5 flashes**	OFF		OFF	• Restart the system • If the problem persists, return the MI12T8 to ReeR to be repaired
Error on other slave or M1	OFF	**ON**	OFF		OFF	• Restart the system • Check which unit is in FAIL mode
Same type of slave with same address detected	OFF	**5 flashes**	**5 flashes**		OFF	• Change the unit's address (see **NODE SEL**)
Node detection circuit error	OFF	**3 flashes**	OFF	**3 flashes**	OFF	• Return the unit to ReeR to be repaired

Table 48 - Troubleshooting MI12T8

English

MI16 (Figure 29 - MI16)

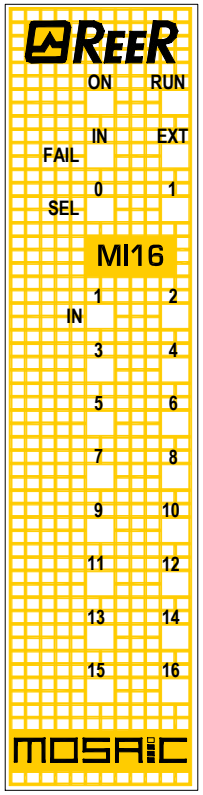


Figure 29 - MI16

MEANING	LED					REMEDY
	RUN	IN FAIL	EXT FAIL	SEL	IN1÷16	
	GREEN	RED	RED	ORANGE	YELLOW	
Internal fault	OFF	**2 or 3 flashes**	OFF	Shows the physical address of the unit	OFF	• Return the unit to ReeR to be repaired
Compatibility error	OFF	**5 flashes**	OFF		**5 flashes**	• Firmware version not compatible with M1, return to ReeR for FW upgrade.
Error in communication with master	OFF	**5 flashes**	OFF		OFF	• Restart the system • If the problem persists, return the MI16 to ReeR to be repaired
Error on other slave or M1	OFF	**ON**	OFF		OFF	• Restart the system • Check which unit is in FAIL mode
Same type of slave with same address detected	OFF	**5 flashes**	**5 flashes**		OFF	• Change the unit's address (see **NODE SEL**)
Node detection circuit error	OFF	**3 flashes**	OFF	**3 flashes**	OFF	• Return the unit to ReeR to be repaired

Table 49 - Troubleshooting MI16

English

MO2 / MO4 (Figure 30)

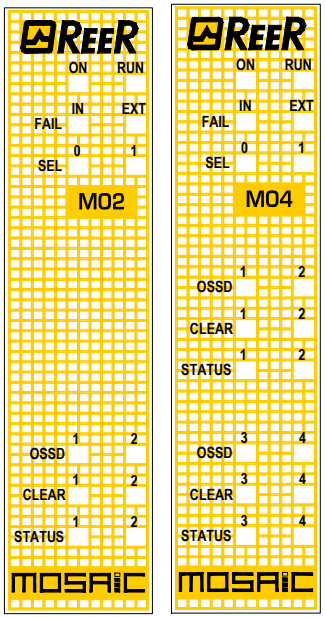


Figure 30 - MO2 / MO4

MEANING	LED							REMEDY
	RUN	IN FAIL	EXT FAIL	SEL	OSSD1/4	CLEAR1/4	STATUS1/4	
	GREEN	RED	RED	ORANGE	RED/GREEN	YELLOW	YELLOW	
Internal fault	OFF	2 or 3 flashes	OFF	Shows the physical address of the unit	Red	OFF	OFF	Return the unit to ReeR to be repaired
Compatibility error	OFF	5 flashes	OFF		5 flashes	5 flashes	5 flashes	• Firmware version not compatible with M1, return to ReeR for FW upgrade.
OSSD output error	OFF	4 flashes	OFF		4 flashes (only the LED corresponding to the output in FAIL mode)	OFF	OFF	• Check OSSD1/2 connections • If the problem persists, return the MO2/4 to ReeR to be repaired
Error in communication with master	OFF	5 flashes	OFF		OFF	OFF	OFF	• Restart the system • If the problem persists, return the MO2/4 to ReeR to be repaired
Error on other slave or M1	OFF	ON	OFF		OFF	OFF	OFF	• Restart the system • Check which unit is in FAIL mode
Same type of slave with same address detected	OFF	5 flashes	5 flashes		OFF	OFF	OFF	• Change the unit's address (see **NODE SEL**)
Power supply missing on OSSD 3,4 (MO4 only)	ON	OFF	ON		Red flashes	flashes	OUTPUT condition	• Connect 13 and 14 pin to power supply
Status output overload or short circuit	OFF	OFF	ON		OUTPUT condition	CLEAR condition	flashes	• Check STATUS connections
Error on node detection circuit	OFF	3 flashes	OFF	3 flashes	OFF	OFF	OFF	• Return the MO2/4 to ReeR to be repaired

Table 50 - Troubleshooting MO2/MO4

English

MOR4 (Figure 31)

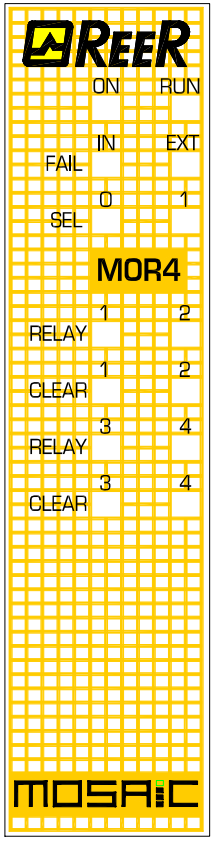


Figure 31 - MOR4

MEANING	LED						REMEDY
	RUN	IN FAIL	EXT FAIL	SEL 0/1	RELAY 1/4	CLEAR1/4	
	GREEN	RED	RED	ORANGE	RED / GREEN	YELLOW	
Internal fault	OFF	**2 / 3 flashes**	OFF	Shows the physical address of the unit	**Rosso**	OFF	• Return the unit to ReeR to be repaired
Compatibility error	OFF	**5 flashes**	OFF		**5 flashes**	**5 flashes**	• Firmware version not compatible with M1, return to ReeR for FW upgrade.
Relais output error	OFF	**4 flashes**	OFF		**4 flashes (only the LED corresponding to the output in FAIL mode)**	OFF	• If the problem persists, return the module to ReeR to be repaired
Error in communication with master	OFF	**5 flashes**	OFF		OFF	OFF	• Restart the system • If the problem persists, return the module to ReeR to be repaired
Error on other slave or M1	OFF	**ON**	OFF		OFF	OFF	• Restart the system • Check which unit is in FAIL mode
Same type of slave with same address detected	OFF	**5 flashes**	**5 flashes**		OFF	OFF	• Change the unit's address (see **NODE SEL**)
External contactors feedback error on Category 4 relay	ON	OFF	**4 flashes**		**4 flashes (only the LEDs corresponding to the outputs in FAIL mode)**		• Verify connections 5,6,7,8.
Error on node detection circuit	OFF	**3 flashes**	OFF	**3 flashes**	OFF	OFF	• Return the module to ReeR to be repaired

Table 51 - Troubleshooting MOR4

English

MOR4S8 (Figure 32)

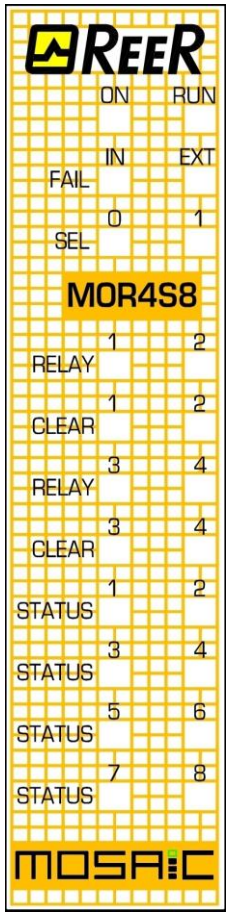


Figure 32 - MOR4S8

MEANING	LED							REMEDY
	RUN	IN FAIL	EXT FAIL	SEL 0/1	RELAY 1/4		CLEAR1/4	STATUS1/8	
	GREEN	RED	RED	ORANGE	RED	GREEN	YELLOW	YELLOW	
Internal fault	OFF	**2 / 3 flashes**	OFF	Shows the physical address of the unit	**Rosso**		OFF		• Return the unit to ReeR to be repaired
Compatibility error	OFF	**5 flashes**	OFF		**5 flashes**		**5 flashes**	**5 flashes**	• Firmware version not compatible with M1, return to ReeR for FW upgrade.
Relais output error	OFF	**4 flashes**	OFF		**4 flashes (only the LED corresponding to the output in FAIL mode)**		OFF	OFF	• If the problem persists, return the module to ReeR to be repaired
Error in communication with master	OFF	**5 flashes**	OFF		OFF		OFF	OFF	• Restart the system • If the problem persists, return the module to ReeR to be repaired
Error on other slave or M1	OFF	**ON**	OFF		OFF		OFF	OFF	• Restart the system • Check which unit is in FAIL mode
Same type of slave with same address detected	OFF	**5 flashes**	**5 flashes**		OFF		OFF	OFF	• Change the unit's address (see **NODE SEL**)
External contactors feedback error on Category 4 relay	ON	OFF	**4 flashes**		**4 flashes (only the LEDs corresponding to the outputs in FAIL mode)**			OFF	• Verify connections 5,6,7,8.
Error on node detection circuit	OFF	**3 flashes**	OFF	**3 flashes**	OFF		OFF	OFF	• Return the module to ReeR to be repaired
Short circuit or overload detected on status output	OFF	OFF	**ON**	OFF	**OUTPUT condition**		**CLEAR condition**	**flash**	• Verify output status connections

Table 52 - Troubleshooting MOR4S8

English

MOS8 (Figure 33)

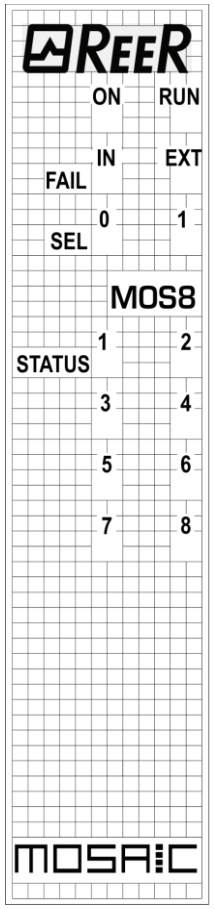


Figure 33 – MOS8

MEANING	LED					REMEDY
	RUN	IN FAIL	EXT FAIL	SEL 0/1	STATUS1/8	
	GREEN	RED	RED	ORANGE	YELLOW	
Internal fault	OFF	**2 / 3 flashes**	OFF	Shows the physical address of the unit	OFF	• Return the unit to ReeR to be repaired
Compatibility error	OFF	**5 flashes**	OFF		**5 flashes**	• Firmware version not compatible with M1, return to ReeR for FW upgrade.
Error in communication with master	OFF	**5 flashes**	OFF		OFF	• Restart the system • If the problem persists, return the module to ReeR to be repaired
Error on other slave or M1	OFF	**ON**	OFF		OFF	• Restart the system • Check which unit is in FAIL mode
Same type of slave with same address detected	OFF	**5 flashes**	**5 flashes**		OFF	• Change the unit's address (see **NODE SEL**)
Error on node detection circuit	OFF	**3 flashes**	OFF	**3 flashes**	OFF	• Return the module to ReeR to be repaired
Short circuit or overload detected on status 1-8 output	OFF	OFF	**ON**	OFF	**flash**	• Verify output status 1-8 connections
Power supply missing on status 1-8 output	OFF	OFF	**ON**	OFF	**flash alternatively**	• Connect 5 pin to power supply

Table 53 - Troubleshooting MOS8

English

MOS16 (Figure 34)

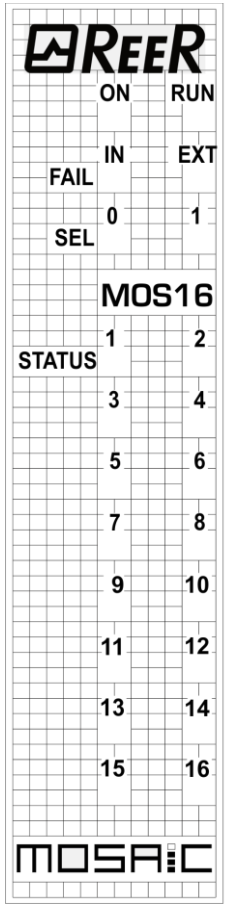


Figure 34 - MOS16

MEANING	LED						REMEDY
	RUN	IN FAIL	EXT FAIL	SEL 0/1	STATUS1/8	STATUS9/16	
	GREEN	RED	RED	ORANGE	YELLOW	YELLOW	
Internal fault	OFF	**2 / 3 flashes**	OFF	Shows the physical address of the unit	OFF	OFF	• Return the unit to ReeR to be repaired
Compatibility error	OFF	**5 flashes**	OFF		**5 flashes**	**5 flashes**	• Firmware version not compatible with M1, return to ReeR for FW upgrade.
Error in communication with master	OFF	**5 flashes**	OFF		OFF	OFF	• Restart the system • If the problem persists, return the module to ReeR to be repaired
Error on other slave or M1	OFF	**ON**	OFF		OFF	OFF	• Restart the system • Check which unit is in FAIL mode
Same type of slave with same address detected	OFF	**5 flashes**	**5 flashes**		OFF	OFF	• Change the unit's address (see **NODE SEL**)
Error on node detection circuit	OFF	**3 flashes**	OFF	**3 flashes**	OFF	OFF	• Return the module to ReeR to be repaired
Short circuit or overload detected on status 1-8 output	OFF	OFF	**ON**	OFF	**flash**	OFF	• Verify output status 1-8 connections
Short circuit or overload detected on status 9-16 output	OFF	OFF	**ON**	OFF	OFF	**flash**	• Verify output status 9-16 connections
Power supply missing on status 1-8 output	OFF	OFF	**ON**	OFF	**flash alternatively**	OFF	• Connect 5 pin to power supply
Power supply missing on status 9-16 output	OFF	OFF	**ON**	OFF	OFF	**flash alternatively**	• Connect 6 pin to power supply

Table 54 - Troubleshooting MOS16

English

MV0, MV1, MV2 (Figure 32)

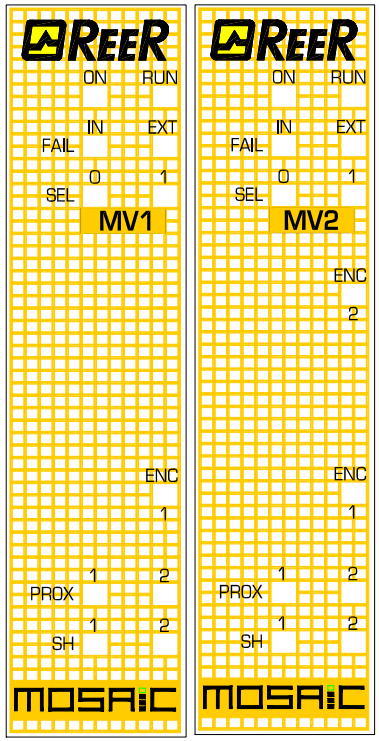


Figure 35 - MV1, MV2

MEANING	LED							REMEDY
	RUN	IN FAIL	EXT FAIL	SEL	ENC*	PROX	SH	
	GREEN	RED	RED	ORANGE	YELLOW	YELLOW	YELLOW	
Internal fault	OFF	**2 or 3 flashes**	OFF	Shows the physical address of the unit	OFF	OFF	OFF	• Return the unit to ReeR to be repaired
Compatibility error	OFF	**5 flashes**	OFF		**5 flashes**	**5 flashes**	**5 flashes**	• Firmware version not compatible with M1, return to ReeR for FW upgrade.
Encoder INTERNAL error	OFF	**3 flashes**	OFF		**3 flashes**	OFF	OFF	• Change the encoder • Return the unit to ReeR to be repaired
Proximity INTERNAL error		**3 flashes**	OFF			**3 flashes**		• Change the proximity • Return the unit to ReeR to be repaired
Error on node detection circuit	OFF	**3 flashes**	OFF	**3 flashes**	OFF	OFF	OFF	• Return the unit to ReeR to be repaired
Same type of slave with same address detected	OFF	**5 flashes**	**5 flashes**		OFF	OFF	OFF	• Change the unit's address (see **NODE SEL**)
Encoder not connected but requested from the configuration	OFF	OFF	**3 flashes** **		**3 flashes** **	OFF	OFF	• Verify encoder connection and power supply • Verify input frequency (in range)
Proximity not connected but requested from the configuration	OFF	OFF	**3 flashes** **		OFF	**3 flashes** **	OFF	• Verify proximity connection • Verify input frequency (in range)

Table 55 - Troubleshooting MV1/MV2

* NOT PRESENT ON MV0 MODULE

** WITH FAULT OF A SINGLE CHANNEL, THE SIGNAL IS PRESENTED IN TWO TEMPORAL WINDOWS: IN THE FIRST IS SHOWED TE FAULT, IN THE SECOND IS SHOWED THE CORRECT CHANNEL.

English

MOSAIC SAFETY DESIGNER SOFTWARE

The ***"MOSAIC SAFETY DESIGNER"*** application software can be used to configure a logic diagram of the connections between the MOSAIC (Master + expansions) and the components of the system being developed.

The MOSAIC and its SLAVE units will thus monitor and control the connected safety components.

The MSD uses a versatile graphic interface to establish the connections between the various components, as described below:

Installing the software

PC HARDWARE requirements

- RAM: 256 MB
  (adequate to run *Windows XP SP3 + Framework 4.0*)
- Hard disk: ≥ 500Mbyte of free space
- USB connector: 1.1, 2.0 or 3.0
- CD-ROM drive

PC SOFTWARE requirements

- Windows XP with Service Pack 3 installed (or higher OS).

➔ Microsoft Framework 4.0 (or higher) must be installed on the PC

How to install MSD

- Insert the installation CD;
- Wait for the auto-run installer to request the SW setup program;

Alternatively follow the path D:/;

- Double-click on the **SetupDesigner.exe** file;

When the installation procedure is complete a window is displayed asking you to close the setup program.

English

Fundamentals

Once the MSD has been correctly installed it creates an icon on the desktop. To launch the program: double-click on this icon. => 

The opening screen shown below is displayed:

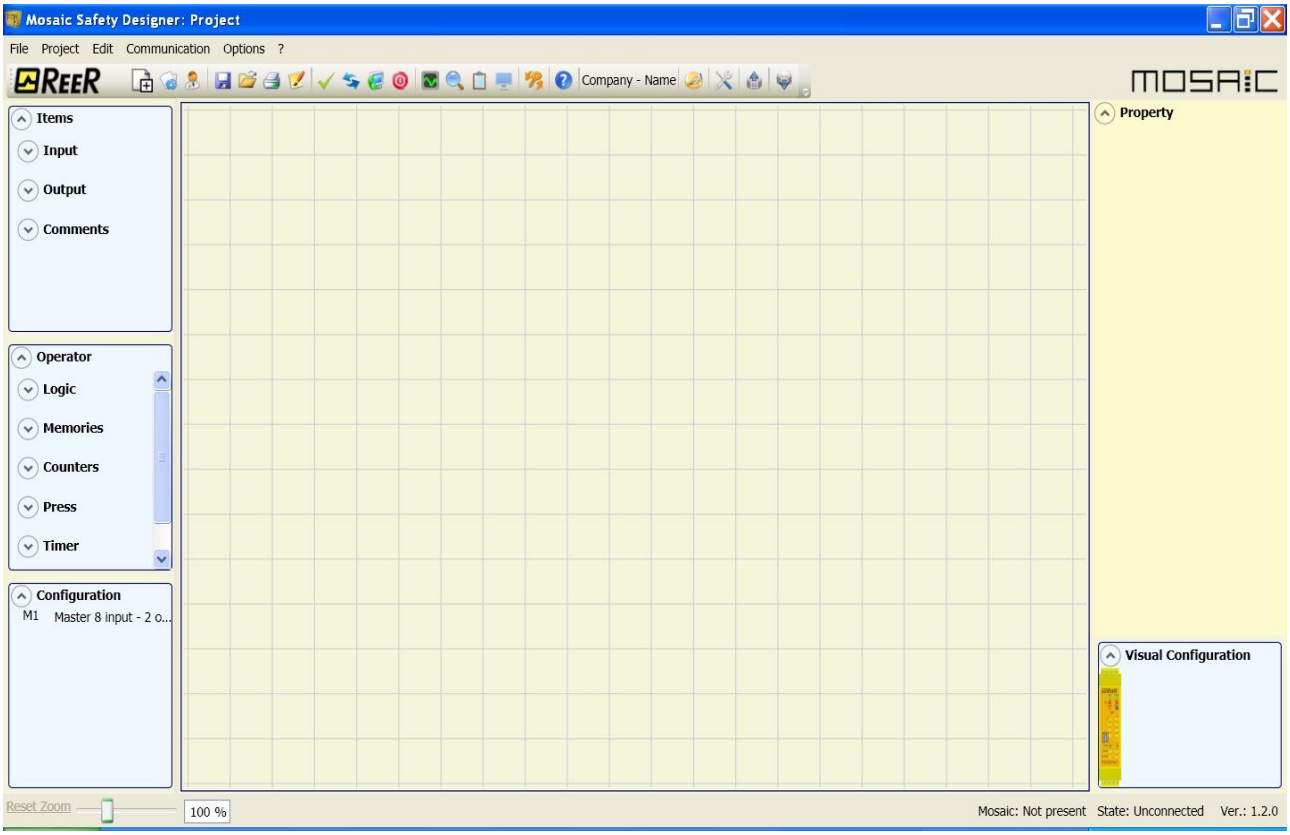


Figure 36

You are now ready to create your project.

English

Standard tool bar

The standard tool bar is shown in Figure 37. The meanings of the icons are listed below:

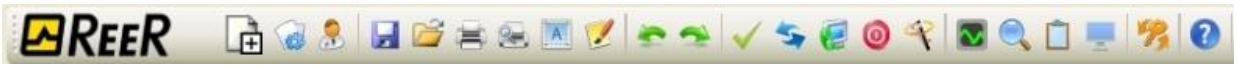


Figure 37

1 -> **CREATE A NEW PROJECT**

2 -> **CHANGE CONFIGURATION** (composition of different modules)

3 -> **CHANGE USER PARAMETERS** (name, company, etc)

4 -> **SAVE THE ACTUAL PROJECT**

5 -> **LOAD AN EXISTING PROJECT (FROM THE PC)**

6 -> **PRINT THE PROJECT SCHEMATIC**

7 -> **PRINT PREVIEW**

8 -> **PRINTING AREA**

9 -> **PRINT THE PROJECT REPORT**

10 -> **UNDO (CANCEL THE LAST COMMAND)**

11 -> **REDO (RESTORE THE LAST CANCELLATION)**

12 -> **VALIDATE THE PROJECT**

13 -> **CONNECT TO MOSAIC**

14 -> **SEND PROJECT TO MOSAIC**

15 -> **DISCONNECT FROM MOSAIC**

16 -> **DOWNLOAD AN EXISTING PROJECT (FROM MOSAIC)**

17 -> **MONITOR** (Real time I/O status - **graphic**)

18 -> **MONITOR** (Real time I/O status - **textual**)

19 -> **DOWNLOAD LOG FILE**

20 -> **SHOW SYSTEM CONFIGURATION**

21 -> **CHANGE PASSWORD**

22 -> **HELP ON-LINE**

23 -> **PASSWORD RECOVERY**

Textual tool bar

Optionally the textual tool bar shown below is also available (drop down).

Figure 38

Create a new project (configure the MOSAIC system)

Select icon CREATE (Figure 37) from the standard tool bar to start a new project. The user authentication window is displayed (Figure 39).

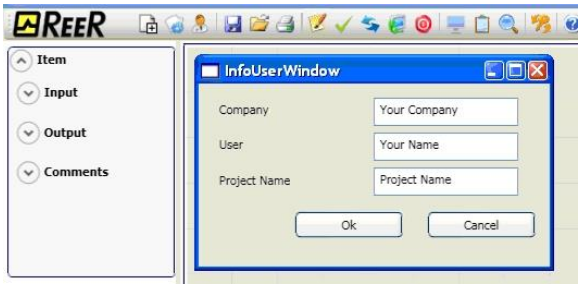


Figure 39

Next the MSD displays a window showing the M1 only.
You may add the various units needed to create your system, using the pull-down menus at the top of the screen (select slave) and at the bottom to select the relative node (0÷3).

SELECT SLAVE (to add to your configuration)

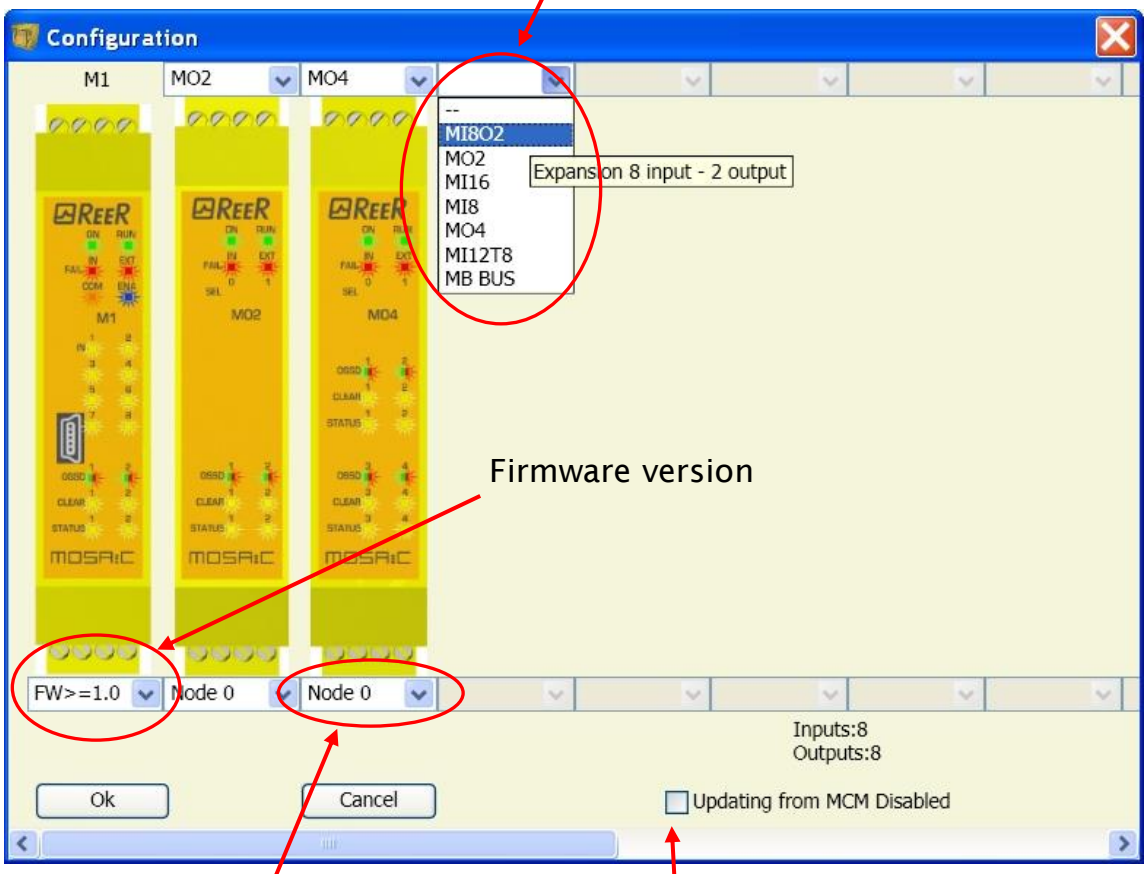


Figure 40

SELECT NODE (from 0 to 3)

Select to disable MCM operations

English

EDIT CONFIGURATION (composition of the various modules)

The change of the system composition is obtained with the icon  .
The configuration window is showed again (Figure 37).

Change user parameters

The change of user parameters is obtained with the icon  .
The dialog user identification request appears (Figure 41). To accomplish this operation is not necessary to Log out from Mosaic. Generally it serves when a new user must create a new project (even using a previously created).

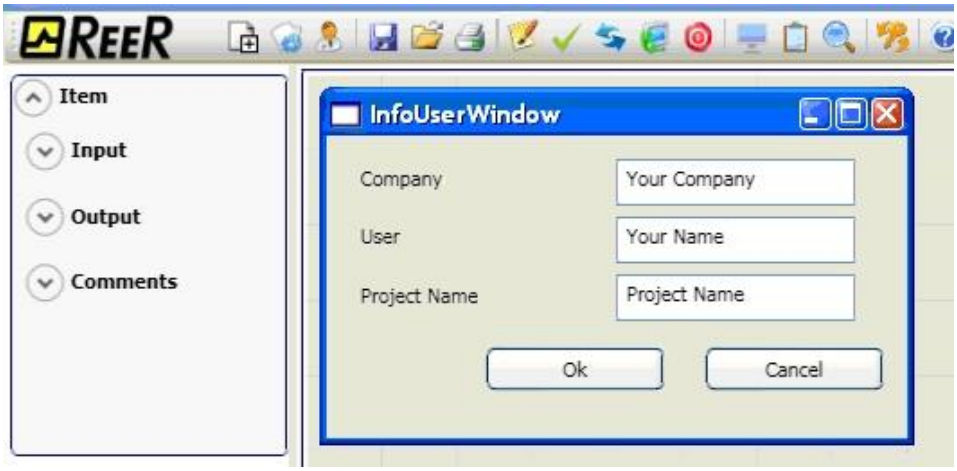


Figure 41

OBJECTS - OPERATOR - CONFIGURATION tool bars

Four large tool windows are displayed to the left and right of the main window (shown in Figure 42):

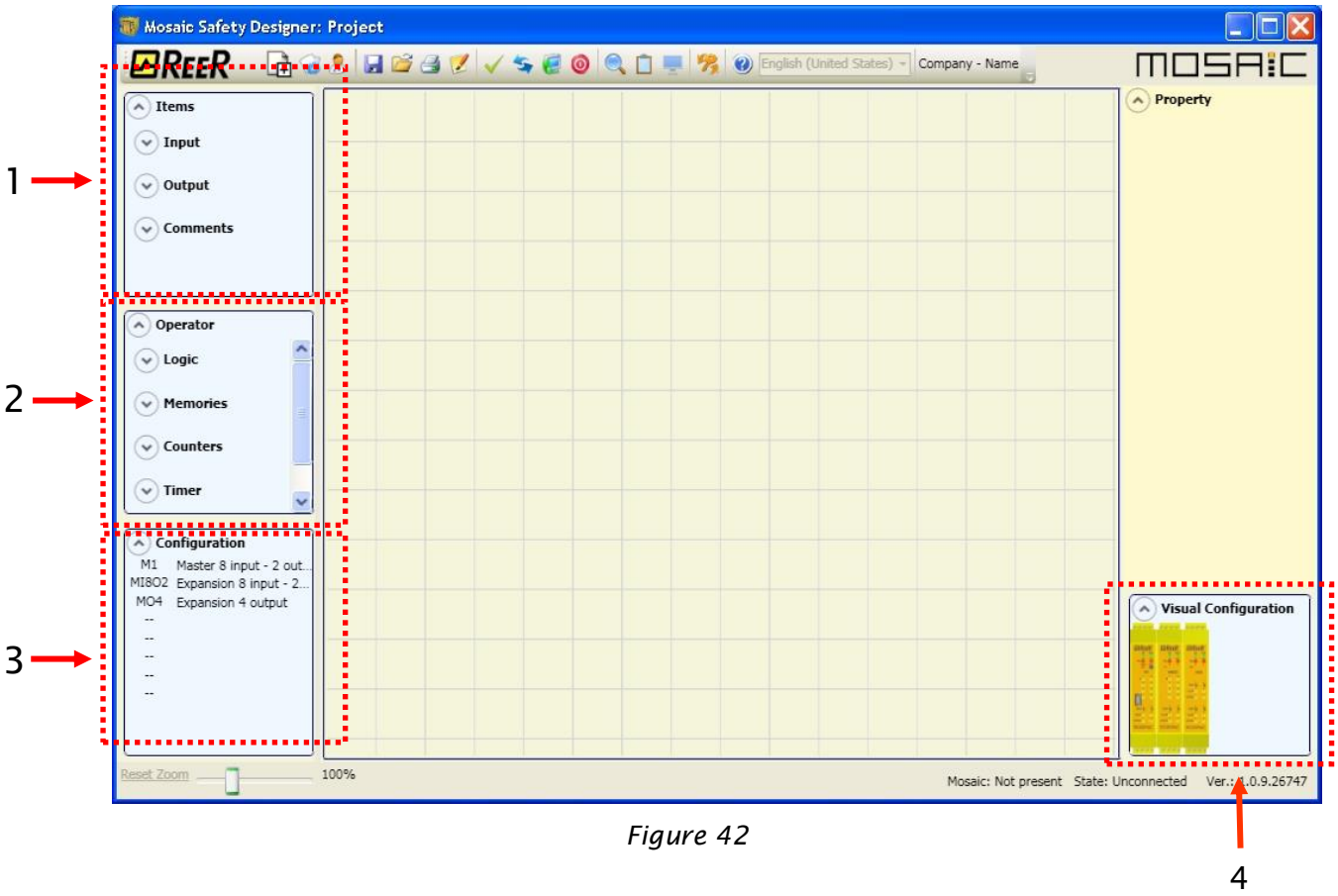


Figure 42

1 > OBJECT TOOL WINDOW

This contains the various function blocks that will make up your project; these blocks are divided into 3 different types:

- **physical**
- **inputs**
- **outputs**
- **comments**

2 > OPERATOR TOOL WINDOW

This contains the various function blocks for connecting the objects in point 1; these blocks are divided into 6 different types:

- **logical**
- **muting**
- **memories**
- **counters**
- **timers**

3 > CONFIGURATION TOOL WINDOW

This contains the description of your project composition.

4 > CONFIGURATION TOOL WINDOW (view)

This contains the graphic representation of your project composition.

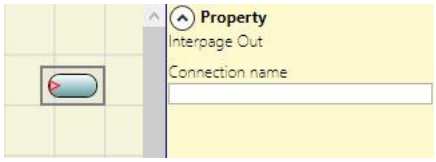
English

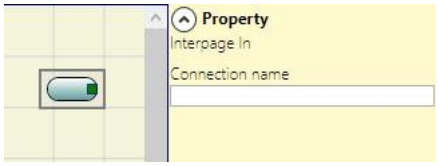
Creating the diagram

Once you have selected your system composition, you are ready to configure the project.
The logic diagram is created using a **DRAG&DROP** function:

- Select the objects as required from the windows described previously (each single object is described in detail in the following sections) and drag it into the design area.
- Now when you select the object the **PROPERTIES** window is enabled, where you must fill in the fields as required.
- When you need to set a specific numerical value with a slide (eg filter) use the left and right arrows on your keyboard or click the sides of the slider of the slide.
- Connect the objects by moving the mouse over the required pin and then dragging it onto the pin to be connected.
- If the scheme requires the PAN function (moving working area in the window), select the object to move and use the arrow keys on your keyboard.
- If the scheme is very complicated and requires a connection between two elements very far, use the "Interpage" component. The element "*Interpage out*" must have a name which, invoked by the corresponding "*Interpage in*", allows the desired link.

(scheme side SX)





(scheme side SX)

- When you need to duplicate an object, select it and press CTRL+C / CTRL+V keys on your keyboard.
- When you need to delete an object or a link, select it and press DEL key on your keyboard.

Use of mouse right button

ON BLOCK INPUT / OUTPUT

- Copy / Paste
- Delete
- Delete all the assigned pins
- Alignment with other functional blocks (multiple selection)
- On-line Help
- Monitor Mode: Show / Hide Properties window
- The block Status: pin input enable / disable logical negation

ON BLOCK OPERATORS

- Copy / Paste
- Delete
- Alignment with other functional blocks (multiple selection)
- On-line Help
- On input pin: activate / deactivate logical negation
- Monitor Mode: Show / Hide Properties window

ON TERMINALS

- Alignment with other blocks

ON CONNECTION (WIRES)

- Delete
- Display full path of the connection (network)

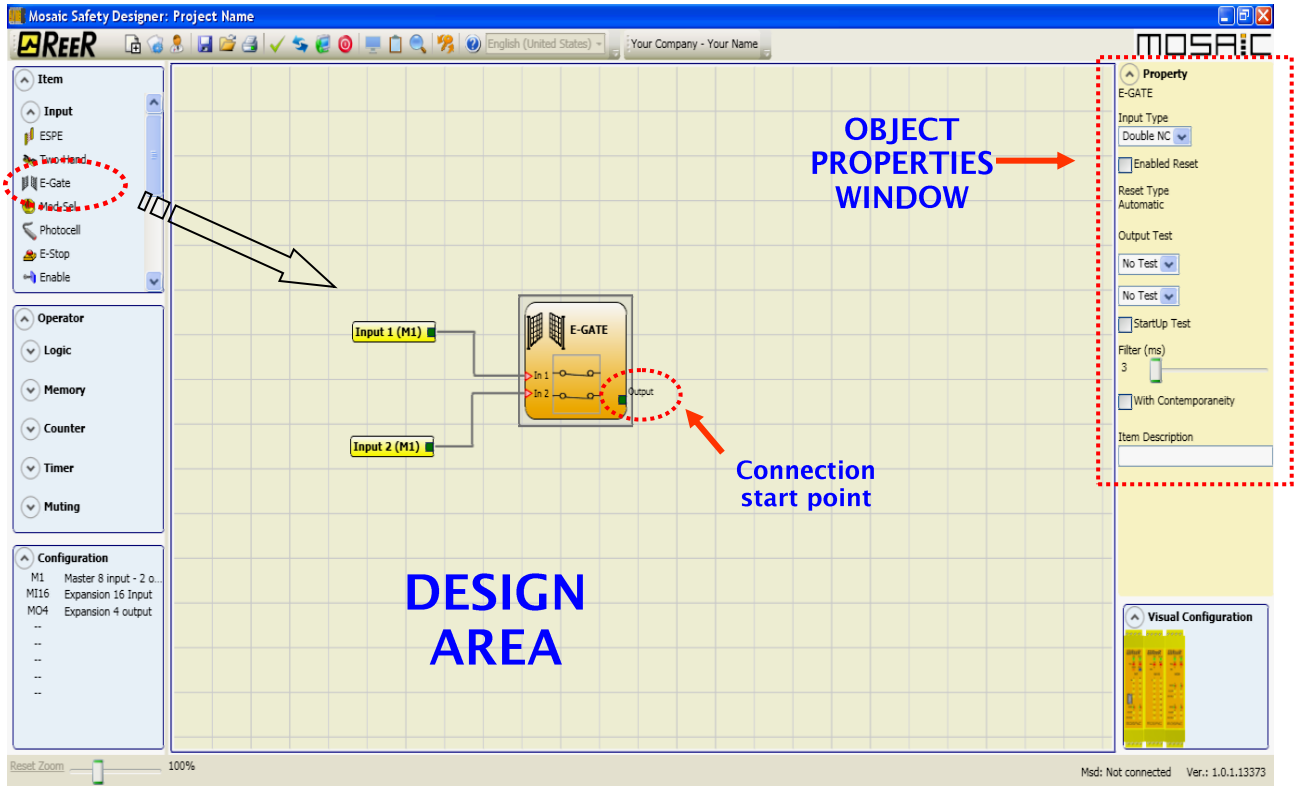


Figure 43

English

Example of a project

Figure 44 shows an example of a project in which the M1 unit only is connected to two safety blocks (E-GATE and E-STOP).
The M1 inputs (1,2,3) for connecting the contacts of the safety components are shown on the left, in yellow. The MOSAIC outputs (from 1 to 4) are activated according to the conditions defined in E-GATE and E-STOP (see the *E-GATE* - *E-STOP* sections).
By clicking on a block to select it, you enable the PROPERTIES WINDOW on the right, which you can use to configure the block activation and test parameters (see the *E-GATE* - *E-STOP* sections).

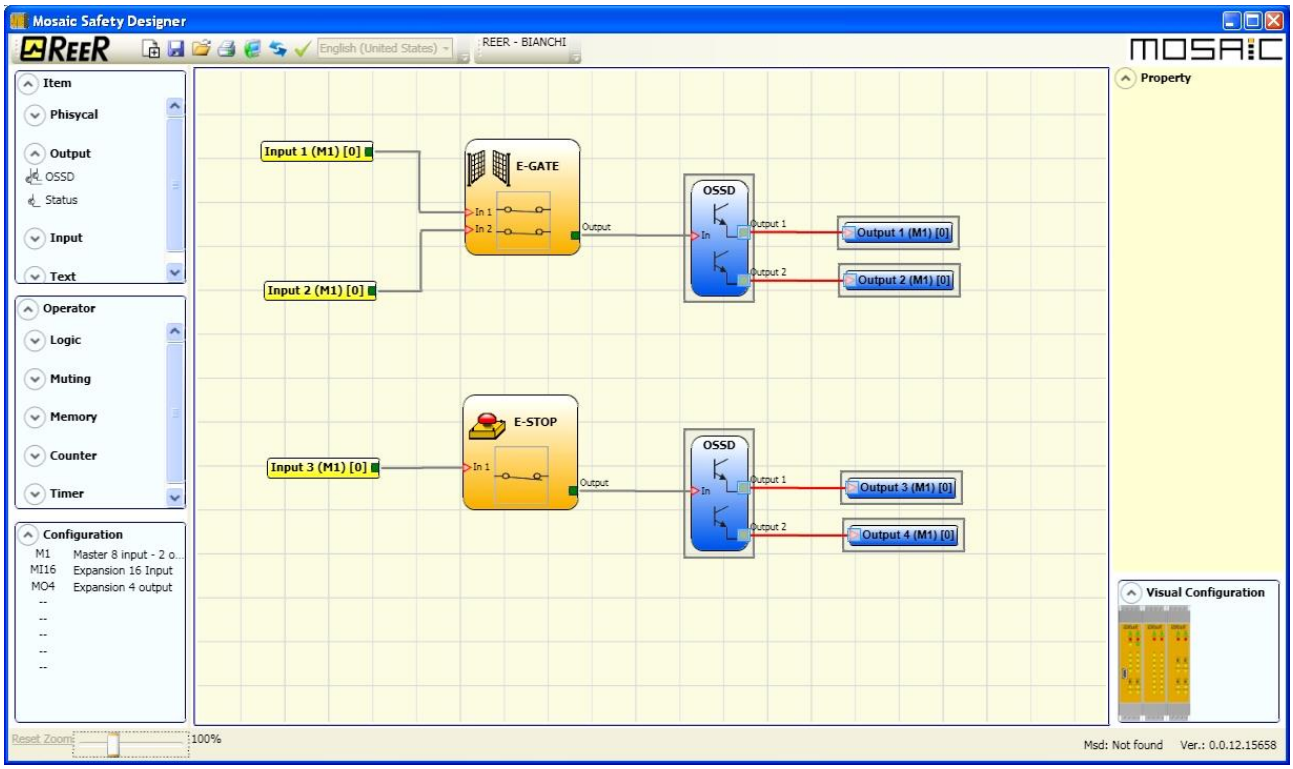


Figure 44

At the end of the project design stage (or at intermediate steps) you can save the current configuration using the icon **SAVE** on the standard tool bar.

Project validation

➔ Now the finished project must be verified. Execute the VALIDATE command (Icon on the standard toolbar).

If the validation is successful, a sequential number is assigned to the input and output of the project. Then, this number is also listed in the REPORT and in the MONITOR of MSD.
Only if the validation is successful we will proceed to send the configuration.

The validation function only verifies the consistency of programming with respect to the characteristics of the MOSAIC system. It does not guarantee that the device has been programmed to meet all the safety requirements for the application.

Project report

Print of the System composition with properties of each block. (Icon  on the standard toolbar).

MOdular SAfety Integrated Controller

Via Carcano, 32
10153 Torino Italia
http://www.reer.it

Project Report generated by Mosaic Safety Designer version 1.2.0

Project Name: Sch24 SOLID STATE DEVICE
User: Greco
Company: Reer
Date: 07/11/2011 14.28.48
Schematic CRC: 3A4BH

Mosaic: Configuration
Module M1 (Configured Firmware version: >= 1.0)
Module MI8O2 Node 0
Module MI8O2 Node 1
Module MO4 Node 0
Module MI12T8 Node 0

Mosaic: Safety Information's
PFHd (according to IEC 61508): 2,42E-008 (1/h)
MTTFd (according to EN ISO 13849-1): 85 years
DCavg (according to EN ISO 13849-1): 98.04 %

Resources used

INPUT: 22% (8/36)
Functional Blocks: 3

Timing: 6% (1/16)
Total number blocks: 5% (3/64)

OSSD: 50% (5/10)
STATUS: 20% (2/10)

Electrical diagram

SSD
Functional Block 1
Filter (ms): 3
Contemporaneity (ms): 10
Reset Type: Automatic
StartUp Test: True
Connections:
M1 INPUT1/Terminal17
M1 INPUT2/Terminal18

SSD
Functional Block 2
Filter (ms): 100
Contemporaneity (ms): 500
Reset Type: Manual
StartUp Test: False
Connections:
MI8O2 - 0 INPUT1/Terminal17
MI8O2 - 0 INPUT2/Terminal18
MI8O2 - 0 INPUT3/Terminal19

SSD
Functional Block 3
Filter (ms): 250
Contemporaneity (ms): 1000
Reset Type: Monitored
StartUp Test: False

- This definition of PL and of the other related parameters as set forth in ISO 13849-1 only refers to the functions implemented in the Mosaic system by the MSD configuration software, assuming configuration has been performed correctly.
- The actual PL of the entire application and the relative parameters must consider data for all the devices connected to the Mosaic system within the scope of the application.
- This must only be performed by the user/installer.

English

Connect to Mosaic

After connecting M1 to the PC via CSU cable (USB) use the icon for the connection.
A window appears to request the password. Enter the password (see "Password protection").

➔ If a remote connection (via internet) is needed M1 can connect to the appropriate devices through its USB port.

➔ In this case (ONLY WITH FW ≥ 3.0.1) select "Remote connection".

Figure 45

Sending the configuration to the MOSAIC

To send the saved configuration from a PC to M1 use the icon on the standard toolbar and wait the execution. M1 will save the project in its internal memory and (if present) in MCM memory. (Password Required: level 2).

➔ This function is possible only after project validation with OK result.

Download a configuration file (project) from Mosaic M1

To download a project from MOSAIC M1 to MSD use the icon on the Standard toolbar.
MSD will display the project residing in M1. (Sufficient Password level 1).

➔ If the project must be used on other modules M1 verify the components effectively connected (ref. **"System composition"** on page 73).

➔ Then perform a **"Project Validation"** (page 70) and a **"System Test"** (page 76).

Configuration LOG

➔ Within the configuration file (project), are included the **creation date** and **CRC (4-digit hexadecimal identification)** of a project that are stored in M1.

➔ This logbook can record up to 5 consecutive events, after which these are overwritten, starting from the least recent event.

The log file can be visualized using the icon in the standard tool bar.
(Password Required: level 1).

english

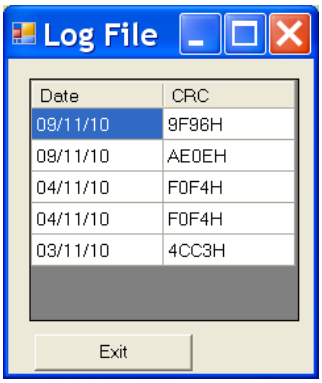


Figure 46

System composition

The check of the actual composition of the MOSAIC system is obtained using the icon  . (Password Required: level 1). A pop-up window will appear with:

- Connected modules;
- Firmware version of each module;
- Node number (physical address) of each module.

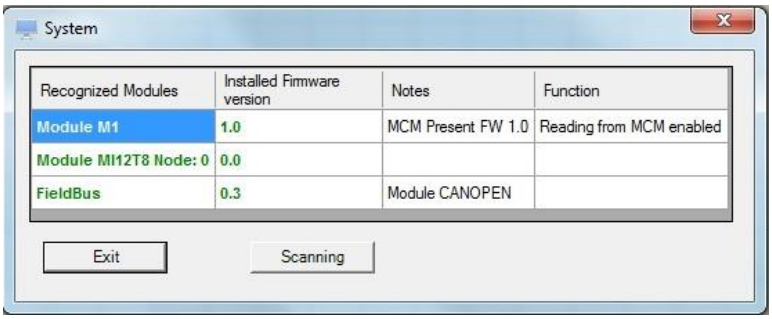


Figure 47

If the modules found are not correct the following window will appear;
e.g. MI12T8 node number not correct (displayed in red color text).

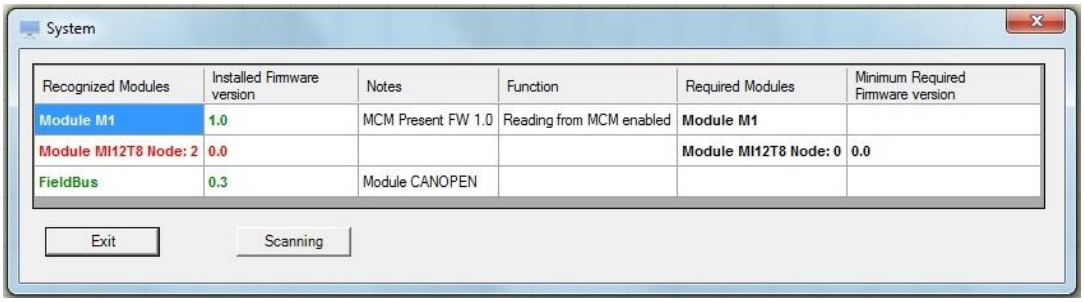


Figure 48

Disconnecting System

To disconnect the PC from M1 use the icon  ; when the system is disconnected it is resetted and it starts with the sent project.

➔ If the system is not composed of all modules provided by the configuration, after the disconnection, M1 indicates the incongruity and does not starts. (See SIGNALS).

English

MONITOR (I/O status in real time - textual)

To activate the monitor use the icon  . (Password Required: level 1).
A pop-up window will appear **(in real time)** with:

- Status of the inputs (when the object has two or more input connections to Mosaic, the MONITOR will show as active only the first), see the example in figure;
- Inputs Diagnostics;
- OSSD State;
- OSSD Diagnostics;
- Status of Signaling OUTPUTS;
- OUT TEST diagnostics.

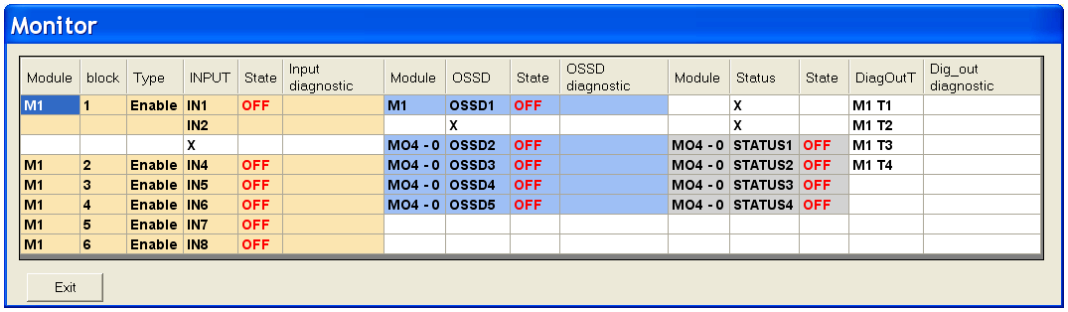


Figure 49 - textual monitor

MONITOR (I/O status in real time - textual - graphic)

To activate/deactivate the monitor use the icon  . (Password Required: level 1).
The color of links (Figure 33) allows you to view the diagnostics **(in real time)** with:
RED = OFF
GREEN = ON
DASHED ORANGE = Connection Error
DASHED RED = Pending enable (for example RESTART)
Placing the mouse pointer over the link, you can display the diagnostics.

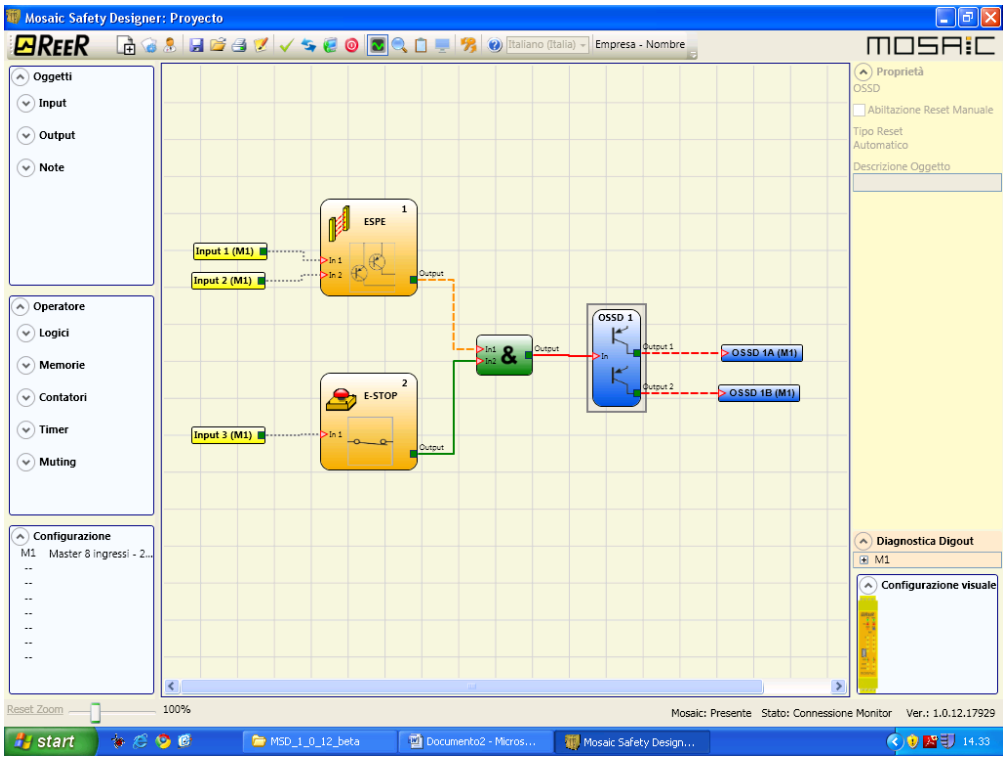


Figure 50 - graphic monitor

english

Password protection

The MSD requests a password in order to upload and save the project.

➔ The password entered as default must be modified to avoid manipulation (level 2 password) or so that the configuration loaded on Mosaic (level 1 password) is not visible.

Level 1 password

All operators using the M1 system must have a Level 1 PASSWORD.
This password allows only to view the LOG file, composition of the system and MONITOR in real time and upload operations.
The first time the system is initialised the operator must use the password "" (ENTER key).

Designers who know the level 2 password can enter a new level 1 password (alphanumerical, max 8 characters).

➔ Operators who know this password **are enabled** to upload (from M1 to PC), modify or save the project.

Level 2 password

Designers authorised to work on the creation of the project must know a Level 2 PASSWORD. The first time the system is initialised the operator must use the password **"SAFEPASS"** (all capital letters)**.**

Designers who know the level 2 password can enter a new level 2 password (alphanumerical, max 8 characters).

➔ This password **enables** the project to be uploaded (from PC to M1), modified and saved. In other words, it allows total control of the PC => MOSAIC system.

➔ When a new project is UPLOADED the level 2 password could be changed.

➔ Should you forget either of these passwords, please contact ReeR which will provide an unlock file (when the unlock file is saved in the right directory the icon will appear on the toolbar). When the icon is activated, the password level 1 and level 2 are restored to their original values. This password is only given to the designer and can only be used once.

Password Change

To activate the PASSWORD Change use icon , after connecting with Level 2 Password.
A window appears (Figure 51) allowing the choice of the new password; insert the old and new passwords in the appropriate fields (max 8 characters). Click OK.
At the end of the operation disconnect to restart the system.
If MCM is present the new password is also saved in it.

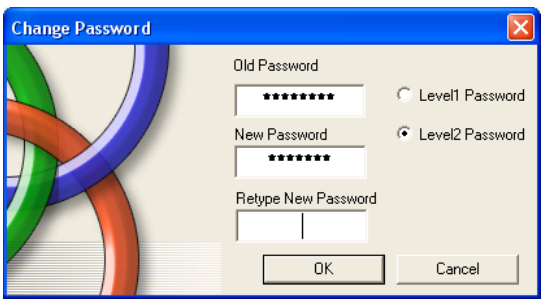


Figure 51

English

TESTING the system

After validating and uploading the project to the M1 and connecting all the safety devices, you must test the system to verify its correct operation.

This is done by forcing a change of status for each safety device connected to the MOSAIC to check that the status of the outputs actually changes.
The following example is helpful for understanding the TEST procedure.

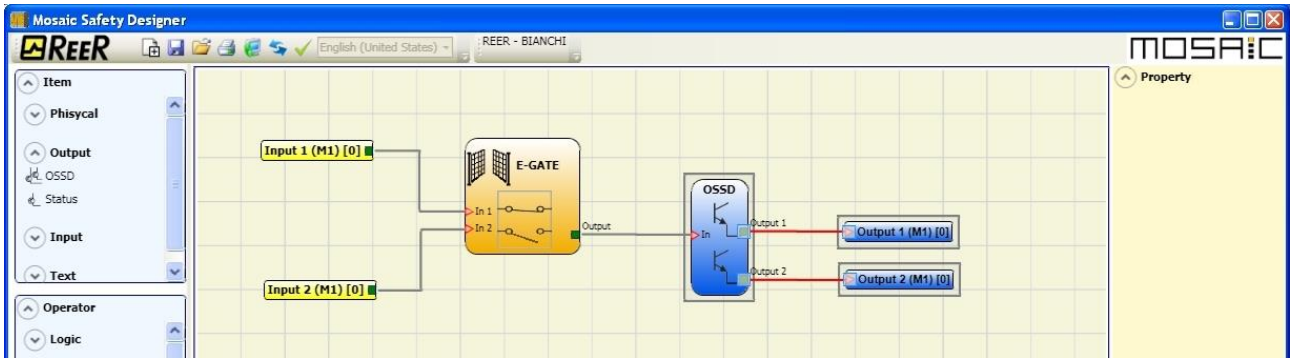
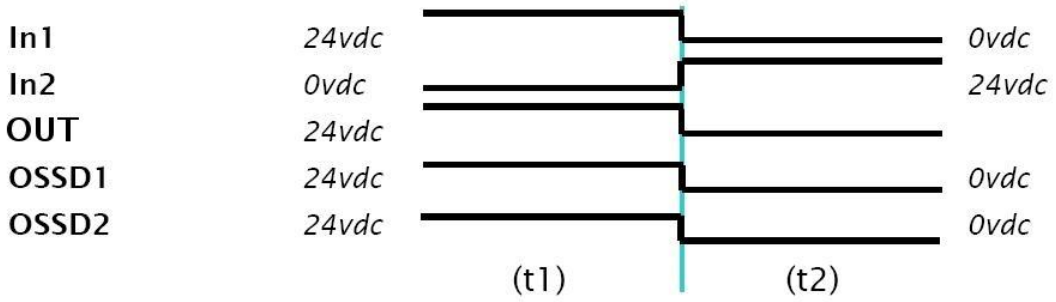


Figure 52

(t1) In the normal operating condition (E-GATE closed) Input1 is closed, Input2 is open and the output of the E-GATE block is set to high logic level; in this mode the safety outputs (OSSD1/2) are active and the power supply to the relative terminals is 24VDC.

(t2) When the E-GATE is **physically** opened, the condition of the inputs and thus of the outputs of the E-GATE block will change: (OUT= 0VDC--->24VDC); **the condition of the OSSD1-OSSD2 safety outputs will change from 24VDC to 0VDC.** If this change is detected the mobile E-GATE is connected correctly.



For the correct installation of each external sensor/component refer to their installation manual.
This test must be performed for each safety component in the project.

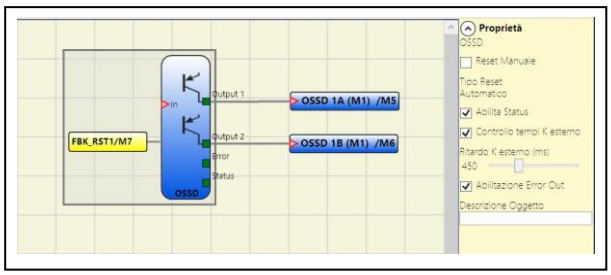
english

OBJECT FUNCTION BLOCKS

OUTPUT OBJECTS

OSSD (safety outputs)

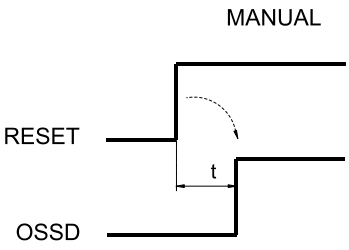
OSSD safety outputs which use semiconductor technology do not require maintenance, Output1 and Output2 supply 24Vdc if the In is 1 (TRUE) and vice versa 0Vdc if the In is 0 (FALSE).



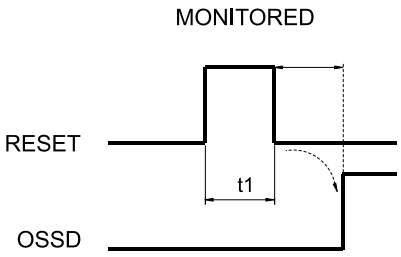
➔ Each pair of OSSD outputs has a relative RESTART_FBK input. This input must always be connected as indicated in the RESTART_FBK paragraph.

Parameters

Manual Reset: If selected this enables the request to reset each time the input signal falls. Otherwise, output enabling directly follows In input conditions.



t = 250ms



5s > t1 > 250ms
t2 = 250ms

There are two types of reset: Manual and Monitored. In selecting the Manual option only signal transition from 0 to 1 is verified. If the Monitored option is selected, the double transition from 0 to 1 and back to 0 is verified.

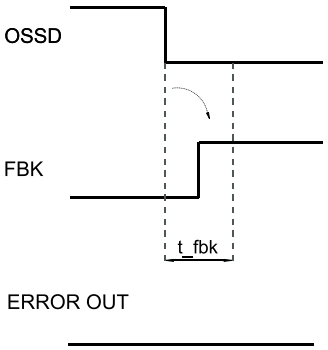
Enable Status: If selected, enables the connection of the current OSSD state to any point on the screen.

K external time check: If selected, enables the setting of the time window within which the external feedback signal is to be monitored (according to output conditions).
With high level (TRUE) OUTPUT, the FBK signal must be at low level (FALSE) and vice versa, within the set time.
Otherwise, OUTPUT is set to low level (FALSE) and the error is indicated on the master M1 by the flashing CLEAR LED corresponding to the OSSD in error.

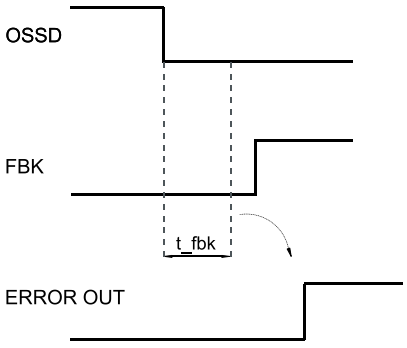
Enable Error Out If selected, enables the ERROR OUT output. This output is set to high level (TRUE) when an external FBK error is detected.

The **Error Out** signal is reset in case of one of the following events:

1. Switching on and switching off of system.
2. Activation of the RESET M1 operator.



Example of OSSD with correct Feedback signal:
In this case ERROR OUT=FALSE

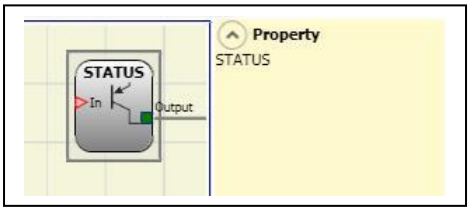


Example of OSSD with incorrect Feedback signal (k external time exceeded):
In this case ERROR OUT=TRUE

English

STATUS (signal output)

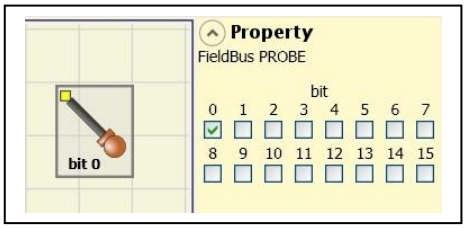
STATUS output (NOT SAFETY OUTPUT) makes it possible to monitor any point on the diagram by connecting it to the input. The output returns 24Vdc if the input is 1 (TRUE), or 0Vdc if the input is 0 (FALSE).



WARNING: The STATUS output is NOT a safety output.

FIELDBUS PROBE

Element that permits display of the status of any point of the scheme on the fieldbus.
Up to 16 probes can be inserted and the bit on which status is represented must be entered for each.
States are represented with 2 bytes on the fieldbus.
(For more detailed information, consult the fieldbus manual on the MSD CD-ROM).



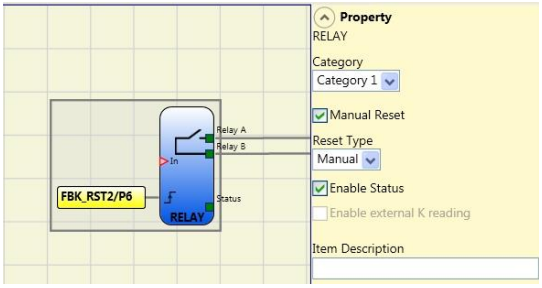
WARNING: the PROBE output is NOT a safety output

RELAY

The Output relay is a N.O. relay output. Relay outputs are closed when the input ***IN*** is equal to 1 (TRUE), otherwise they are open (FALSE).

Parameters

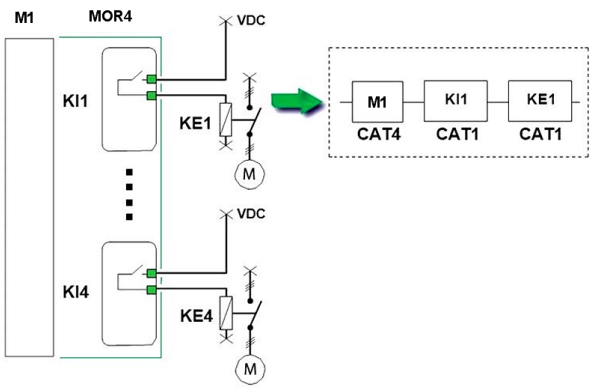
Category There is a choice of 3 different relay output categories:



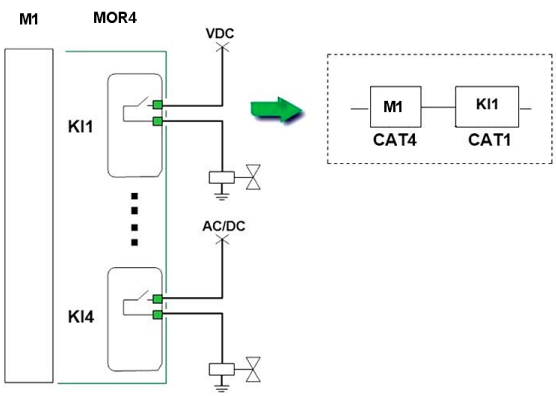
Category 1. Outputs with single Category 1 relay. Each MOR4/S8 unit may have up to 4 of these outputs.

Features:
- Internal relays are monitored.
- EDM feedback (check of FBK 1-4) not used (not requested for Category 1).
- Each output can be set as AUTO or MANUAL RESTART.

Example with external relay

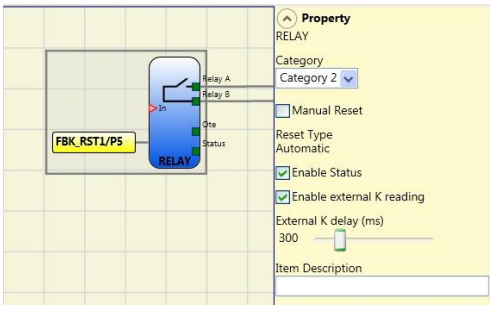


Example with the internal relay only



english

Category 2. Outputs with single Category 2 relay with OTE outputs. Each MOR4/S8 unit can have up to 4 of these outputs.



Features:
- Internal relays are always monitored.
- Monitored EDM feedback.
- The output can be configured to Manual or Automatic restart. The EDM feedback monitor cannot be activated with the manual restart. To monitor the EDM feedback must be confi- gured automatic restart. In this case, if you want to use the manual restart shall be provided a dedicated logic. Refer to the following note.

(Output Test Equipment)

OTE (Output Test Equipment) is activated; this is necessary with configurations of category 2 for the reporting of hazardous failures in accordance with EN 13849-1: 2006 / DAM1 (under development).OTE output: normally ON. In case of fault of internal feedback or EDM => OFF.
This permits to inform the machine logic, with the aim of stopping the dangerous movement or at least signaling the fault to the user.
OTE: The OTE (Output Test Equipment) output is normally 1 (TRUE) exept in the case of an internal error or a fault associated with feedback from the external contactors (FALSE).

Use with RESTART: Automatic (A) or Manual (B) (Category 2)

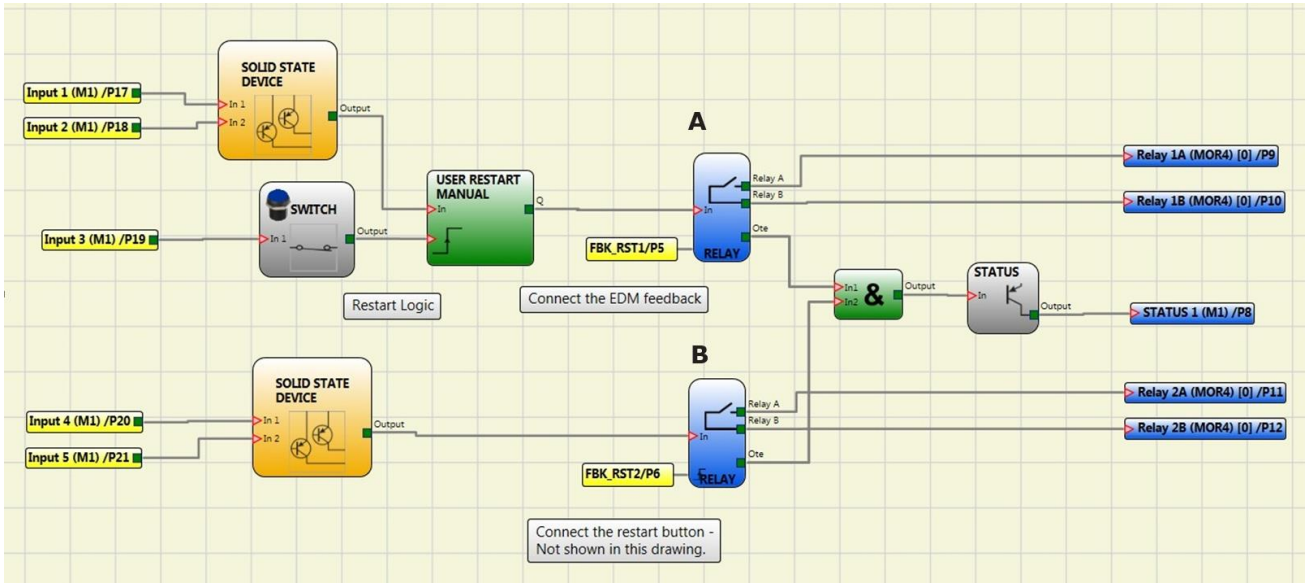
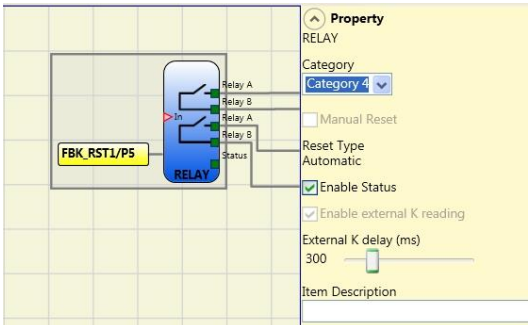


Figure 53

Category 4. Outputs with two Category 4 relays. Each MOR4/S8 unit can have up to 2 of these outputs.
With this output the relays are controlled in pairs.

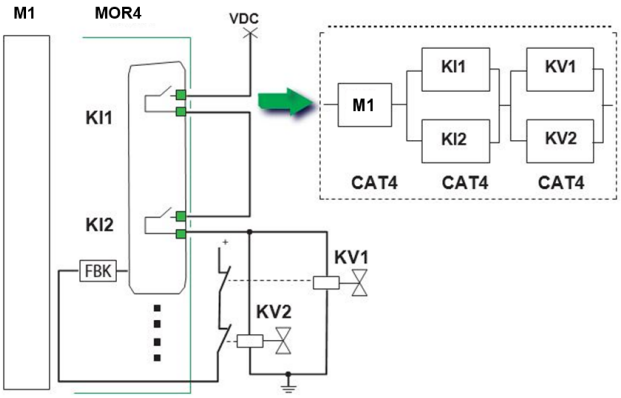


Features:
- 2 double channel outputs.
- Double internal relays are monitored.
- Each output can be set as AUTO or MANUAL RESTART.

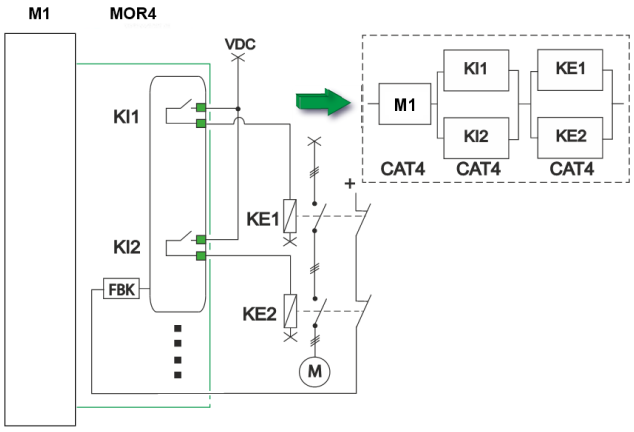
➔ In order to not affect the outcome of the calculation of the PL, the inputs (sensors or safety devices) must be of a category equal to or higher than the other devices in the chain.

English

Example of use with only the internal relay and monitored solenoid valves.



Example of use with external contactors with feedback.



External K delay (ms): Select the Maximum delay the external contactors are allowed to introduce. This value can be used to check the maximum delay between switching of the internal relays and switching of the external contactors (during both activation and deactivation).

Manual Reset: If selected this enables the request to reset each time the IN input signal falls. Otherwise, the output is enabled directly according to the condition of the IN input.

There are two types of reset: Manual and Monitored. When Manual is selected the system only verifies the signal's transition from 0 to 1. If Monitored is selected, the double transition from 0 to 1 and then back to 0 is verified.

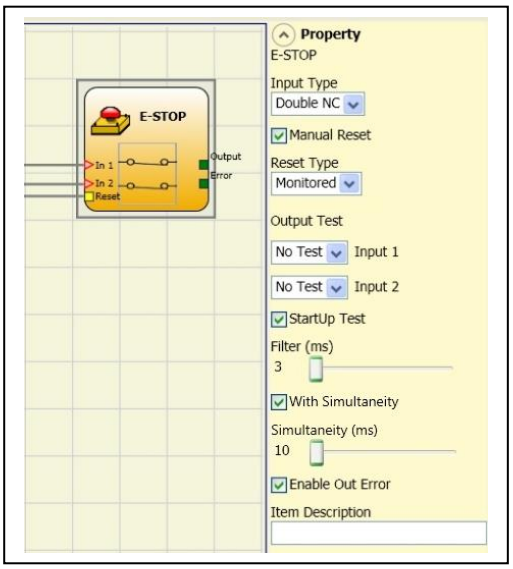
Enable status: If selected this enables the connection of the current status of the relay outputs to a STATUS.

Enable reading of external K: When this is selected it enables reading and verification of external contactor switching times:

- With Category 1 control of external contactors cannot be enabled.
- With Category 4 control of external contactors is mandatory (always enabled).

INPUT OBJECTS

E-STOP (emergency stop)

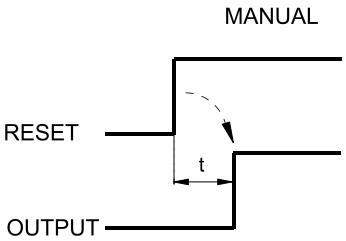


E-STOP function block verifies an emergency stop device inputs status. If the emergency stop button has been pressed the output is 0 (FALSE). If not the output is 1 (TRUE).

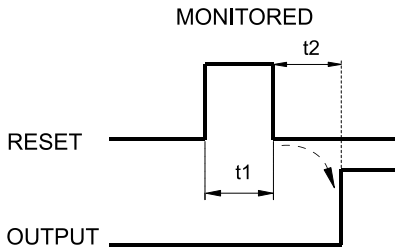
Parameters

Input type:
- Single NC – allows connection of one-way emergency stops
- Double NC – allows connection of two-way emergency stops .

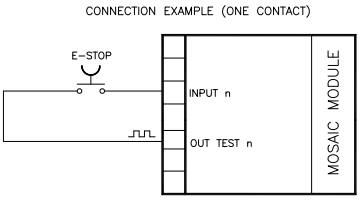
Manual reset: If selected this enables the request to reset each time the emergency stop is activated. Otherwise, enabling of the output directly follows the input conditions.
There are two types of reset: Manual and Monitored. When Manual is selected the system only verifies the signal's transition from 0 to 1. If Monitored is selected the double transition from 0 to 1 and then back to 0 is verified.

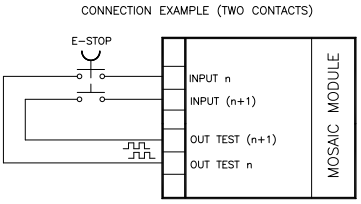


t = 250ms



t1 > 250ms
t2 = 250ms





➔ WARNING: If the Manual Reset is active, a consecutive Input have to be used. Example : Input 1 and Input 2 are used for the fuctional block, then Input 3 have to be used for the Reset Input.

Output test: This is used to select which test output signals are to be sent to the emergency stop (mushroom pushbutton). This additional test makes it possible to detect and manage any short-circuits between the lines. This additional control permits detection and management of any short-circuits between the lines. To enable this control, the test output signals must be configured (amongst those available).
Test at start-up: If selected this enables the test at start-up of the external component (emergency stop). This test is performed by pressing and releasing the pushbutton to run a complete function test and enable the output. This test is only requested at machine start-up (when the unit is switched on).

English

Filter (ms): This is used to filter the signals coming from the emergency stop. The filter can be configured to between 3 and 250 ms and eliminates any bouncing on the contacts. The length of the filter affects the calculation of the unit's total response time.

With Simultaneity: If selected this activates the test to verify concurrent switching of the signals coming from the emergency stop.

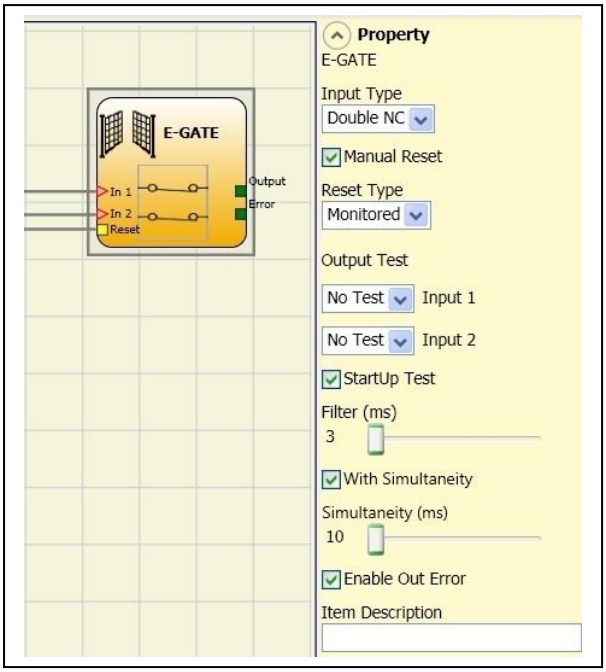
Simultaneity (ms): This is only active if the previous parameter is enabled. It defines the maximum time (in msecs) between the switching of two different signals from the emergency stop.

Enable Error Out: If selected reports a fault detected by the function block.

Item description: This allows a description of the component's function to be entered. The text is displayed in the top part of the symbol.

E-GATE (safety gate device)

E-GATE function block verifies a mobile guard or safety gate device input status. If the mobile guard or safety gate is open, the output is 0 (FALSE). Otherwise the output is 1 (TRUE).

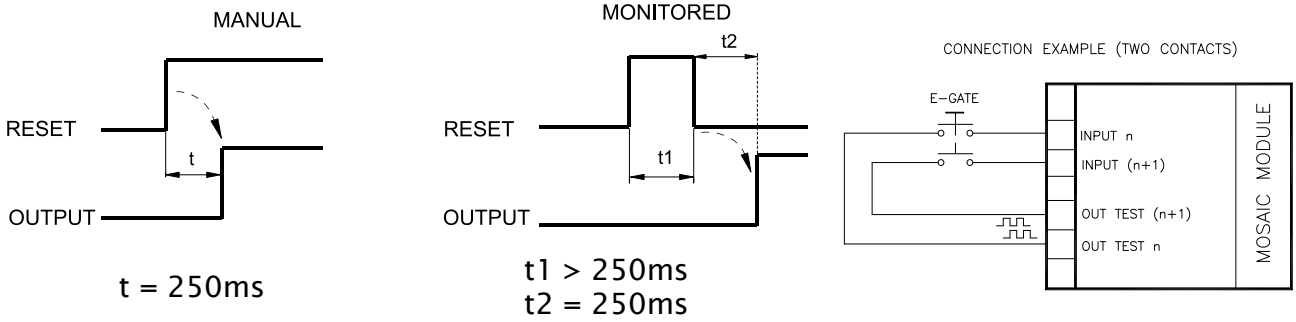


Parameters

Input type:
- Double NC – Allows connection of components with two NC contacts
- Double NC/NO – Allows connection of components with one NO contact and one NC.

➔ With inactive input (block with Output FALSE), connect:
- Contact NO to terminal corresponding to IN1.
- Contact NC to terminal corresponding to IN2.

Enable reset: If selected this enables the request to reset each time the mobile guard/safety gate is activated. Otherwise, enabling of the output directly follows the input conditions.
There are two types of reset: Manual and Monitored. When Manual is selected the system only verifies the signal's transition from 0 to 1. If Monitored is selected the double transition from 0 to 1 and then back to 0 is verified.



➔ WARNING: If the Manual Reset is active, a consecutive Input have to be used. Example : Input 1 and Input 2 are used for the fuctional block, then Input 3 have to be used for the Reset Input.

Output test: This is used to select which test output signals are to be sent to the component contacts. This additional control permits detection and management of any short-circuits between the lines. To enable this control, the test output signals must be configured (amongst those available).

Test at start-up: If selected this enables the test at start-up of the external component. This test is performed by opening the mobile guard or safety gate to run a complete function test and enable the output. This test is only requested at machine start-up (when the unit is switched on).

Filter (ms): This is used to filter the signals coming from the external contacts. The filter can be configured to between 3 and 250 ms and eliminates any bouncing on the contacts. The length of the filter affects the calculation of the unit's total response time.

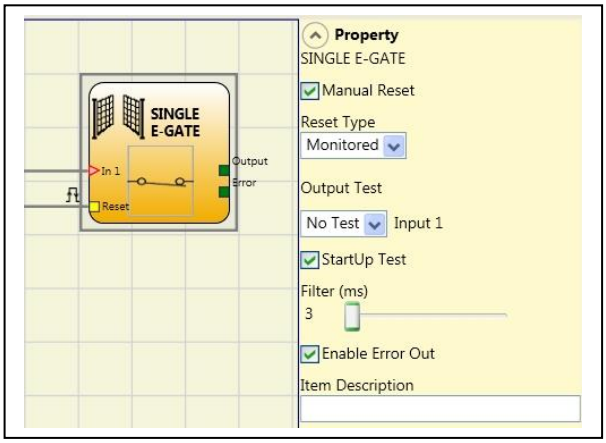
With Simultaneity: If selected this activates the test to verify concurrent switching of the signals coming from the external contacts.

Simultaneity (ms): This is only active if the previous parameter is enabled. It defines the maximum time (in msecs) between the switching of two different signals from the external contacts.

Enable Error Out: If selected reports a fault detected by the function block.

Item description: This allows a description of the component's function to be entered. The text is displayed in the top part of the symbol.

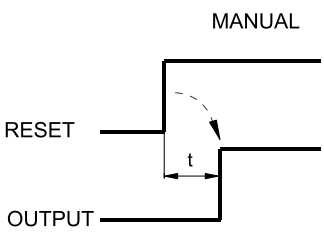
SINGLE E-GATE (safety gate device)



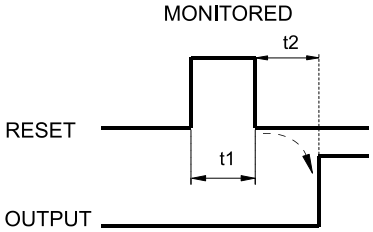
SINGLE E-GATE function block verifies a mobile guard or safety gate device input status. If the mobile guard or safety gate is open, the output is 0 (FALSE). Otherwise the output is 1 (TRUE).

Parameters

Enable reset: If selected this enables the request to reset each time the mobile guard/safety gate is activated. Otherwise, enabling of the output directly follows the input conditions.
There are two types of reset: Manual and Monitored. When Manual is selected the system only verifies the signal's transition from 0 to 1. If Monitored is selected the double transition from 0 to 1 and then back to 0 is verified.



t = 250ms



t1 > 250ms
t2 = 250ms

English

➔ WARNING: If the Manual Reset is active, a consecutive Input have to be used. Example : Input 1 and Input 2 are used for the fuctional block, then Input 3 have to be used for the Reset Input.

Output test: This is used to select which test output signals are to be sent to the component contacts. This additional control permits detection and management of any short-circuits between the lines. To enable this control, the test output signals must be configured (amongst those available).

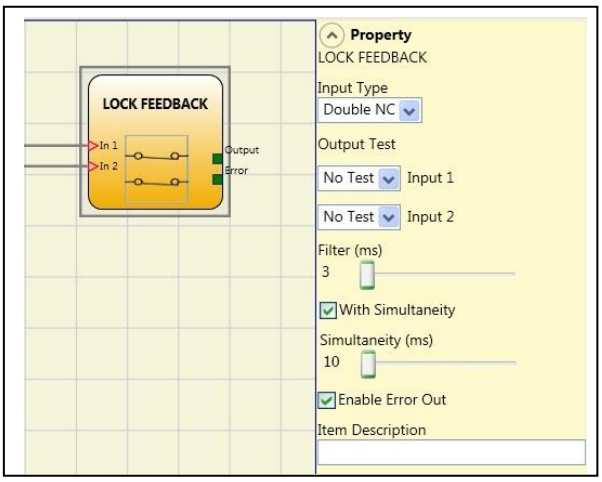
Test at start-up: If selected this enables the test at start-up of the external component. This test is performed by opening the mobile guard or safety gate to run a complete function test and enable the output. This test is only requested at machine start-up (when the unit is switched on).

Filter (ms): This is used to filter the signals coming from the external contacts. The filter can be configured to between 3 and 250 ms and eliminates any bouncing on the contacts. The length of the filter affects the calculation of the unit's total response time.

Enable Error Out: If selected reports a fault detected by the function block.

Item description: This allows a description of the component's function to be entered. The text is displayed in the top part of the symbol.

LOCK FEEDBACK



The function block LOCK FEEDBACK verifies the lock status of the guard lock device for mobile guard or safety gate. In the case where the inputs indicate that the guard is locked the Output will be 1 (TRUE). Otherwise the output is 0 (FALSE).

Parameters

Input type
- Single NC – Allows connection of components with one NC contact;
- Double NC – Allows connection of components with two NC contacts.
- Double NC/NO – Allows connection of components with one NO contact and one NC.

➔ With inactive input (guard unlocked), connect:
- Contact NO to terminal corresponding to IN1
- Contact NC to terminal corresponding to IN2.

Output test: This is used to select which test output signals are to be sent to the component contacts. This additional control permits detection and management of any short-circuits between the lines. To enable this control, the test output signals must be configured (amongst those available).

Filter (ms): This is used to filter the signals coming from the external contacts. The filter can be configured to between 3 and 250 ms and eliminates any bouncing on the contacts. The length of the filter affects the calculation of the unit's total response time.

With Simultaneity: If selected this activates the test to verify concurrent switching of the signals coming from the external contacts.

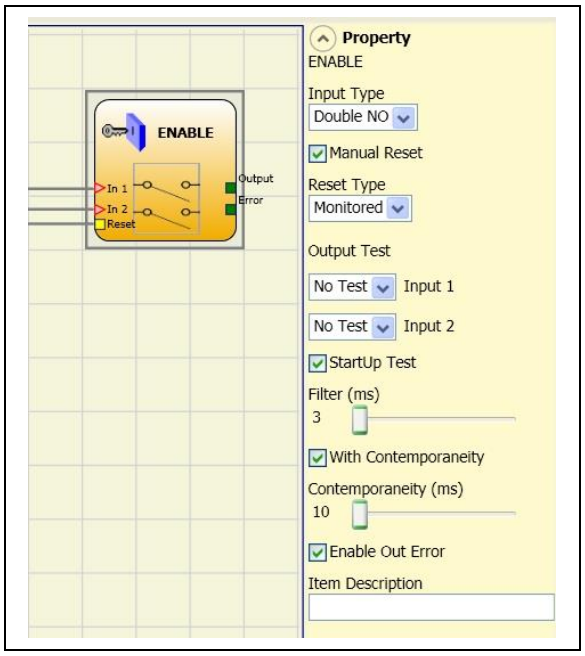
Simultaneity (ms): This is only active if the previous parameter is enabled. It defines the maximum time (in msecs) between the switching of two different signals from the external contacts.

Enable Error Out: If selected reports a fault detected by the function block.

Item description: This allows a description of the component's function to be entered. The text is displayed in the top part of the symbol.

ENABLE (enable key)

ENABLE function block verifies a manual key device Input status. If the key is not turned the output is 0 (FALSE). Otherwise the output is 1 (TRUE).

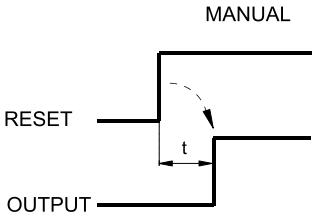


Parameters

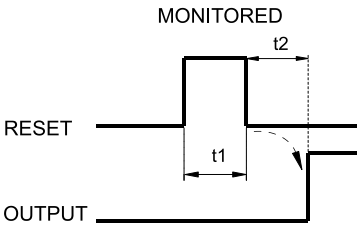
Input type
- Single NO – Allows connection of components with one NO contact;
- Double NO – Allows connection of components with two NO contacts.

Enable reset: If selected this enables the request to reset each time the command is activated. Otherwise, enabling of the output directly follows the input conditions.
There are two types of reset: Manual and Monitored. When Manual is selected the system only verifies the signal's transition from 0 to 1.
If Monitored is selected the double transition from 0 to 1 and then back to 0 is verified.

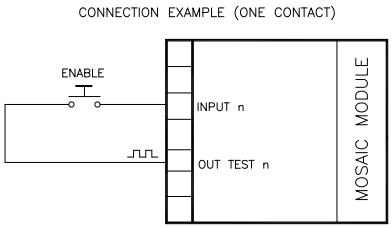
➔ WARNING: If the Manual Reset is active, a consecutive Input have to be used. Example : Input 1 and Input 2 are used for the fuctional block, then Input 3 have to be used for the Reset Input.

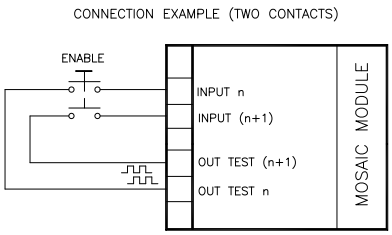


t = 250ms



t1 > 250ms
t2 = 250ms





English

Output test: This is used to select which test output signals are to be sent to the component contacts. This additional control permits detection and management of any short-circuits between the lines. To enable this control, the test output signals must be configured (amongst those available).

Test at start-up: If selected this enables the test at start-up of the external component. This test is performed by opening and activating the enable key to run a complete function test and enable the output. This test is only requested at machine start-up (when the unit is switched on).

Filter (ms): This is used to filter the signals coming from the external contacts. The filter can be configured to between 3 and 250 ms and eliminates any bouncing on the contacts. The length of the filter affects the calculation of the unit's total response time.

With Simultaneity: If selected this activates the test to verify concurrent switching of the signals coming from the external contacts.

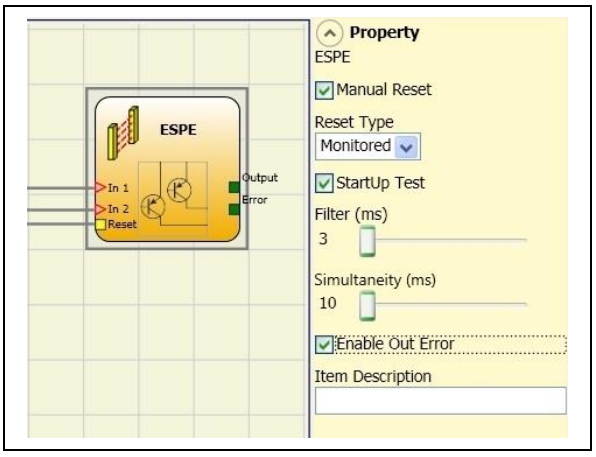
Simultaneity (ms): This is only active if the previous parameter is enabled. It defines the maximum time (in msecs) between the switching of two different signals from the external contacts.

Enable Error Out: If selected reports a fault detected by the function block.

Item description: This allows a description of the component's function to be entered. The text is displayed in the top part of the symbol.

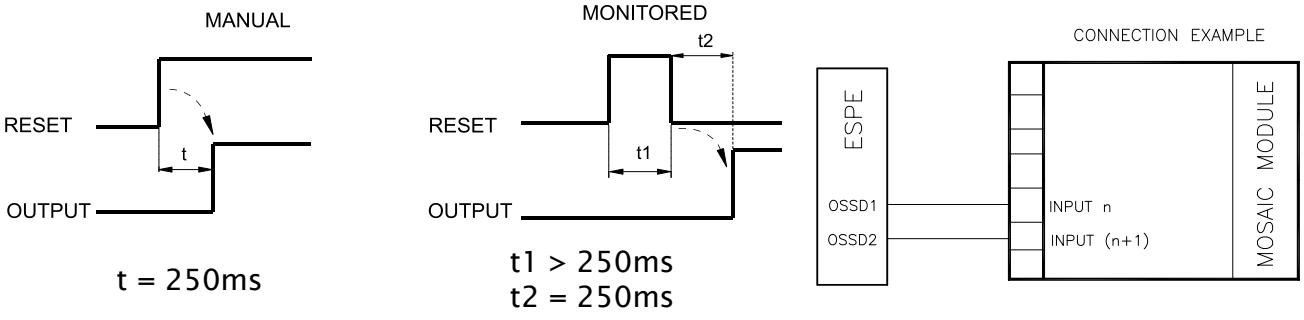
ESPE (optoelectronic safety light curtain / laser scanner)

ESPE function block verifies an optoelectronic safety light curtain (or laser scanner) inputs state. If the area protected by the light curtain is occupied, (light curtain outputs FALSE) the output is 0 (FALSE). Otherwise, with the area clear and outputs to 1 (TRUE) the output is 1 (TRUE).



Parameters

Enable reset: If selected this enables the request to reset each time the area protected by the safety light curtain is occupied. Otherwise, enabling of the output directly follows the input conditions.
There are two types of reset: Manual and Monitored. When Manual is selected the system only verifies the signal's transition from 0 to 1. If Monitored is selected the double transition from 0 to 1 and then back to 0 is verified.



➔ WARNING: If the Manual Reset is active, a consecutive Input have to be used. Example : Input 1 and Input 2 are used for the fuctional block, then Input 3 have to be used for the Reset Input.

OUT TEST signals cannot be used in case of safety static output ESPE because the control is carried out from the ESPE.

Test at start-up: If selected this enables the test at start-up of the safety light curtain. This test is performed by occupying and clearing the area protected by the safety light curtain to run a complete function test and enable the output. This test is only requested at machine start-up (when the unit is switched on).

Filter (ms): This is used to filter the signals coming from the safety light curtain. The filter can be configured to between 3 and 250 ms and eliminates any bouncing on the contacts. The length of the filter affects the calculation of the unit's total response time.

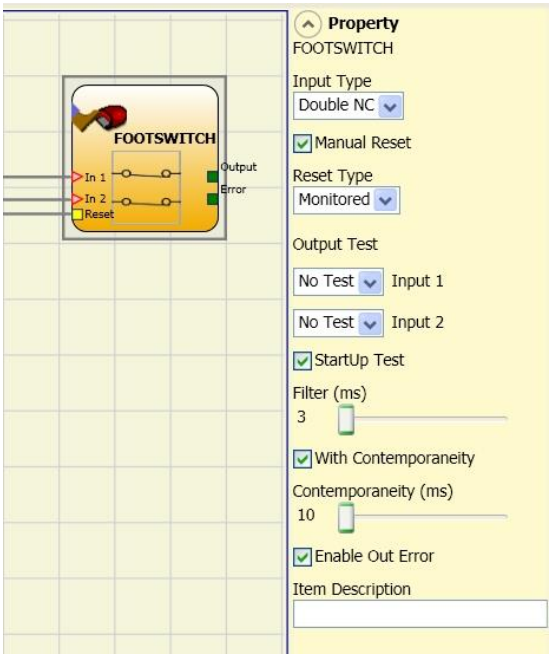
Simultaneity (ms): always active. Determines the maximum permissible time (msec) between switching of the various signals from the external contacts of the device.

Enable Error Out: If selected reports a fault detected by the function block.

Item description: This allows a description of the component's function to be entered. The text is displayed in the top part of the symbol.

FOOTSWITCH (safety pedal)

The FOOTSWITCH function block verifies the status of the inputs of a safety pedal device. If the pedal is not pressed the output is 0 (FALSE). Otherwise the output is 1 (TRUE).



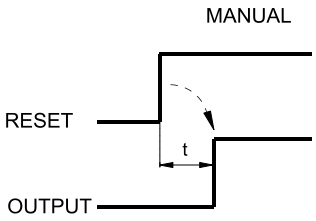
Parameters

Input type:
- Single NC – Allows connection of pedals with one NC contact
- Single NO – Allows connection of pedals with one NO contact.
- Double NC – Allows connection of pedals with two NC contacts
- Double NC/NO – Allows connection of pedals with one NO contact and one NC.

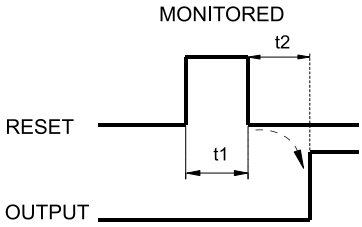
➔ With inactive input (block with Output FALSE), connect:
- Contact NO to terminal corresponding to IN1
- Contact NC to terminal corresponding to IN2.

English

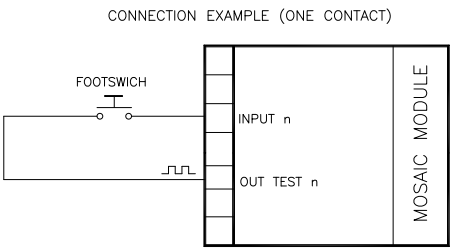
Manual reset: If selected this enables the request to reset each time the safety pedal is activated. Otherwise, enabling of the output directly follows the input conditions.
There are two types of reset: Manual and Monitored. When Manual is selected the system only verifies the signal's transition from 0 to 1. If Monitored is selected the double transition from 0 to 1 and then back to 0 is verified.

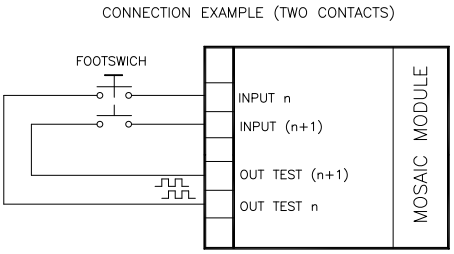


t = 250ms



t1 > 250ms
t2 = 250ms





➔ WARNING: If the Manual Reset is active, a consecutive Input have to be used. Example : Input 1 and Input 2 are used for the fuctional block, then Input 3 have to be used for the Reset Input.

Output test: This is used to select which test output signals are to be sent to the component contacts. This additional control permits detection and management of any short-circuits between the lines. To enable this control, the test output signals must be configured (amongst those available).

Test at start-up: If selected this enables the test at start-up of the external component. This test is performed by pressing and releasing the footswitch to run a complete function test and enable the output. This test is only requested at machine start-up (when the unit is switched on).

Filter (ms): This is used to filter the signals coming from the external contacts. The filter can be configured to between 3 and 250 ms and eliminates any bouncing on the contacts. The length of the filter affects the calculation of the unit's total response time.

With Simultaneity: If selected this activates the test to verify concurrent switching of the signals coming from the external contacts.

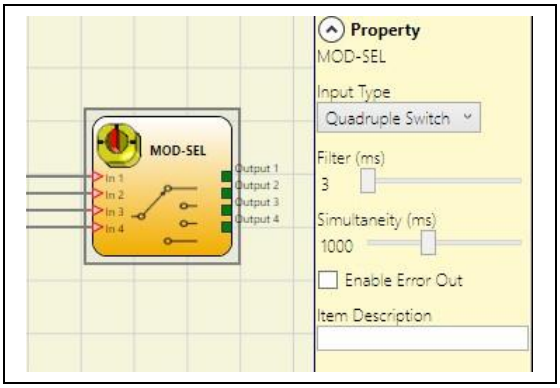
Simultaneity (ms): This is only active if the previous parameter is enabled. It defines the maximum time (in msecs) between the switching of two different signals from the external contacts.

Enable Error Out: If selected reports a fault detected by the function block.

Item description: This allows a description of the component's function to be entered. The text is displayed in the top part of the symbol.

MOD-SEL (safety selector)

The MOD-SEL function block verifies the status of the inputs from a mode selector (up to 4 inputs): If only one input is 1 (TRUE) the corresponding output is also 1 (TRUE). In all other cases, and thus when all inputs are 0 (FALSE) or more than one input is 1 (TRUE) all the outputs are 0 (FALSE).



Parameters

Input type:
- Double selector – Allows connection of two-way mode selectors.
- Triple selector – Allows connection of three-way mode selectors.
- Quadruple selector - Allows connection of four-way mode selectors.

Filter (ms): This is used to filter the signals coming from the mode selector. The filter can be configured to between 3 and 250 ms and eliminates any bouncing on the contacts. The length of the filter affects the calculation of the unit's total response time.

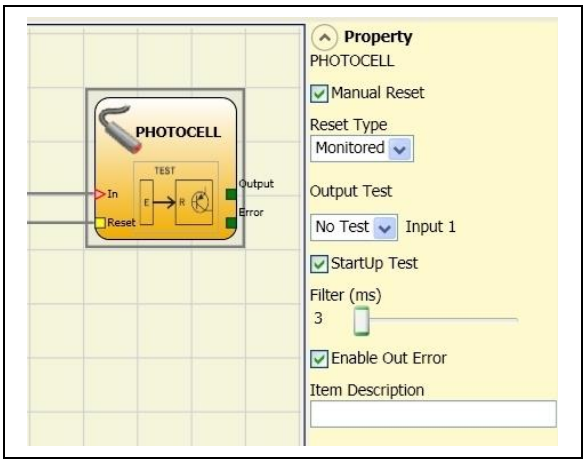
Simultaneity (ms): always active. Determines the maximum permissible time (msec) between switching of the various signals from the external contacts of the device.

Enable Error Out: If selected reports a fault detected by the function block.

Item description: This allows a description of the component's function to be entered. The text is displayed in the top part of the symbol.

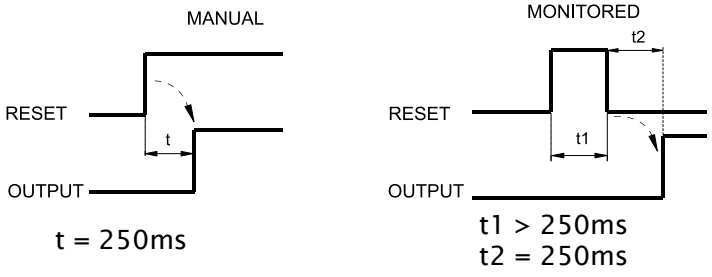
PHOTOCELL (safety photocell)

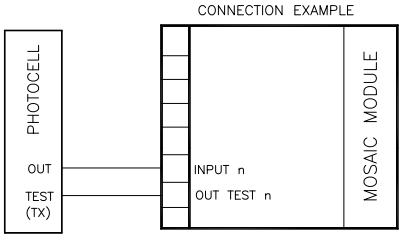
The PHOTOCELL function block verifies the status of the inputs of an optoelectronic safety photocell. If the beam of the photocell is occupied (photocell output FALSE) the output is 0 (FALSE). Otherwise with the beam clear and an output of 1 (TRUE) the output is 1 (TRUE).



Parameters

Manual reset: If selected this enables the request to reset each time safety photocell is activated. Otherwise, enabling of the output directly follows the input conditions.
There are two types of reset: Manual and Monitored. When Manual is selected the system only verifies the signal's transition from 0 to 1. If Monitored is selected the double transition from 0 to 1 and then back to 0 is verified.





➔ An output test signal is mandatory and can be selected from the 4 possible Test Output 1 ÷ 4.

➔ If the Manual Reset is active, a consecutive Input have to be used. Example: Input 1 is used for the functional block, then Input 2 have to be used for the Reset Input.

English

➔ The response time of the photocell must be >2ms and <20ms.

Output test: This is used to select which test output are to be sent to the photocell test input. This additional control permits detection and management of any short-circuits between the lines. To enable this control, the test output signals must be configured (amongst those available).

Test at start-up: If selected this enables the test at start-up of the external component. This test is performed by occupying and clearing the photocell to run a complete function test and enable the output. This test is only requested at machine start-up (when the unit is switched on).

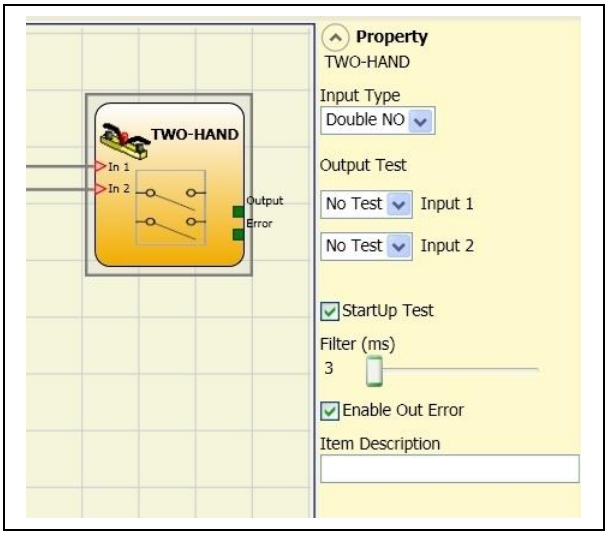
Filter (ms): This is used to filter the signals coming from the external contacts. The filter can be configured to between 3 and 250 ms and eliminates any bouncing on the contacts. The length of the filter affects the calculation of the unit's total response time.

Enable Error Out: If selected reports a fault detected by the function block.

Item description: This allows a description of the component's function to be entered. The text is displayed in the top part of the symbol.

TWO-HAND (bimanual control)

The TWO HAND function block verifies the status of the inputs of a two hand control switch. Only if both the press-buttons are pressed within 500 msec the output is 1 (TRUE). Otherwise the output is 0 (FALSE).



Input type:
- Double NO – Allows connection of two-hand switch with one NO contact for each button (EN 574 III A).
- Quadruple NC-NO - Allows connection of two-hand switch with a double NO/NC contact for each button (EN 574 III C).

➔ With inactive input (block with Output FALSE), connect:
- Contact NO to terminal corresponding to IN1
- Contact NC to terminal corresponding to IN2.

Output test: This is used to select which test output signals are to be sent to the component contacts. This additional control permits detection and management of any short-circuits between the lines. To enable this control, the test output signals must be configured (amongst those available).

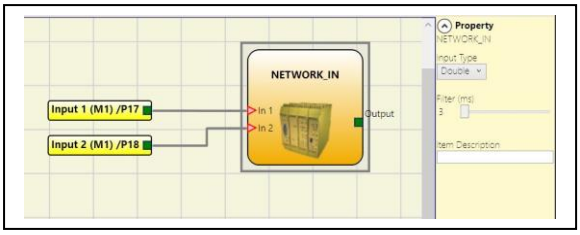
Test at start-up: If selected this enables the test at start-up of the external component. This test is performed by pressing the two buttons (within 500 msec) and releasing them to run a complete function test and enable the output. This test is only requested at machine start-up (when the unit is switched on).

Filter (ms): This is used to filter the signals coming from the mode selector. The filter can be configured to between 3 and 250 ms and eliminates any bouncing on the contacts. The length of the filter affects the calculation of the unit's total response time.

Enable Error Out: If selected reports a fault detected by the function block.

Item description: This allows a description of the component's function to be entered. The text is displayed in the top part of the symbol.

NETWORK_IN



This functional block implements a Network connection input interface; it generates an LL1 in the OUT output when the line is high, otherwise an LL0.

Parameters

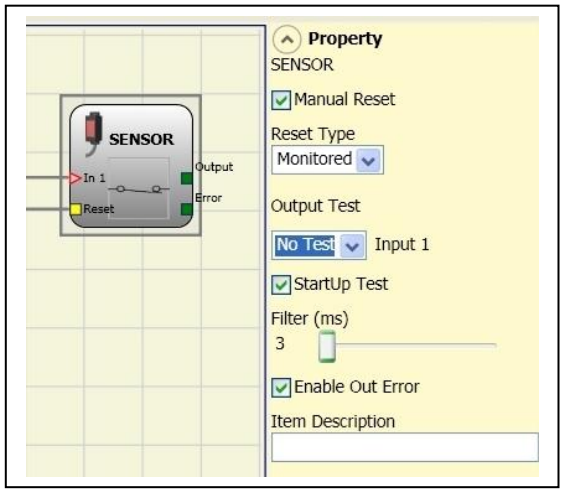
Type of input:
- Single - enables the connection of Signaling outputs of an additional M1 unit.
- Double - enables the connection of OSSD outputs of an additional M1 unit.

Filter (ms): Enables the filtering of signals from an additional M1 unit.
This filter can be set to between 3 and 250 ms. The length of the filter affects the calculation of the unit's total response time.

➔ This input can only be allocated on M1.

➔ This input must be used when Mosaic OSSD outputs are connected to the inputs of a second downstream Mosaic or together with the NETWORK operator.

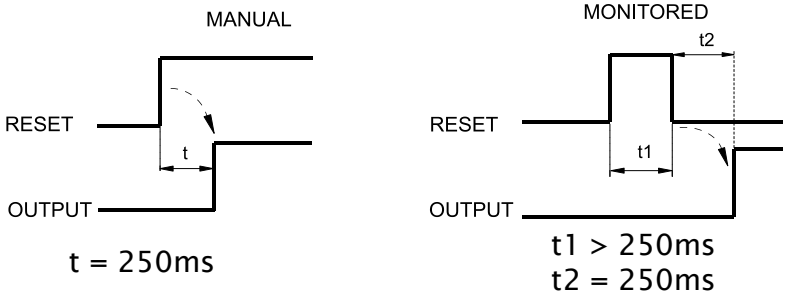
SENSOR



The SENSOR function block verifies the status of the input of a sensor (not a safety sensor). If the beam of the sensor is occupied (sensor output FALSE) the output is 0 (FALSE). Otherwise, with the beam clear and an output of 1 (TRUE) then the output is 1 (TRUE).

Parameters

Manual reset: If selected this enables the request to reset each time the area protected by the sensor is occupied. Otherwise, enabling of the output directly follows the input conditions.
There are two types of reset: Manual and Monitored. When Manual is selected the system only verifies the signal's transition from 0 to 1. If Monitored is selected the double transition from 0 to 1 and then back to 0 is verified.



English

➔ WARNING: If the Manual Reset is active, a consecutive Input have to be used. Example : Input 1 is used for the fuctional block, then Input 2 have to be used for the Reset Input.

Output test: This is used to select which test output signals are to be sent to the sensor. This additional control permits detection and management of any short-circuits between the lines. To enable this control, the test output signals must be configured (amongst those available).

Test at start-up: If selected this enables the test at start-up of the sensor. This test is performed by occupying and clearing the area protected by the sensor to run a complete function test and enable the output. This test is only requested at machine start-up (when the unit is switched on).

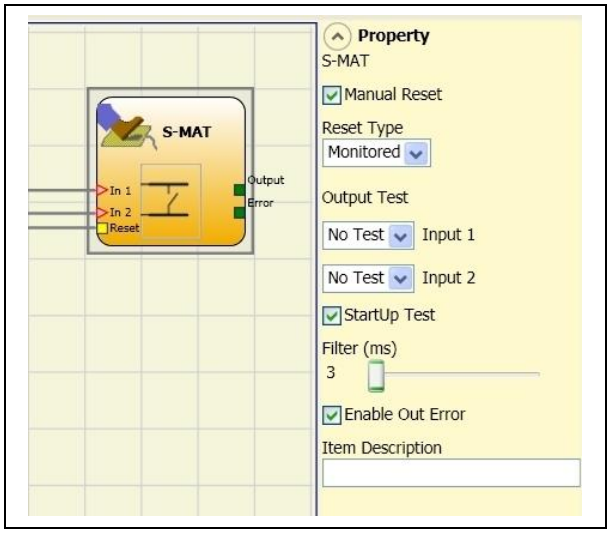
Filter (ms): This is used to filter the signals coming from the sensor. The filter can be configured to between 3 and 250 ms and eliminates any bouncing on the contacts. The length of the filter affects the calculation of the unit's total response time.

Enable Error Out: If selected reports a fault detected by the function block.

Item description: This allows a description of the component's function to be entered. The text is displayed in the top part of the symbol.

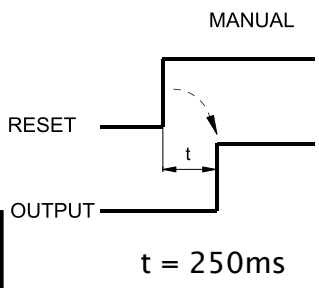
S-MAT (safety mat)

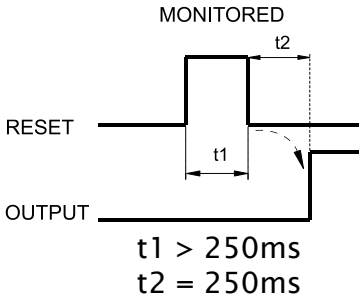
The S-MAT function block verifies the status of the inputs of a safety mat. If a person stands on the mat the output is 0 (FALSE). Otherwise, with the mat clear, the output is 1 (TRUE).

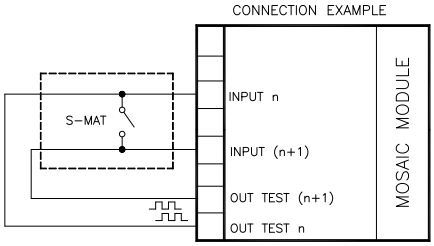


Parameters

Manual reset: If selected this enables the request to reset each time the mobile guard/safety gate is activated. Otherwise, enabling of the output directly follows the input conditions.
There are two types of reset: Manual and Monitored. When Manual is selected the system only verifies the signal's transition from 0 to 1. If Monitored is selected the double transition from 0 to 1 and then back to 0 is verified.







➔ If the Manual Reset is active, a consecutive Input have to be used. Example: Input 1 and Input 2 are used for the fuctional block, then Input 3 have to be used for the Reset Input.

➔ Two output test signals are mandatory. Each output OUT TEST can be connected to only one input S-MAT (it is not allowed parallel connection of 2 inputs).

➔ The function block S-MAT can not be used with 2-wire components and termination resistance.

Output test: This is used to select which test output signals are to be sent to the s-mat contact. This additional control permits detection and management of any short-circuits between the lines. To enable this control, the test output signals must be configured (amongst those available). Test signals are mandatory.

Test at start-up: If selected this enables the test at start-up of the external component. This test is performed by pressing and releasing the safety mat to run a complete function test and enable the output. This test is only requested at machine start-up (when the unit is switched on).

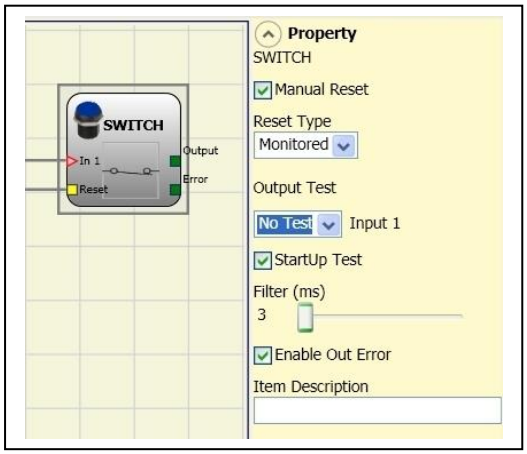
Filter (ms): This is used to filter the signals coming from the external contacts. The filter can be configured to between 3 and 250 ms and eliminates any bouncing on the contacts. The length of the filter affects the calculation of the unit's total response time.

Enable Error Out: If selected reports a fault detected by the function block.

Item description: This allows a description of the component's function to be entered. The text is displayed in the top part of the symbol.

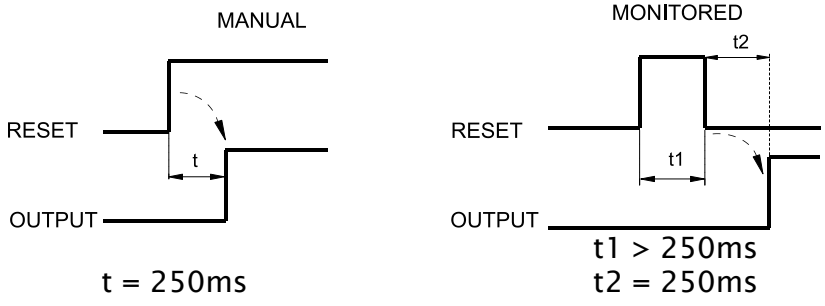
SWITCH

SWITCH function block verifies the input status of a pushbutton or switch (NOT SAFETY SWITCHES). If the pushbutton is pressed the output is 1 (TRUE). Otherwise, the output is 0 (FALSE).



Parameters

Manual reset: If selected this enables the request to reset each time the device is activated. Otherwise, enabling of the output directly follows the input conditions.
There are two types of reset: Manual and Monitored. When Manual is selected the system only verifies the signal's transition from 0 to 1.
If Monitored is selected the double transition from 0 to 1 and then back to 0 is verified.



English

➔ WARNING: If the Manual Reset is active, a consecutive Input have to be used. Example : Input 1 is used for the fuctional block, then Input 2 have to be used for the Reset Input.

Output test: This is used to select which test output signals are to be sent to the switch. This additional control permits detection and management of any short-circuits between the lines. To enable this control, the test output signals must be configured (amongst those available).

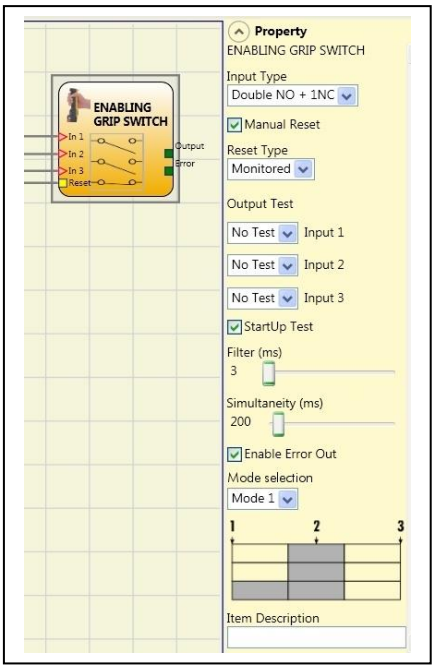
Test at start-up: If selected this enables the test at start-up of the switch. This test is performed by opening and closing the switch contact to run a complete function test and enable the output. This test is only requested at machine start-up (when the unit is switched on).
Filter (ms): This is used to filter the signals coming from the switch. The filter can be configured to between 3 and 250ms and eliminates any bouncing on the contacts. The length of the filter affects the calculation of the unit's total response time.

Enable Error Out: If selected reports a fault detected by the function block.

Item description: This allows a description of the component's function to be entered. The text is displayed in the top part of the symbol.

ENABLING GRIP SWITCH

The ENABLING GRIP functional block checks the status of the In_X inputs of an enabling grip. If this is not gripped (position 1) or is gripped completely (position 3), the OUTPUT will be 0 (FALSE). If it is gripped to middle position (position 2), the OUTPUT will be 1 (TRUE).
Refer to truth tables at the bottom of the page.



➔ The ENABLING GRIP functional block requires that the assigned module has a minimum Firmware version as Table below:

M1	MI8O2	MI8	MI16	MI12
1.0	0.4	0.4	0.4	0.0

Parameters

Type of inputs:
- Double NO – Permits connection of an enabling grip with 2 NO contacts.
- Double NO+1NC – Permits connection of an enabling grip switch with 2 NO contacts + 1 NC contact.

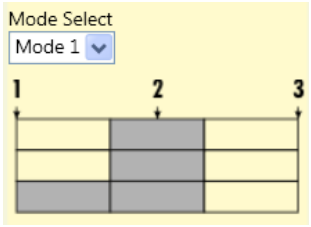
Test outputs: Permits selection of the test output signals to be sent to the enabling grip. This additional control permits detection and management of any short-circuits between the lines. To enable this control, the test output signals must be configured (amongst those available).

Power-on test: If selected, enables the power-on test of the external component (Enabling Grip). To run the test, the device must be gripped and released to carry out a complete functional check and enable the Output terminal. This control is required only at machine start-up (power-on of the module).

Simultaneity (ms): always active. Determines the maximum permissible time (msec) between switching of the various signals from the external contacts of the device.

Filter (ms): Permits filtering of signals from the device control. This filter can be set to between 3 and 250 ms and eliminates any rebounds on the contacts. The duration of the filter affects calculation of module total response time.

Table mode 1 (device 2NO + 1NC)

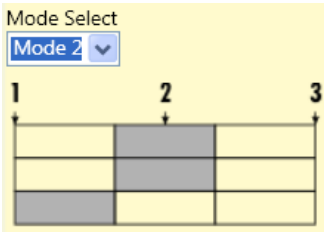


POSITION 1: enabling grip fully released
POSITION 2: enabling grip pressed to middle position
POSITION 3: enabling grip fully pressed

(only with 2NO+1NC)

	Position		
Input	**1**	**2**	**3**
IN1	0	1	0
IN2	0	1	0
IN3	1	1	0
OUT	**0**	**1**	**0**

Table mode 1 (device 2NO + 1NC)



POSITION 1: enabling grip fully released
POSITION 2: enabling grip pressed to middle position
POSITION 3: enabling grip fully pressed

(only with 1NO+1NC)

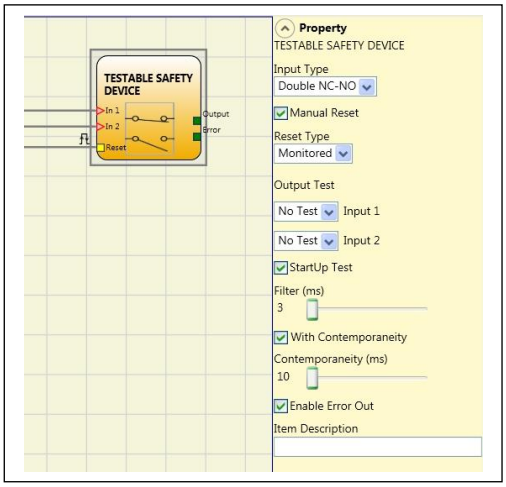
	Position		
Input	**1**	**Input**	**1**
IN1	0	1	0
IN2	0	1	0
IN3	1	0	0
OUT	**0**	**1**	**0**

Enable Error Out: If selected reports a fault detected by the function block.

Item description: Permits insertion of a descriptive text of the function of the component. This text will be displayed in the top part of the symbol.

TESTABLE SAFETY DEVICE

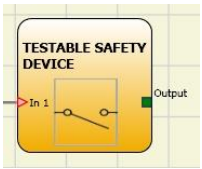
The TESTABLE SAFETY DEVICE functional block checks the status of the Inx inputs of a single or double safety sensor, both NO and NC. Refer to the tables below to check type of sensor and behaviour.



(single NC)

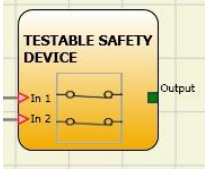
IN1	OUT
0	0
1	1

(single NO)



IN1	OUT
0	0
1	1

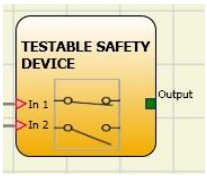
(double NC)



IN1	IN2	OUT	Simultaneity error *
0	0	**0**	–
0	1	**0**	X
1	0	**0**	X
1	1	**1**	–

English

(double NC-NO)

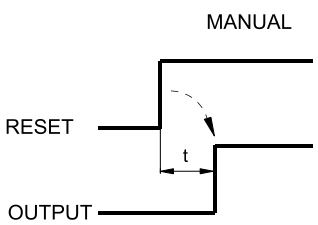


IN1	IN2	OUT	Simultaneity error *
0	0	**0**	X
0	1	**0**	-
1	0	**1**	-
1	1	**0**	X

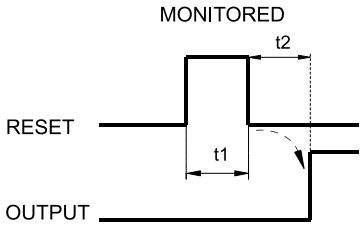
** Simultaneity error = the maximum time between switching of the single contacts has been exceeded.*

Parameters

Manual Reset: If selected, enables the reset request after each activation of the device. Otherwise, enabling of the output follows directly the conditions of the inputs. Reset may be of two types: Manual and Monitored. Selecting the Manual option, only transition of the signal from 0 to 1 is checked. If Monitored is selected, double transition from 0 to 1 and return to 0 is checked.



t = 250ms



t1 > 250ms
t2 = 250ms

➔ WARNING: if Reset is enabled, the input consecutive to those used by the functional block must be used. For example: If inputs 1 and 2 are used for the functional block, input 3 must be used for Reset.

Power-on test: If selected, enables the power-on test of the device. This test requires activation and de-activation of the device in order to run a complete functional check and enable the Output terminal. This test is required only at machine start-up (power-on of the module).

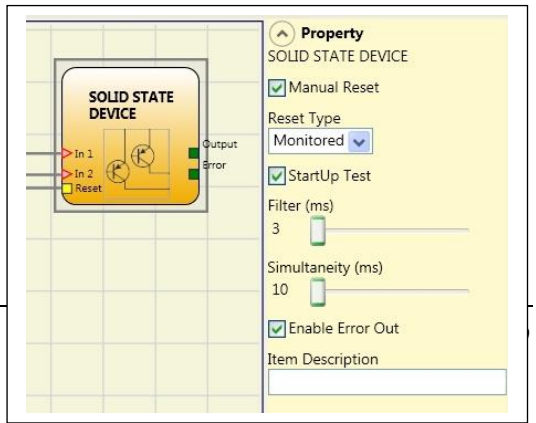
Filter (ms): Permits filtering of signals from the device. This filter can be set to between 3 and 250 ms and eliminates any rebounds on the contacts. The duration of the filter affects calculation of module total response time.

With simultaneity: If selected, activates control of simultaneity between switching of signals from the device.

Simultaneity (ms): Is active only if the previous parameter is enabled. Determines the maximum permissible time (msec) between switching of two different signals from the sensor.

Enable Error Out: If selected reports a fault detected by the function block.

Item description: Permits insertion of a descriptive text of the function of the component. This text will be displayed in the top part of the symbol.



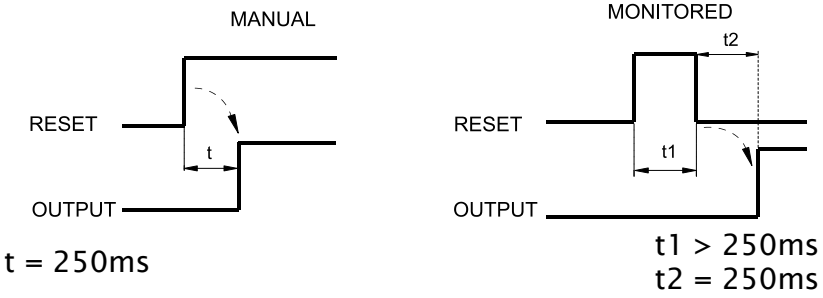
SOLID STATE DEVICE

English

The SOLID STATE DEVICE functional block checks the status of the Inx inputs. If the inputs are at 24VDC, the Output will be 1 (TRUE), otherwise the OUTPUT will be 0 (FALSE).

Parameters

Manual Reset: If selected, enables the reset request after each safety function activaction. Otherwise, enabling of the output follows directly the conditions of the inputs. Reset may be of two types: Manual and Monitored. Selecting the Manual option, only transition of the signal from 0 to 1 is checked. If Monitored is selected, double transition from 0 to 1 and return to 0 is checked.



WARNING: if Reset is enabled, the input consecutive to those used by the functional block must be used. For example: if inputs 1 and 2 are used for the functional block, input 3 must be used for Reset.

Power-on test: If selected, enables the power-on test of the safety device. This test requires activation and de-activation of the device in order to run a complete functional check and enable the Output terminal. This test is required only at machine start-up (power-on of the module)

Filter (ms): Permits filtering of signals from the safety device. This filter can be set to between 3 and 250 ms and eliminates any rebounds on the contacts. The duration of the filter affects calculation of module total response time.

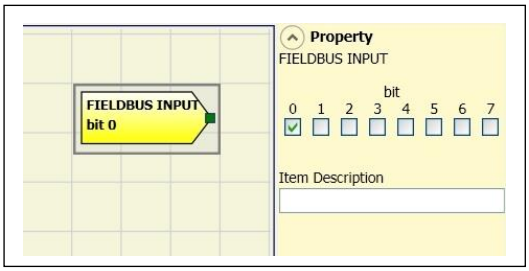
Simultaneity (ms): always active. Determines the maximum permissible time (msec) between switching of the various signals from the external contacts of the device.

Enable Error Out: If selected reports a fault detected by the function block.

Item description: Permits insertion of a descriptive text of the function of the component. This text will be displayed in the top part of the symbol.

FIELDBUS INPUT

Element that permits insertion of a non-safety input whose status is modified via the fieldbus.
Up to 8 virtual inputs can be inserted and the bit on which status is to be modified must be selected for each.
They are represented with one byte on the fieldbus.
(For more detailed information, consult the fieldbus manual on the MSD CD-ROM).



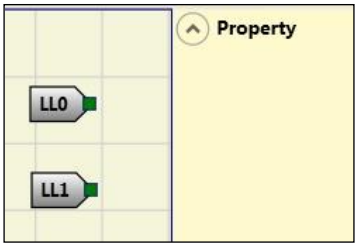
WARNING: the FIELDBUS INPUT is NOT a safety input.

English

LL0-LL1

These allow a predefined logical level to be entered on a component's input.

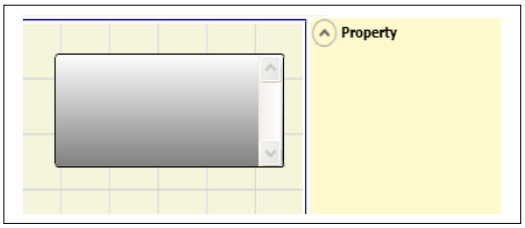
LL0 -> logical level 0
LL1 -> logical level 1



IMPORTANT: LL0 and LL1 cannot be used to disable the logical ports in the diagram.

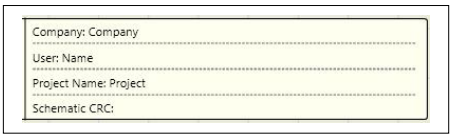
COMMENTS

This allows a description to be entered and placed in any point of the diagram.



TITLE

Automatically adds the name of the manufacturer, the designer, the project name and the CRC.



English

SPEED CONTROL TYPE FUNCTION BLOCKS

Warning concerning safety

- An external error or malfunction deriving from encoder/proximity or its wiring, does not necessarily involve a change of safety status of the normal output **(i.e. "Zero")** of the function block. Failures or malfunctions of encoder/proximity switch or its wiring are then recognized by the module, managed and specified via the diagnostic bit on every function block **("Enable Error Out").**
- To ensure the safety features the diagnostic bit has to be used in the configuration program created by the user to cause a possible deactivation of the outputs if the axis is working. In absence of encoder/proximity external anomalies, **Error** bit will be equal to 0 (zero).
- In presence of encoder/proximity external anomalies, error_out bit will be equal to 1 (one):
  - Absence of encoder or proximity.
  - Absence of one or more wiring from encoder/proximity.
  - Absence of encoder power supply (only model with TTL external power supply).
  - Error of congruence frequencies between signals from encoder/proximity.
  - Phase error between signals from the encoder or duty cycle error of a single phase.

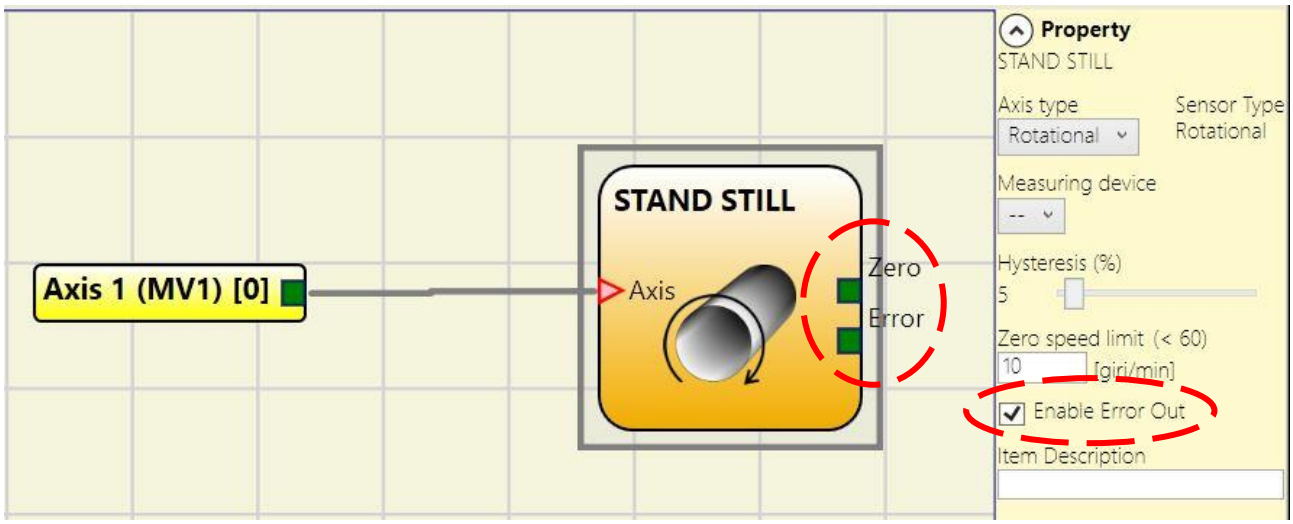
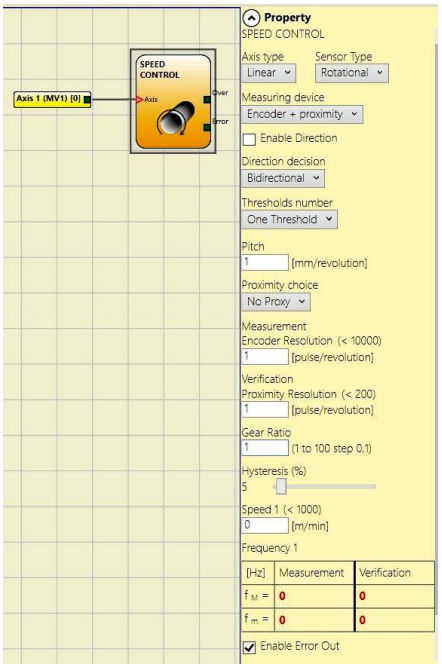


Figure 54 – Example of speed control functional block with Error Out enabled

English

SPEED CONTROL

The **Speed Control** function block monitors the speed of a device generating an output 0 (FALSE) when the measured speed exceeds a predetermined threshold. In the case in which the speed is below the predetermined threshold the output will be 1 (TRUE).



Parameters

Axis type: It defines the type of axis controlled by the device. It will be Linear in the case of a translation and will be Rotary in the case of motion around an axis.

Sensor Type: In the event that the previous parameter is Linear, the Sensor Type defines the type of sensor connected to the module inputs. It can be Rotary (e.g. shaft encoder) or Linear (e.g. optical array). This choice allows to define the following parameters.

Measuring device: It defines the type of sensor(s) used. The possible choices are:

- Encoder
- Proximity
- Encoder+Proximity
- Proximity1+ Proximity2
- Encoder1+ Encoder2

Enable direction: Enabling this parameter, the DIR output is enabled on the function block. This output will be 1 (TRUE) when the axis rotates Counterclockwise and will be 0 (FALSE) when the axis rotates Clockwise

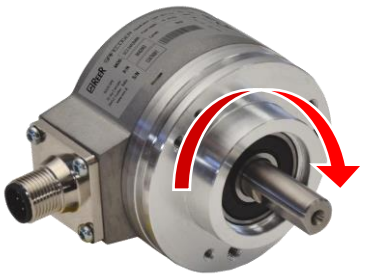
Direction decision: It defines the direction of rotation for which the set thresholds are made active. The possible choices are:

- Bidirectional
- Clockwise
- Counterclockwise

If Bidirectional is selected, the excess of the set threshold is detected whether the axis rotates clockwise or counterclockwise. Selecting Clockwise or Counterclockwise, this is detected only when the axis rotates in the selected direction.

Threshold number: It allows you to enter the number of thresholds for the maximum value of speed. Changing this value will increase/decrease the number of thresholds that can be entered from a minimum of 1 to a maximum of 4. In the case of thresholds greater than 1, the input pins for the selection of the specific threshold will appear in the lower part of the function block.

Pitch: If the Axis Type chosen was linear, this field allows you to enter the sensor pitch to obtain a conversion between sensor revolutions and distance travelled.



Example of CLOCKWISE axis rotation

2 threshold settings

In1	Threshold no.
0	Speed 1
1	Speed 2

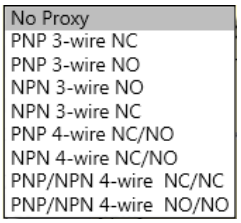
4 threshold settings

In2	In1	Threshold no.
0	0	Speed 1
0	1	Speed 2
1	0	Speed 3
1	1	Speed 4

English

Proximity choice: It allows you to choose the type of proximity sensor from PNP, NPN, Normally Open (NA) and Normally Closed (NC), with 3 or 4 wires.

(In order to ensure a Performance Level = PLe use a proximity switch type PNP NO: ref. "Interleaved proximity -> page 27).

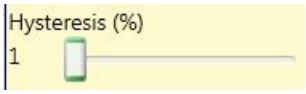


Measurement: Enter in this field the number of pulses/revolution (in the case of rotary sensor) or µm/pulse (linear sensor) relating to the sensor used

Verification: Enter in this field the number of pulses/revolution (in the case of rotary sensor) or µm/pulse (linear sensor) relating to the second sensor used.

Gear Ratio: This parameter is active if there are two sensors on the selected axis. This parameter allows you to enter the ratio between the two sensors. If both sensors are on the same moving parts, the ratio will be 1 otherwise the number corresponding to the report must be entered. E.g. there are an encoder and a proximity switch, and the latter is on a moving part that (due to a gear reduction ratio) rotates at twice the speed of the encoder. Therefore, this value must be set at 2.

Hysteresis (%): It represents the percentage hysteresis value below which the speed change is filtered. Enter a value other than 1 to avoid continuous switching as the input changes.



Speed 1, 2, 3, 4: Enter in this field the maximum speed value above which the function block output (OVER) will be 0 (FALSE). If the measured speed is less than the set value, the function block output (OVER) will be 1 (TRUE).

Frequency: It shows the maximum calculated frequency values fM and fm (decreased by the hysteresis set). If the displayed value is GREEN, the calculation of frequency gave a positive result.
If the displayed value is RED, it is necessary to change the parameters given in the following formulas.

1. Rotary axis, rotary sensor. The frequency obtained is:

$$f[\mathrm{Hz}] = \frac{\mathrm{rpm}[\mathrm{rev/min}]}{60} * \mathrm{Resolution}[\mathrm{pulses/rev}]$$

2. Linear axis, rotary sensor. The frequency obtained is:

$$f[\mathrm{Hz}] = \frac{speed[\mathrm{m/min}] * 1000}{60 * pitch[\mathrm{mm/rev}]} * \mathrm{Re}\,solution[\mathrm{pulses/rev}]$$

3. Linear axis, linear sensor. The frequency obtained is:

$$f[\mathrm{Hz}] = \frac{\mathrm{speed}[\mathrm{mm/s}] * 1000}{\mathrm{Resolution}[\mu\mathrm{m/pulse}]}$$

4. Hysteresis. To be changed only if: fM=green; fm=red

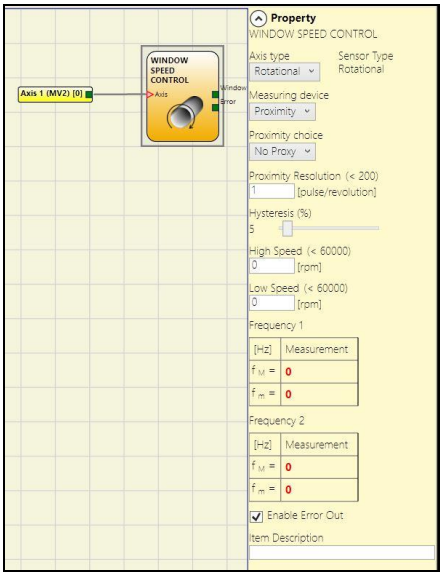
KEY:

f = frequency
Rpm = rotational speed
Resolution = measurement
Speed = linear speed
Pitch = sensor pitch

English

WINDOW SPEED CONTROL

The **Window Speed Control** function block monitors the speed of a device, generating the Zero to 1 (TRUE) output when the speed is within a prefixed range.



Parameters

Axis type: It defines the type of axis controlled by the device. It will be Linear in the case of a translation and will be Rotary in the case of motion around an axis.

Sensor Type: In the event that the previous parameter is Linear, the Sensor Type defines the type of sensor connected to the module inputs. It can be Rotary (e.g. shaft encoder) or Linear (e.g. optical array). This choice allows to define the following parameters.

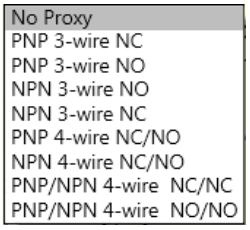
Measuring device: It defines the type of sensor(s) used. The possible choices are:

- Encoder
- Proximity
- Encoder+Proximity
- Proximity1+ Proximity2
- Encoder1+ Encoder2

Pitch: If the Axis Type chosen was linear, this field allows you to enter the sensor pitch to obtain a conversion between sensor revolutions and distance travelled.

Proximity choice: It allows you to choose the type of proximity sensor from PNP, NPN, Normally Open (NA) and Normally Closed (NC), with 3 or 4 wires.

(In order to ensure a Performance Level = PLe use a proximity switch type PNP NO: ref. "Interleaved proximity -> page 27).



Proximity choice

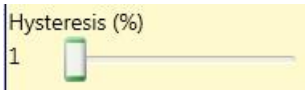
Measurement: Enter in this field the number of pulses/revolution (in the case of rotary sensor) or µm/pulse (linear sensor) relating to the sensor used.

Verification: Enter in this field the number of pulses/revolution (in the case of rotary sensor) or µm/pulse (linear sensor) relating to the second sensor used.

English

Gear Ratio: This parameter is active if there are two sensors on the selected axis. This parameter allows you to enter the ratio between the two sensors. If both sensors are on the same moving parts, the ratio will be 1 otherwise the number corresponding to the report must be entered. E.g. there are an encoder and a proximity switch, and the latter is on a moving part that (due to a gear reduction ratio) rotates at twice the speed of the encoder. Therefore, this value must be set at 2.

Hysteresis (%): It represents the percentage hysteresis value below which the speed change is filtered. Enter a value other than 1 to avoid continuous switching as the input changes.



High speed:
Enter in this field the maximum speed value above which the output of the function block (WINDOW) will be 0 (FALSE). If the measured speed is less than the set value, the output (WINDOW) of the function block will be 1 (TRUE).

Low speed:
Enter in this field the minimum speed value below which the output of the function block (WINDOW) will be 0 (FALSE). If the measured speed is more than the set value, the output (WINDOW) of the function block will be 1 (TRUE).

Frequency: It shows the maximum calculated frequency values fM and fm (decreased by the hysteresis set). If the displayed value is GREEN, the calculation of frequency gave a positive result.
If the displayed value is RED, it is necessary to change the parameters given in the following formulas.

1. Rotary axis, rotary sensor. The frequency obtained is:

$$f[\mathrm{Hz}] = \frac{\mathrm{rpm}[\mathrm{rev/min}]}{60} * \mathrm{Resolution}[\mathrm{pulses/rev}]$$

2. Linear axis, rotary sensor. The frequency obtained is:

$$f[\mathrm{Hz}] = \frac{speed[\mathrm{m/min}] * 1000}{60 * pitch[\mathrm{mm/rev}]} * \mathrm{Re}\,solution[\mathrm{pulses/rev}]$$

3. Linear axis, linear sensor. The frequency obtained is:

$$f[\mathrm{Hz}] = \frac{\mathrm{speed}[\mathrm{mm/s}] * 1000}{\mathrm{Resolution}[\mu\mathrm{m/pulse}]}$$

4. Hysteresis. To be changed only if: fM=green; fm=red

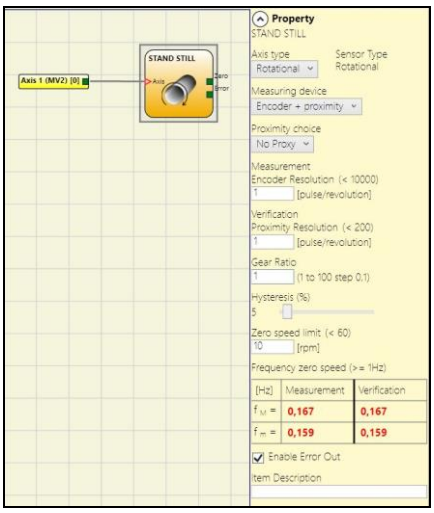
KEY:

f = frequency
Rpm = rotational speed
Resolution = measurement
Speed = linear speed
Pitch = sensor pitch

English

STAND STILL

The **StandStill** function block monitors the speed of a device, generating the Zero to 1 (TRUE) output when the speed is lower than a selected value.



Parameters

Axis type: It defines the type of axis controlled by the device. It will be Linear in the case of a translation and will be Rotary in the case of motion around an axis.

Sensor Type: In the event that the previous parameter is Linear, the Sensor Type defines the type of sensor connected to the module inputs. It can be Rotary (e.g. shaft encoder) or Linear (e.g. optical array). This choice allows to define the following parameters.

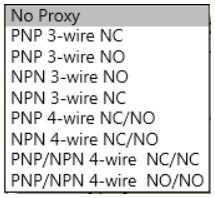
Measuring device: It defines the type of sensor(s) used. The possible choices are:

- Encoder
- Proximity
- Encoder+Proximity
- Proximity1+ Proximity2
- Encoder1+ Encoder2

Pitch: If the Axis Type chosen was linear, this field allows you to enter the sensor pitch to obtain a conversion between sensor revolutions and distance travelled.

Proximity choice: It allows you to choose the type of proximity sensor from PNP, NPN, Normally Open (NA) and Normally Closed (NC), with 3 or 4 wires.

(In order to ensure a Performance Level = PLe use a proximity switch type PNP NO: ref. "Interleaved proximity -> page 25).



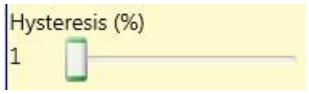
Proximity choice

Measurement: Enter in this field the number of pulses/revolution (in the case of rotary sensor) or µm/pulse (linear sensor) relating to the sensor used

Verification: Enter in this field the number of pulses/revolution (in the case of rotary sensor) or µm/pulse (linear sensor) relating to the second sensor used.

Gear Ratio: This parameter is active if there are two sensors on the selected axis. This parameter allows you to enter the ratio between the two sensors. If both sensors are on the same moving parts, the ratio will be 1 otherwise the number corresponding to the report must be entered. E.g. there are an encoder and a proximity switch, and the latter is on a moving part that (due to a gear reduction ratio) rotates at twice the speed of the encoder. Therefore, this value must be set at 2.

Hysteresis (%): It represents the percentage hysteresis value below which the speed change is filtered. Enter a value other than 1 to avoid continuous switching as the input changes.



English

Zero speed limit:
Enter in this field the maximum speed value above which the output of the function block (ZERO) will be 0 (FALSE). If the measured speed is less than the set value, the output (ZERO) of the function block will be 1 (TRUE).

Frequency zero speed: It shows the maximum calculated frequency values fM and fm (decreased by the hysteresis set). If the displayed value is GREEN, the calculation of frequency gave a positive result.
If the displayed value is RED, it is necessary to change the parameters given in the following formulas.

1. Rotary axis, rotary sensor. The frequency obtained is:

$$f[\mathrm{Hz}] = \frac{\mathrm{rpm}[\mathrm{rev/min}]}{60} * \mathrm{Resolution}[\mathrm{pulses/rev}]$$

2. Linear axis, rotary sensor. The frequency obtained is:

$$f[\mathrm{Hz}] = \frac{speed[\mathrm{m/min}] * 1000}{60 * pitch[\mathrm{mm/rev}]} * \mathrm{Re}\,solution[\mathrm{pulses/rev}]$$

3. Linear axis, linear sensor. The frequency obtained is:

$$f[\mathrm{Hz}] = \frac{\mathrm{speed}[\mathrm{mm/s}] * 1000}{\mathrm{Resolution}[\mu\mathrm{m/pulse}]}$$

4. Hysteresis. To be changed only if: fM=green; fm=red

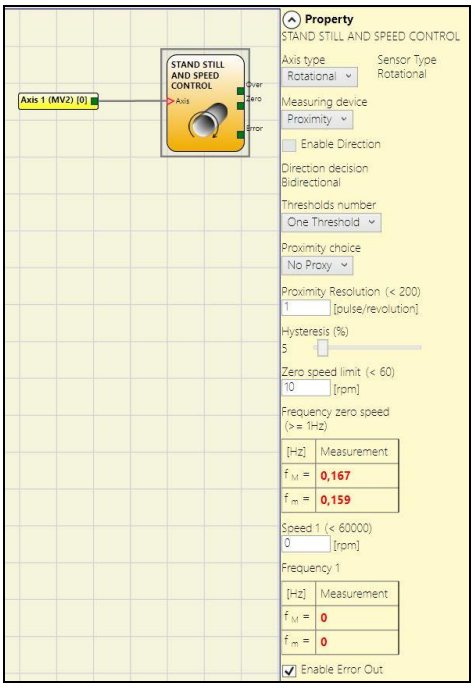
KEY:

f = frequency
Rpm = rotational speed
Resolution = measurement
Speed = linear speed
Pitch = sensor pitch

English

STAND STILL AND SPEED CONTROL

The **StandStill and Speed Control** function block monitors the speed of a device, generating the Zero to 1 (TRUE) output when the speed is lower than a selected value. In addition, it generates the Over = 0 (FALSE) output if the measured speed exceeds a predetermined threshold.



Parameters

Axis type: It defines the type of axis controlled by the device. It will be Linear in the case of a translation and will be Rotary in the case of motion around an axis.

Sensor Type: In the event that the previous parameter is Linear, the Sensor Type defines the type of sensor connected to the module inputs. It can be Rotary (e.g. shaft encoder) or Linear (e.g. optical array). This choice allows to define the following parameters.

Measuring device: It defines the type of sensor(s) used. The possible choices are:

- Encoder
- Proximity
- Encoder+Proximity
- Proximity1+ Proximity2
- Encoder1+ Encoder2

Enable direction: Enabling this parameter, the DIR output is enabled on the function block. This output will be 1 (TRUE) when the axis rotates Counterclockwise and will be 0 (FALSE) when the axis rotates Clockwise.

Direction decision: It defines the direction of rotation for which the set thresholds are made active. The possible choices are:

- Bidirectional
- Clockwise
- Counterclockwise

If Bidirectional is selected, the excess of the set threshold is detected whether the axis rotates clockwise or counterclockwise. Selecting Clockwise or Counterclockwise, this is detected only when the axis rotates in the selected direction.

Threshold number: It allows you to enter the number of thresholds for the maximum value of speed. Changing this value will increase/decrease the number of thresholds that can be entered from a minimum of 1 to a maximum of 4. In the case of thresholds greater than 1, the input pins for the selection of the specific threshold will appear in the lower part of the function block.

Pitch: If the Axis Type chosen was linear, this field allows you to enter the sensor pitch to obtain a conversion between sensor revolutions and distance travelled.

Example of CLOCKWISE axis rotation

2 threshold settings

In1	Threshold no.
0	Speed 1
1	Speed 2

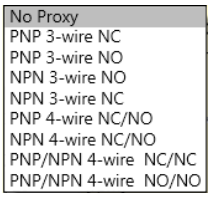
4 threshold settings

In2	In1	Threshold no.
0	0	Speed 1
0	1	Speed 2
1	0	Speed 3
1	1	Speed 4

English

Proximity choice: It allows you to choose the type of proximity sensor from PNP, NPN, Normally Open (NA) and Normally Closed (NC), with 3 or 4 wires.

(In order to ensure a Performance Level = PLe use a proximity switch type PNP NO: ref. "Interleaved proximity -> page 27).



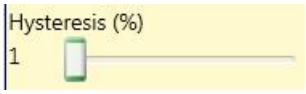
Proximity choice:

Measurement: Enter in this field the number of pulses/revolution (in the case of rotary sensor) or µm/pulse (linear sensor) relating to the sensor used

Verification: Enter in this field the number of pulses/revolution (in the case of rotary sensor) or µm/pulse (linear sensor) relating to the second sensor used.

Gear Ratio: This parameter is active if there are two sensors on the selected axis. This parameter allows you to enter the ratio between the two sensors. If both sensors are on the same moving parts, the ratio will be 1 otherwise the number corresponding to the report must be entered. E.g. there are an encoder and a proximity switch, and the latter is on a moving part that (due to a gear reduction ratio) rotates at twice the speed of the encoder. Therefore, this value must be set at 2.

Hysteresis (%): It represents the percentage hysteresis value below which the speed change is filtered. Enter a value other than 1 to avoid continuous switching as the input changes.



Zero speed limit:
Enter in this field the maximum speed value above which the output of the function block (ZERO) will be 0 (FALSE). If the measured speed is less than the set value, the output (ZERO) of the function block will be 1 (TRUE).

Speed 1, 2, 3, 4: Enter in this field the maximum speed value above which the function block output (OVER) will be 0 (FALSE). If the measured speed is less than the set value, the function block output (OVER) will be 1 (TRUE).

Frequency zero speed/Frequency1/ Frequency2: It shows the maximum calculated frequency values fM and fm (decreased by the hysteresis set). If the displayed value is GREEN, the calculation of frequency gave a positive result.
If the displayed value is RED, it is necessary to change the parameters given in the following formulas.

KEY:

f = frequency
Rpm = rotational speed
Resolution = measurement
Speed = linear speed
Pitch = sensor pitch

1. Rotary axis, rotary sensor. The frequency obtained is:

$$f[\mathrm{Hz}] = \frac{\mathrm{rpm}[\mathrm{rev/min}]}{60} * \mathrm{Resolution}[\mathrm{pulses/rev}]$$

2. Linear axis, rotary sensor. The frequency obtained is:

$$f[\mathrm{Hz}] = \frac{speed[\mathrm{m/min}] * 1000}{60 * pitch[\mathrm{mm/rev}]} * \mathrm{Re}\,solution[\mathrm{pulses/rev}]$$

3. Linear axis, linear sensor. The frequency obtained is:

$$f[\mathrm{Hz}] = \frac{\mathrm{speed}[\mathrm{mm/s}] * 1000}{\mathrm{Resolution}[\mu\mathrm{m/pulse}]}$$

4. Hysteresis. To be changed only if: fM=green; fm=red

English

OPERATOR FUNCTION BLOCKS

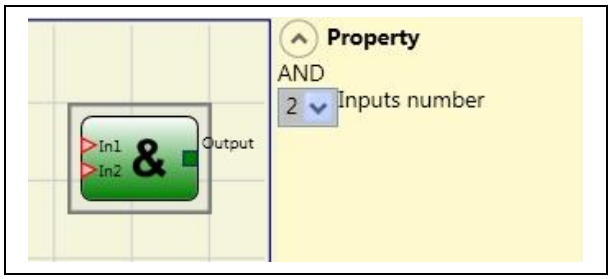
All the input of these operators could be inverted (logical NOT). It could be done clicking with the right mouse key on the input to be inverted. A little circle will be showed on the inverted input. To cancel the inversion, simply click another time on the same input pin.

➔ The maximum number of user blocks is 64.

LOGICAL OPERATORS

AND

Logical AND returns an output of 1 (TRUE) if all the inputs are 1 (TRUE).



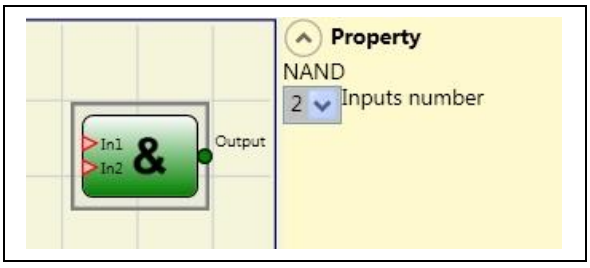
In_1	In_2	In_x	Out
0	0	0	0
1	0	0	0
0	1	0	0
1	1	0	0
0	0	1	0
1	0	1	0
0	1	1	0
1	1	1	1

Parameters

Number of inputs: this is used to set between 2 and 8 inputs.

NAND

Logical NAND returns an output of 0 (FALSE) if all the inputs are 1 (TRUE).



In_1	In_2	In_x	Out
0	0	0	1
1	0	0	1
0	1	0	1
1	1	0	1
0	0	1	1
1	0	1	1
0	1	1	1
1	1	1	0

Parameters

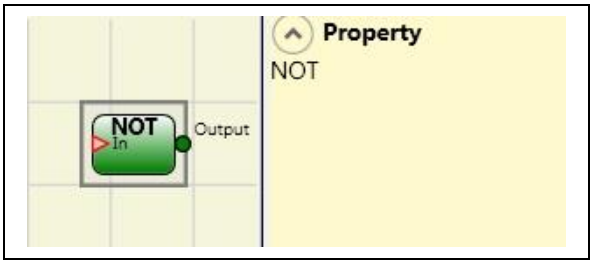
Number of inputs: this is used to set between 2 and 8 inputs.

English

NOT

Logical NOT inverts the logical status of the input.

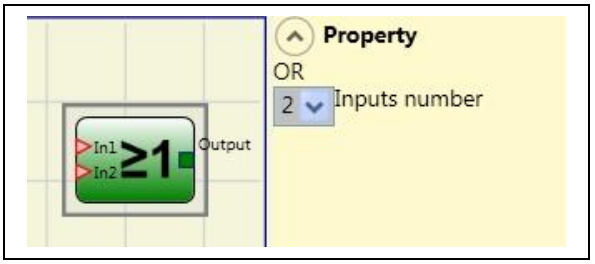
In	Out
0	1
1	0



OR

Logical OR returns an output of 1 (TRUE) if at least one of the inputs is 1 (TRUE).

In_1	In_2	In_x	Out
0	0	0	0
1	0	0	1
0	1	0	1
1	1	0	1
0	0	1	1
1	0	1	1
0	1	1	1
1	1	1	1



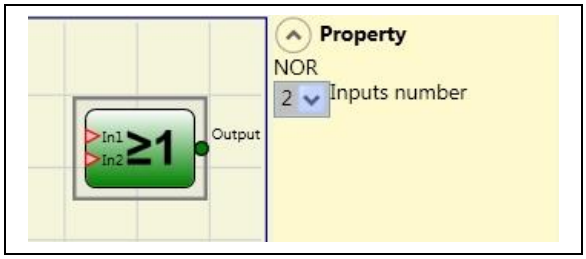
Parameters

Number of inputs: this is used to set between 2 and 8 inputs.

NOR

Logical NOR returns an output of 0 (FALSE) if at least one of the inputs is 1 (TRUE).

In_1	In_2	In_x	Out
0	0	0	1
1	0	0	0
0	1	0	0
1	1	0	0
0	0	1	0
1	0	1	0
0	1	1	0
1	1	1	0



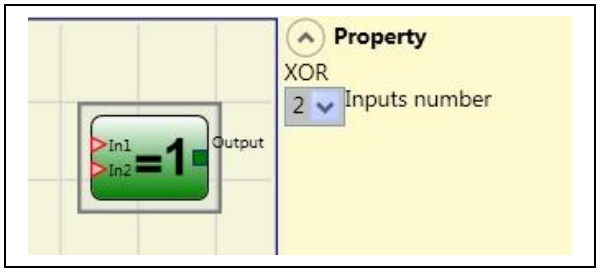
Parameters

Number of inputs: this is used to set between 2 and 8 inputs.

English

XOR

Logical XOR returns an output 0 (FALSE) if the input's number at 1 (TRUE) is even or the inputs are all 0 (FALSE).



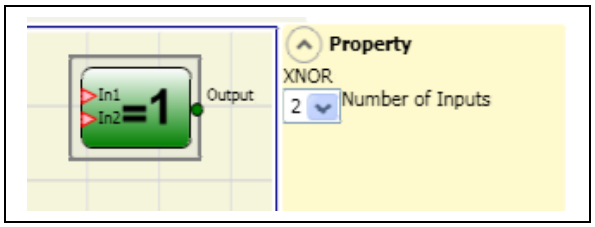
In1	In2	Inx	Out
0	0	0	0
1	0	0	1
0	1	0	1
1	1	0	0
0	0	1	1
1	0	1	0
0	1	1	0
1	1	1	1

Parameters

Number of inputs: this is used to set between 2 and 8 inputs.

XNOR

Logical XNOR returns an output 1 (TRUE) if the input's number at 1 (TRUE) is even or the inputs are all 0 (FALSE).



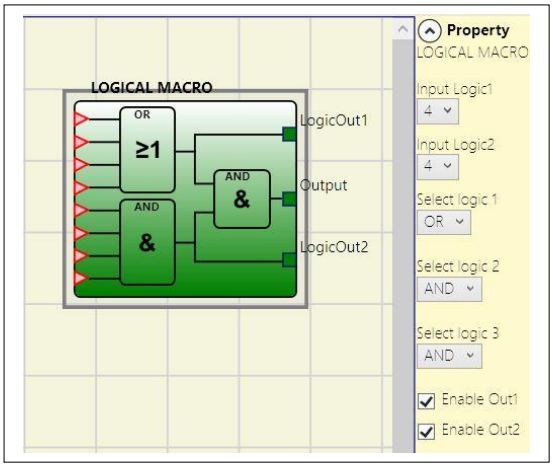
In1	In2	Inx	Out
0	0	0	1
1	0	0	0
0	1	0	0
1	1	0	1
0	0	1	0
1	0	1	1
0	1	1	1
1	1	1	0

Parameters

Number of inputs: this is used to set between 2 and 8 inputs.

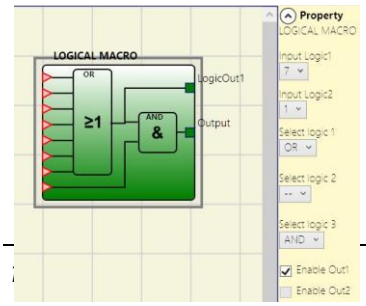
LOGICAL MACRO

This operator enables the grouping together of two or three logic gates.
A maximum of 8 inputs is foreseen.
The result of the first two operators converges into a third operator, the result of which is the OUTPUT.



Parameters

Logic inputs 1, 2: enables the selection of the number of logic inputs (from 1 to 7).



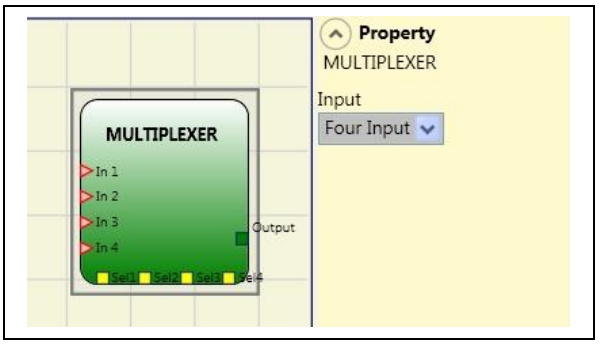
If one of the Logic Inputs equals "1", the corresponding logic is disabled and the input is directly connected to the end logic (refer to diagram opposite for example).

English

Select Logic 1, 2, 3: enables the selection of one of the following types of operator:
AND, NAND, OR, NOR, XOR, XNOR.

Enable (OUT1, OUT2) If selected, activates an output with the result of the first two operators.

MULTIPLEXER



Logical MULTIPLEXER forwards the signal of the inputs to the output according to the Sel selection. If the SEL1÷SEL4 have only one bit set, the selected *In n* is connected to the Output. If the SEL inputs are:
- more than one = 1 (TRUE)
- none = 1 (TRUE)
the output is set to 0 (FALSE) independently from the *In n* values.

Parameters

Number of inputs: this is used to set between 2 and 4 inputs.

English

MEMORY OPERATORS

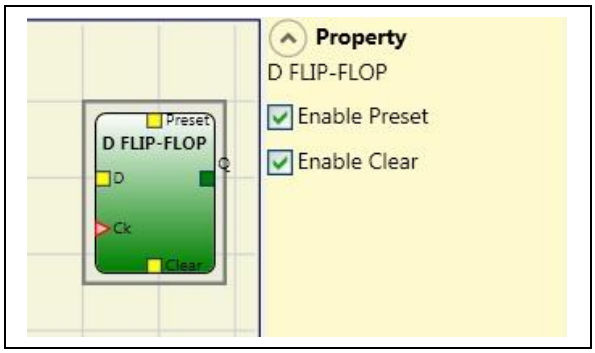
MEMORY operators can be used if you decide to save any data (TRUE or FALSE) from other project components.

Status changes are performed according to the truth tables shown for each operator.

D FLIP FLOP (max number = 16)

The D FLIP FLOP operator saves the previously set status on output Q according to the following truth table.

Preset	Clear	Ck	D	Q
1	0	X	X	1
0	1	X	X	0
1	1	X	X	0
0	0	L	X	Keep memory
0	0	Rising edge	1	1
0	0	Rising edge	0	0



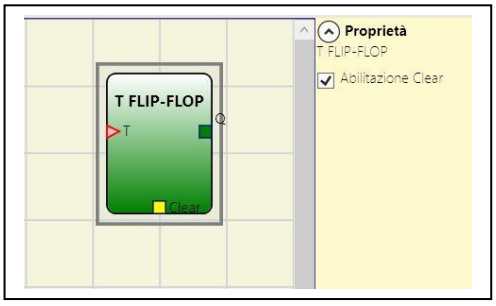
Parameters

Preset: If selected enables output Q to be set to 1 (TRUE).

Clear: If selected enables the saving process to be reset.

T FLIP FLOP (max number = 16)

This operator switches the Q output at each rising edge of the T input (Toggle).



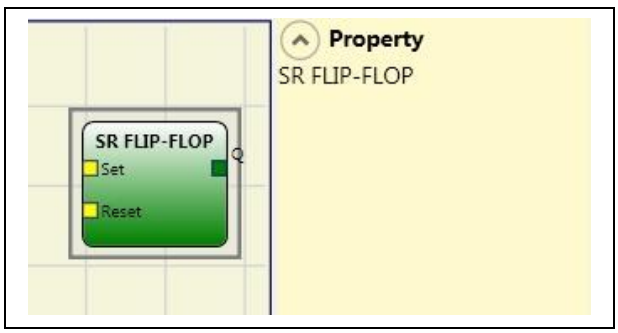
Parameters

Enable Clear: If selected enables the saving process to be reset.

SR FLIP FLOP (max number = 16)

SR FLIP FLOP operator brings output Q at 1 with Set, 0 with Reset.
See the following truth table.

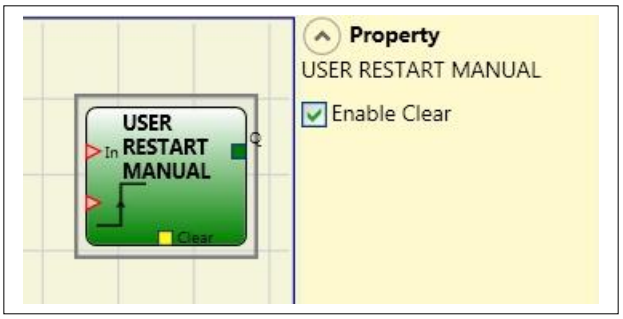
SET	RESET	Q
0	0	Keep memory
0	1	0
1	0	1
1	1	0



English

USER RESTART MANUAL (max number = 16 with other RESTART operators)

The USER RESTART MANUAL operator saves the restart signal according to the following truth table.



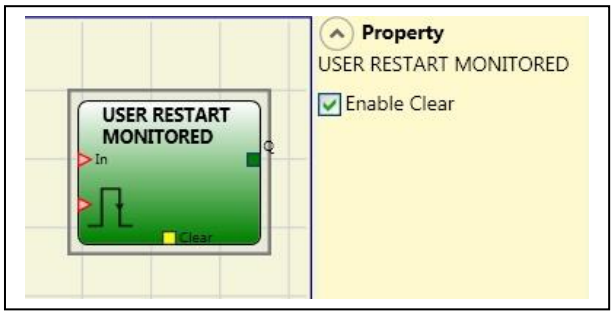
Clear	Restart	In	Q
1	X	X	0
X	X	0	0
0	L	1	Keep memory
0	Rising edge	1	1
0	Falling edge	1	Keep memory

Parameters

Clear enable: If selected enables the saving process to be reset.

USER RESTART MONITORED (max number = 16 with other RESTART operators)

The USER RESTART MONITORED operator is used to save the restart signal according to the following truth table.



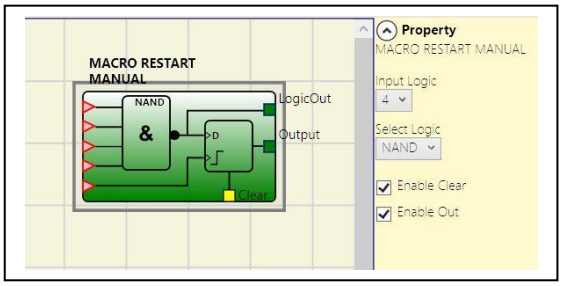
Clear	Restart	In	Q
1	X	X	0
X	X	0	0
0	L	1	Keep memory
0	Rising edge	1	Keep memory
0		1	1

Parameters

Clear enable: If selected enables the saving process to be reset.

MACRO RESTART MANUAL (max number = 16 with other RESTART operators)

The MACRO RESTART MANUAL operator is used to combine a logic gate chosen by the user with the Restart Manual functional block ("USER RESTART MANUAL") in accordance with the following truth table.



Clear	Restart	D	Q
1	X	X	0
X	X	0	0
0	L	1	Keep memory
0	Rising edge	1	1
0	Falling edge	1	Keep memory

English

Parameters

Logic Inputs: enables the selection of the number of logic inputs (from 1 to 7).

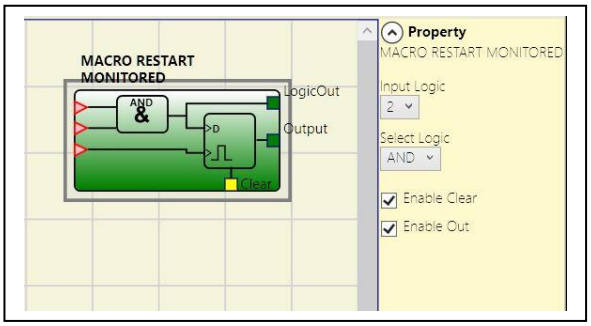
Select Logic: enables the selection of one of the following types of operator:
AND, NAND, OR, NOR, XOR, XNOR.

Enable Clear: If selected enables the saving process to be reset.

Enable Out: If selected activates an output with the result of the calculation done by the logic.

MACRO RESTART MONITORED (max number = 16 with other RESTART operators)

The MACRO RESTART MONITORED operator is used to combine a logic gate chosen by the user with the Restart Manual functional block ("USER RESTART MONITORED") in accordance with the following truth table.



Clear	Restart	D	Q
1	X	X	0
X	X	0	0
0	L	1	Keep memory
0	Rising edge	1	Keep memory
0	⎍	1	1

Parameters

Logic Inputs: enables the selection of the number of logic inputs (from 1 to 7).

Select Logic: enables the selection of one of the following types of operator:
AND, NAND, OR, NOR, XOR, XNOR.

Enable Clear: If selected enables the saving process to be reset.

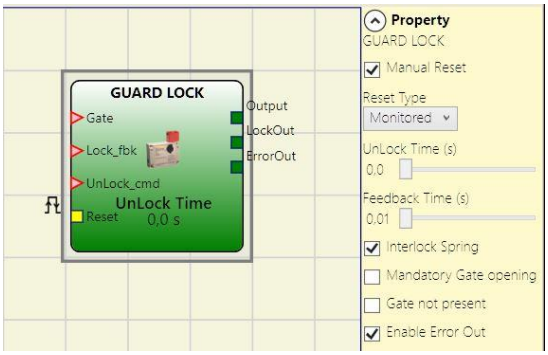
Enable Out: If selected activates an output with the result of the calculation done by the logic.

English

GUARD LOCK OPERATORS (max number = 4)

GUARD LOCK

The “**GUARD LOCK”** operator is designed to control locking/unlocking of an **ELECTROMECHANICAL GUARD LOCK** in a variety of operating contexts.



Description of "GUARD LOCK" operator inputs/outputs

“Lock_fbk” input

The “Lock_fbk” input is used to detect the status (feedback) of the electromagnet that unlocks/locks the guard lock.

Electromechanical guard locks are unlocked/locked via an electric control that energises/de-energises an electromagnet. Its status (energised/de-energised) is indicated by appropriate contacts. For example, the status of the electromagnet may be indicated by a normally open contact that is closed when the electromagnet is energised, as in the case shown in Figure 55.

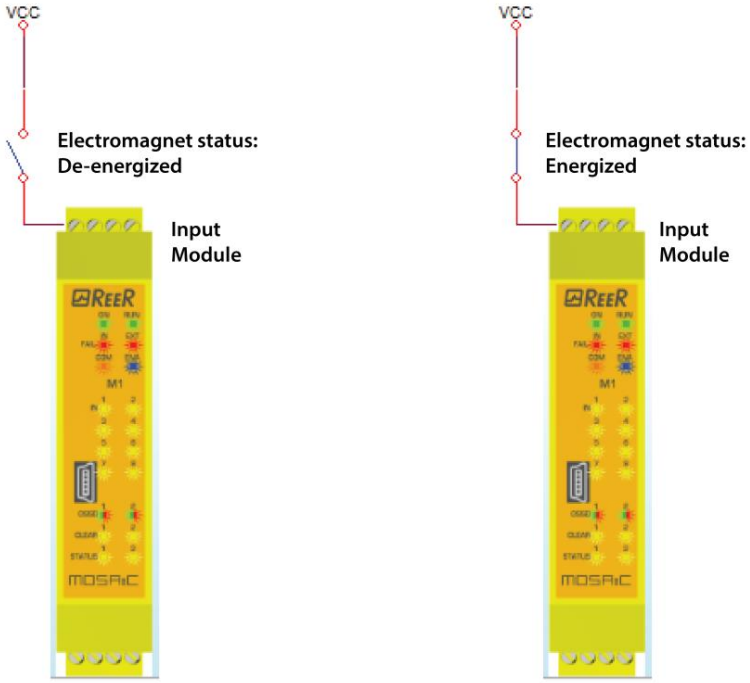


Figure 55 - Example of feedback of the status of the electromagnet of a guard lock. The signal received by the module is processed by the "Guard Lock" operator.

English

"Gate" input

When the "Gate" input is selected, it detects the status (feedback) of the door/gate connected to the guard lock.
The status of the door/gate (GATE) is detected using specific contacts. For example, the status of the door/gate may be indicated by a normally open contact that is closed when the door/gate is closed, as in the case in Figure 56.

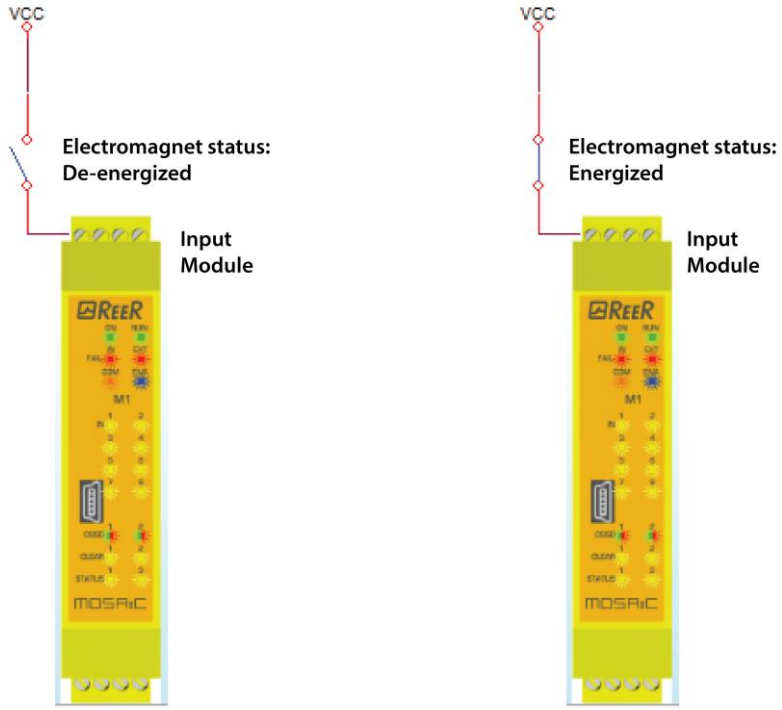


Figure 56 - Example of feedback of the status of a door/gate connected to the guard lock. The signal received by the module is processed by the "Guard Lock" operator.

"Unlock_cmd" input

The "Unlock_cmd" input detects the command sent by the user to lock or unlock the guard lock. In detail:

- Request to unlock: the Unlock_cmd signal must be set to LL1
- Request to lock: the Unlock_cmd signal must be set to LL0

The command signal may be sent via a key, for example.

"Output" out

This signal indicates the information shown in the table below, depending on its value.

	Value	Meaning
Output	LL1	• Door/Gate closed • Guard lock locked
Output	LL0	• User request to unlock the guard lock • Error condition

English

"LockOut" output

This signal controls the guard lock electromagnet and can assume LL0 and LL1 value.

"ErrorOut" output

If enabled, when this signal is set to LL1 it indicates an error in the control of the guard lock. It is set to LL0 when no errors have occurred.

Operation: general description

The "Guard Lock" operator analyses consistency between the status of the "Unlock_cmd" signal, the status of a door/gate (E-GATE), if present, via the "Gate" signal, and the status of the electromagnet via the "Lock_fbk" signal. The main output, "Output", is LL1 (TRUE) when the guard lock is closed and locked.

Operation in the "no Gate" mode

In this case, the user must select the "Gate not prese
The **Lock_Fbk** input must always be connected to a "
the LOCK FEEDBACK section on page 84) that ve
electromagnet.

The **UnLock_cmd** input can be connected freely i
request to unlock the guard lock (when set to LL1).

The **Output** signal is LL1 (TRUE) if the safety guard i
command is applied to the **UnLock_cmd** input, the
guard lock is unlocked via the **LockOut** signal.
The **Output** signal can also be set to LL0 (FALSE) when error conditions are present (e.g. open door with guard lock locked, *Feedback Time* exceeding the maximum allowed, etc.).

When the **Unlock_cmd** signal is detected, the **LockOut** signal unlocks the guard lock after the *UnLock Time,* a parameter that can be defined by the user.

The time after which the electromagnet is activated depends entirely on the technical/physical characteristics of the specific device and may therefore vary according to the type of guard lock used. Thus, since the **LockOut** signal controls the activation of this device, the status of the **Lock_Fbk** feedback signal will change at different times, depending on the type of guard lock. This variability can be avoided by changing the value of the *Feedback Time* parameter, which is the maximum delay accepted by the "Guard_Lock" operator before the **Lock_Fbk** signal switches status following a request to activate the electromagnet. Clearly, the following condition must be met:

$$Feedback\ Time \geq Electromagnet\ activation\ time$$

This will now be explained using a practical example.

Example of operation in the "no Gate" mode

In this example the user unlocks the guard lock with the "COMMAND" block, which is a switch. The "LockOut" signal controls an "ACTIV." output that controls the guard lock

English

electromagnet, the status of which is detected by the “Lock_fbk” input via the “FBK_ELECTRO” input block. “Output1” indicates the status of the operations.
The guard lock used in the example continues to be locked when the electromagnet is not energised. Therefore the "Interlock spring" option must be selected.

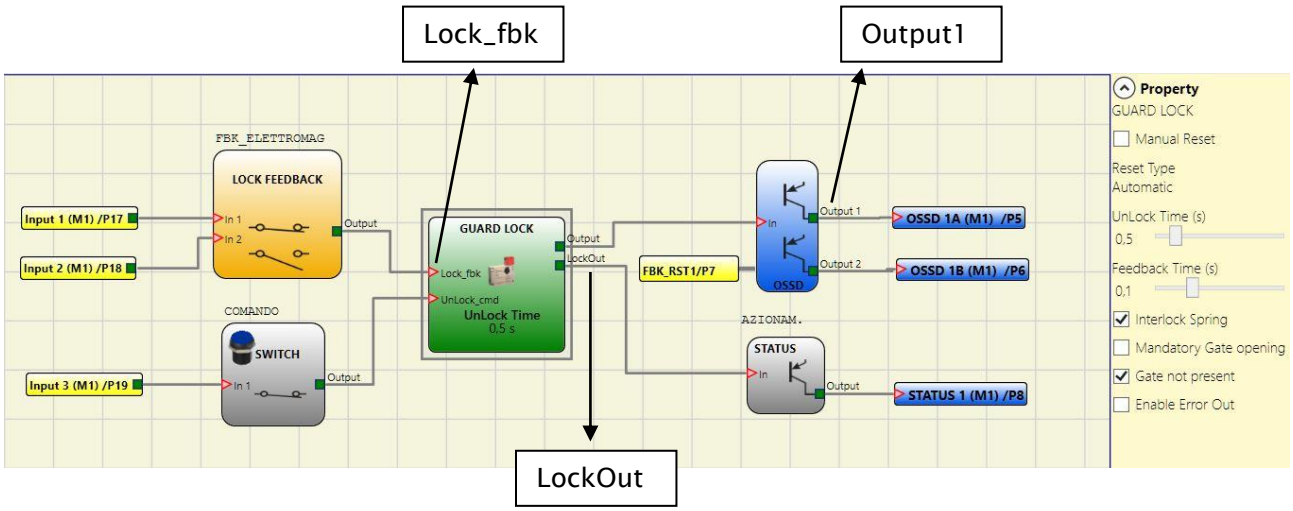


Figure 57 – Example of operation in the no Gate mode

➔ The Guard Lock operator parameters are shown on the right. On the left there is an example of an application diagram. The electromagnet feedback consists of two contacts, one normally closed and one normally open. When the electromagnet is energised the two contacts switch status.

Figure 58 shows the traces relative to the operation. These are described in detail below:

(1) At this time the user requests to unlock the guard lock. The “COMMAND” signal switches from LL0 to LL1, and the “OUTPUT1” signal switches from LL1 to LL0.
(2) At this time the electromagnet is activated with a delay of "Unlock Time", after the command is sent. This delay has been set to 0.5 seconds. The “ACTIV.” signal switches from LL0 to LL1.
(3) At this time the electromagnet is actually activated, 95ms after the command was sent. This delay is due to the technical characteristics of the electromagnet. In any case, 95ms is less than 100ms ("Feedback Time") and so no errors have occurred.
(4) At this time the user releases the unlock command and the “COMMAND” signal switches from LL1 to LL0 as does the “ACTIV.” activation signal.
(5) At this time the electromagnet is actually deactivated, approx. 95ms after the command was sent due to the technical characteristics of the device. The guard lock is now locked.
(6) As soon as the “Guard Lock” operator detects that the guard lock is locked and the gate is closed, the “OUTPUT1” signal switches to LL1.

English

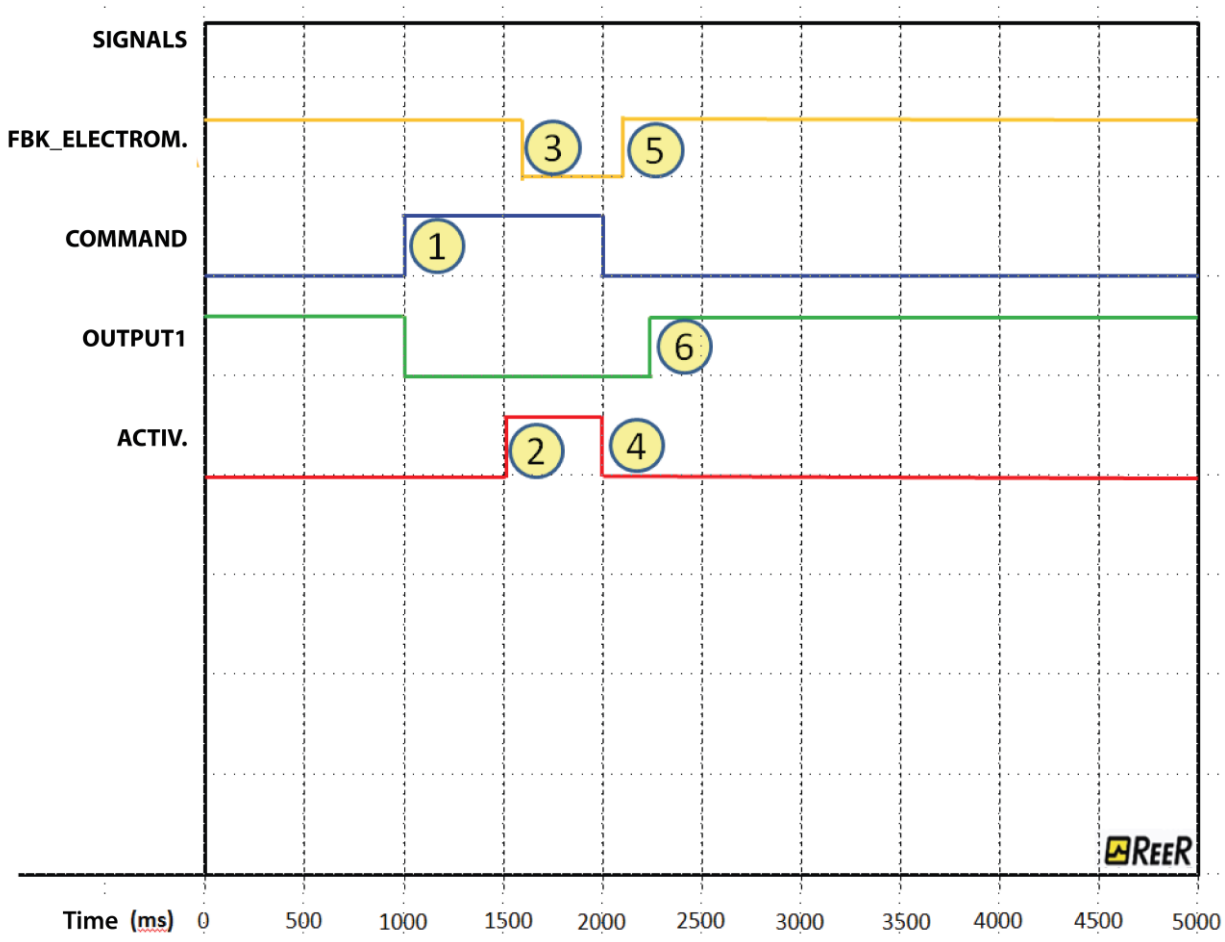
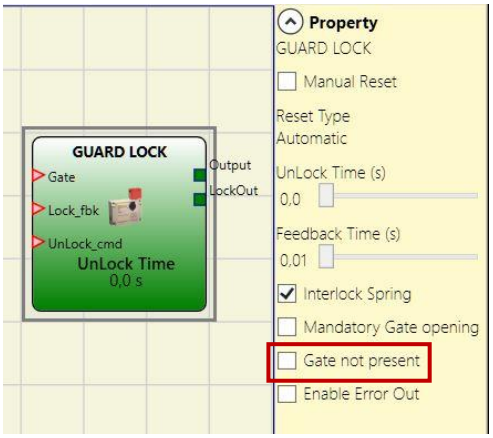


Figure 58 - Traces relative to "Guard Lock" block operation in the no gate mode.

Operation in the "with Gate" mode



In this case, the user must **NOT** select the "Gate not present" parameter.

The **Gate** input must always be connected to an "E-GATE" input element (see the E-GATE (safety gate device) section on page 82) that verifies the status of the door/gate.

The **Lock_Fbk** input must always be connected to a "LOCK FEEDBACK" input element (see the LOCK FEEDBACK section on page 84) that verifies the status of the guard lock electromagnet.

The **UnLock_cmd** input can be connected freely in the diagram and determines the request to unlock the guard lock (when set to LL1).

The **Output** signal is LL1 (TRUE) if the safety guard is closed and locked. When an unlock command is applied to the **UnLock_cmd** input, the **Output** signal is set to LL0 and the guard lock is unlocked via the **LockOut** signal.
The **Output** signal can also be set to LL0 (FALSE) when error conditions are present (e.g. open door with guard lock locked, **Feedback Time** exceeding the maximum allowed, etc.).

English

When the **Unlock_cmd** signal is detected, the **LockOut** signal unlocks the guard lock after the *UnLock Time,* a parameter that can be defined by the user.
The time after which the electromagnet is activated depends entirely on the technical/physical characteristics of the specific device and may therefore vary according to the type of guard lock used. Thus, since the **LockOut** signal controls the activation of this device, the status of the **Lock_Fbk** feedback signal will change at different times, depending on the type of guard lock. This variability can be avoided by changing the value of the *Feedback Time* parameter, which is the maximum delay accepted by the "Guard_Lock" operator before the **Lock_Fbk** signal switches status following a request to activate the electromagnet. Clearly, the following condition must be met:

$$\textit{Feedback Time} \geq \textit{Electromagnet activation time}$$

This will now be explained using a practical example.

Example of operation in the "with Gate" mode

In this example the user unlocks the guard lock with the "COMMAND" block, which is a switch. The "LockOut" signal controls an "ACTIV." output that controls the guard lock electromagnet, the status of which is detected by the "Lock_fbk" input via the "FBK_ELECTRO" input block. "Output1" indicates the status of the operations.
The status of the safety gate is monitored by the "Gate" input via the "FBK_GATE" input.
The guard lock used in the example continues to be locked when the electromagnet is not energised. Therefore the "Interlock spring" option must be selected.

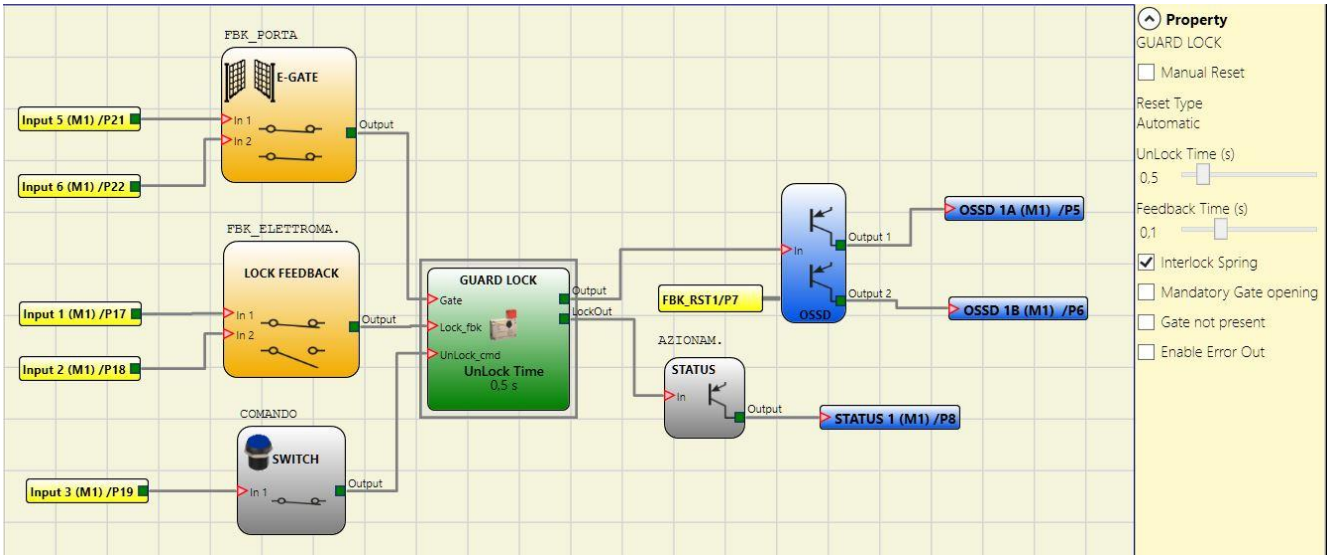


Figure 59 – Example of operation in the with Gate mode

➔ The Guard Lock operator parameters are shown on the right. On the left there is an example of an application diagram. The electromagnet feedback consists of two contacts, one normally closed and one normally open. When the electromagnet is energised the two contacts switch status. The gate feedback consists of two normally closed contacts.

English

Figure 60 shows the traces relative to the operation. These are described in detail below:

(1) At this time the user requests to unlock the guard lock. The “COMMAND” signal switches from LL0 to LL1, and the “OUTPUT1” signal switches from LL1 to LL0.
(2) At this time the electromagnet is activated with a delay of "Unlock Time", after the command is sent. This delay has been set to 0.5 seconds. The “ACTIV.” signal switches from LL0 to LL1.
(3) At this time the electromagnet is actually activated, 95ms after the command was sent. This delay is due to the technical characteristics of the electromagnet. In any case, 95ms is less than100ms ("Feedback Time") and so no errors have occurred.
(4) At this time the guard lock is unlocked and the user opens the gate, the FBK_GATE signal switches from LL1 to LL0.
(5) At this time the user closes the gate and the FBK_GATE signal thus switches from LL0 to LL1.
(6) At this time the user releases the unlock gate command. The “Guard Lock” detects the gate closed condition, via the FBK_GATE signal, and sends a command to lock the guard lock. The “ACTIV.” signal switches from LL1 to LL0.
(7) At this time the electromagnet is actually deactivated, approx. 95ms after the command was sent due to the technical characteristics of the device. The guard lock is now locked.
(8) As soon as the “Guard Lock” operator detects that the guard lock is locked and the gate is closed, the “OUTPUT1” signal switches to LL1.

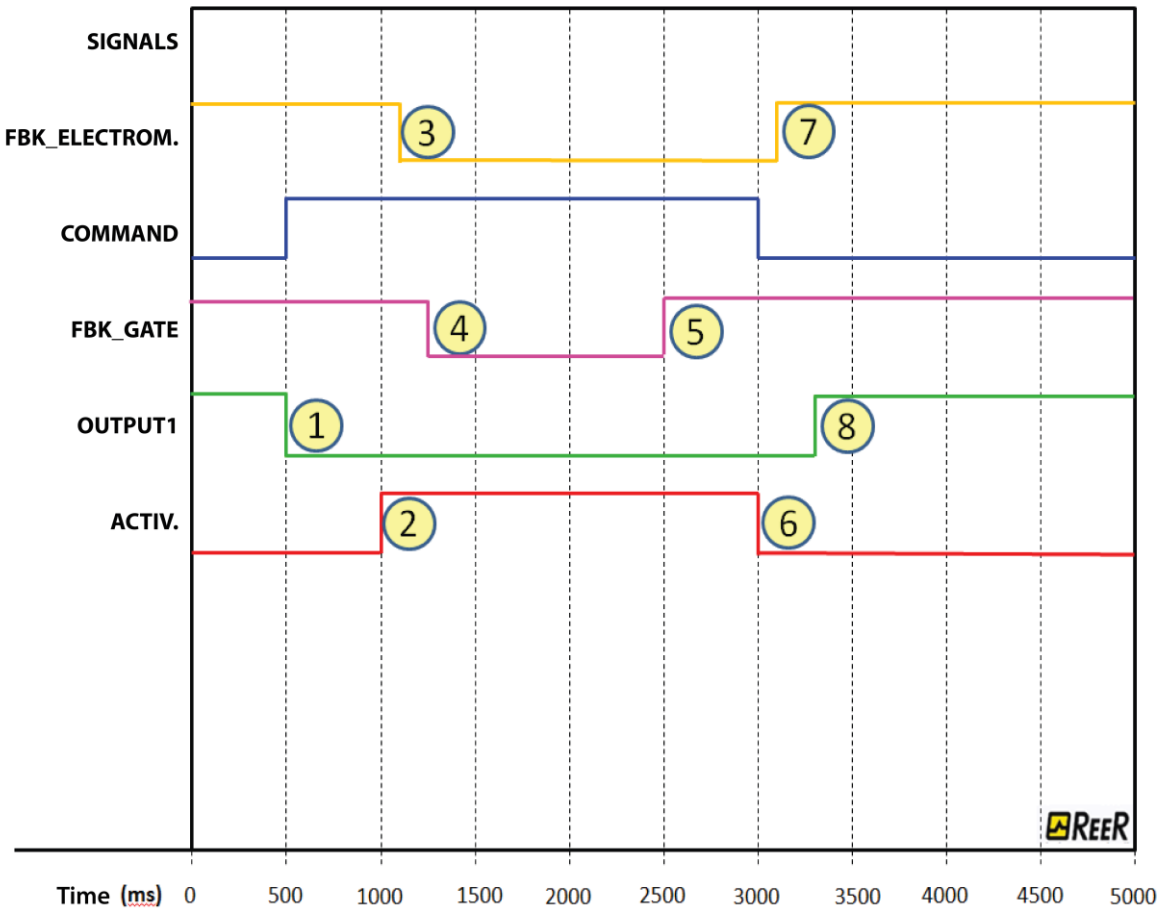
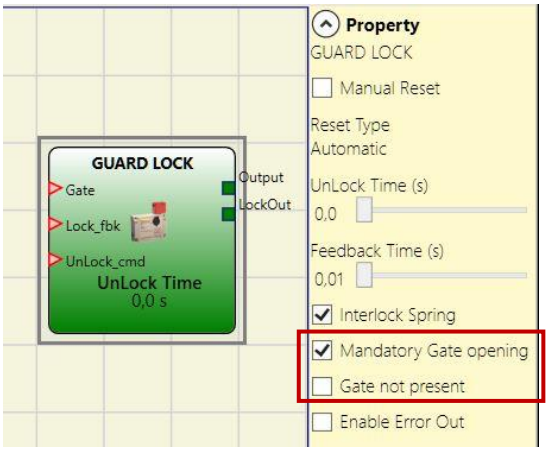


Figure 60 - Traces relative to “Guard Lock” block operation in the with gate mode.

English

Operation in the "Mandatory Gate Opening" mode



In this case, the user must **NOT** select the "Gate not present" parameter and must select the "Mandatory Gate opening" parameter.

The **Gate** input must always be connected to an "E-GATE" input element (see the E-GATE (safety gate device) section on page 82) that verifies the status of the door/gate. NB: IN THIS OPERATING MODE THE "GATE" INPUT MUST CONFIRM THE OPENING OF THE GATE.

The **Lock_Fbk** input must always be connected to a "LOCK FEEDBACK" input element (see the LOCK FEEDBACK section on page 84) that verifies the status of the guard lock electromagnet.

The **UnLock_cmd** input can be connected freely in the diagram and determines the request to unlock the guard lock (when set to LL1).

The **Output** signal is LL1 (TRUE) if the safety guard is closed and locked. When an unlock command is applied to the **UnLock_cmd** input, the **Output** signal is set to LL0 and the guard lock is unlocked via the **LockOut** signal.
The **Output** signal can also be set to LL0 (FALSE) when error conditions are present (e.g. open door with guard lock locked, **Feedback Time** exceeding the maximum allowed, etc.).

When the **Unlock_cmd** signal is detected, the **LockOut** signal unlocks the guard lock after the *UnLock Time,* a parameter that can be defined by the user.

The time after which the electromagnet is activated depends entirely on the technical/physical characteristics of the specific device and may therefore vary according to the type of guard lock used. Thus, since the the **LockOut** signal controls the activation of this device, the status of the **Lock_Fbk** feedback signal will change at different times, depending on the type of guard lock. This variability can be avoided by changing the value of the *Feedback Time* parameter, which is the maximum delay accepted by the "Guard_Lock" operator before the **Lock_Fbk** signal switches status following a request to activate the electromagnet. Clearly, the following condition must be met:

$$\textit{Feedback Time} \geq \textit{Electromagnet activation time}$$

This will now be explained using a practical example.

English

Example of operation in the "Mandatory Gate Opening" mode

In this example the user unlocks the guard lock with the "COMMAND" block, which is a switch. The "LockOut" signal controls an "ACTIV." output that controls the guard lock electromagnet, the status of which is detected by the "Lock_fbk" input via the "FBK_ELECTRO" input block. "Output1" indicates the status of the operations.
The status of the safety gate is monitored by the "Gate" input via the "FBK_GATE" input block, the "Mandatory Gate opening" parameter is selected.
The guard lock used in the example continues to be locked when the electromagnet is not energised. Therefore the "Interlock spring" option must be selected.

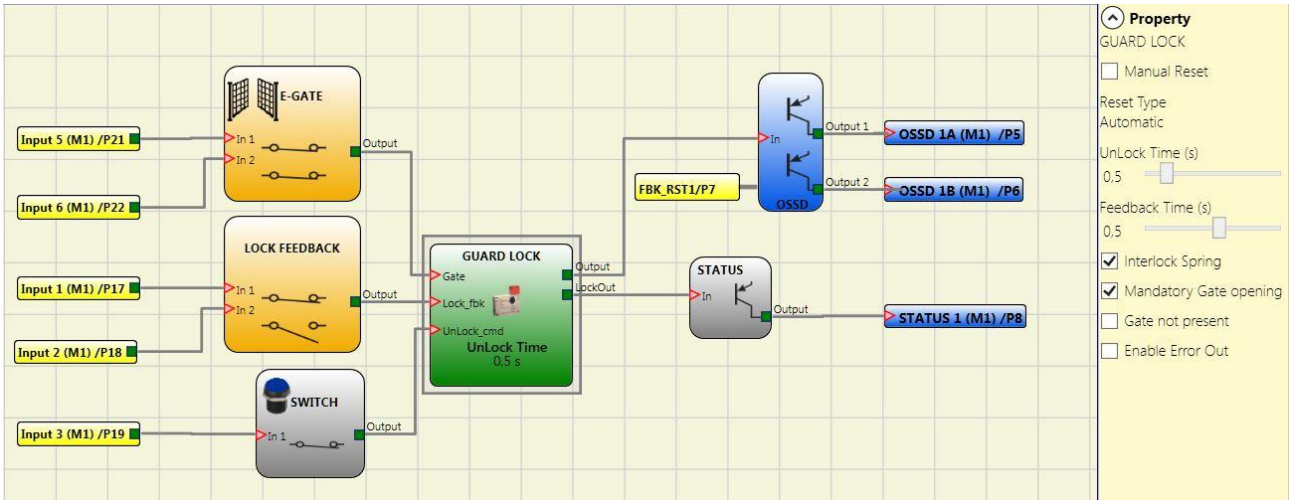


Figure 61 Example of operation in the Mandatory Gate Opening mode

➔ The Guard Lock operator parameters are shown on the right. On the left there is an example of an application diagram. The electromagnet feedback consists of two contacts, one normally closed and one normally open. When the electromagnet is energised the two contacts switch status. The gate feedback consists of two normally closed contacts.

Figure 62 shows the traces relative to the operation. These are described in detail below:

(1) At this time the user requests to unlock the guard lock. The "COMMAND" signal switches from LL0 to LL1, and the "Output1" signal switches from LL1 to LL0.
(2) At this time the electromagnet is activated with a delay of "Unlock Time", after the command is sent. This delay has been set to 0.5 seconds. The "ACTIV." signal switches from LL0 to LL1.
(3) At this time the electromagnet is actually activated, 95ms after the command was sent. This delay is due to the technical characteristics of the electromagnet. In any case, 95ms is less than 100ms ("Feedback Time") and so no errors have occurred.
(4) At this time the guard lock is unlocked and the user opens the gate. The FBK_GATE signal switches from LL1 to LL0.
(5) At this time the user closes the gate and the FBK_GATE signal thus switches from LL0 to LL1.
(6) At this time the user releases the unlock gate command. The "Guard Lock" detects the gate closed condition, via the FBK_GATE signal, and sends a command to lock the guard lock. The "ACTIV." signal switches from LL1 to LL0.

English

(7) At this time the electromagnet is actually deactivated, approx. 95ms after the command was sent due to the technical characteristics of the device. The guard lock is now locked.
(8) As soon as the “Guard Lock” operator detects that the guard lock is locked and the gate is closed, the “Output1” signal switches to LL1.

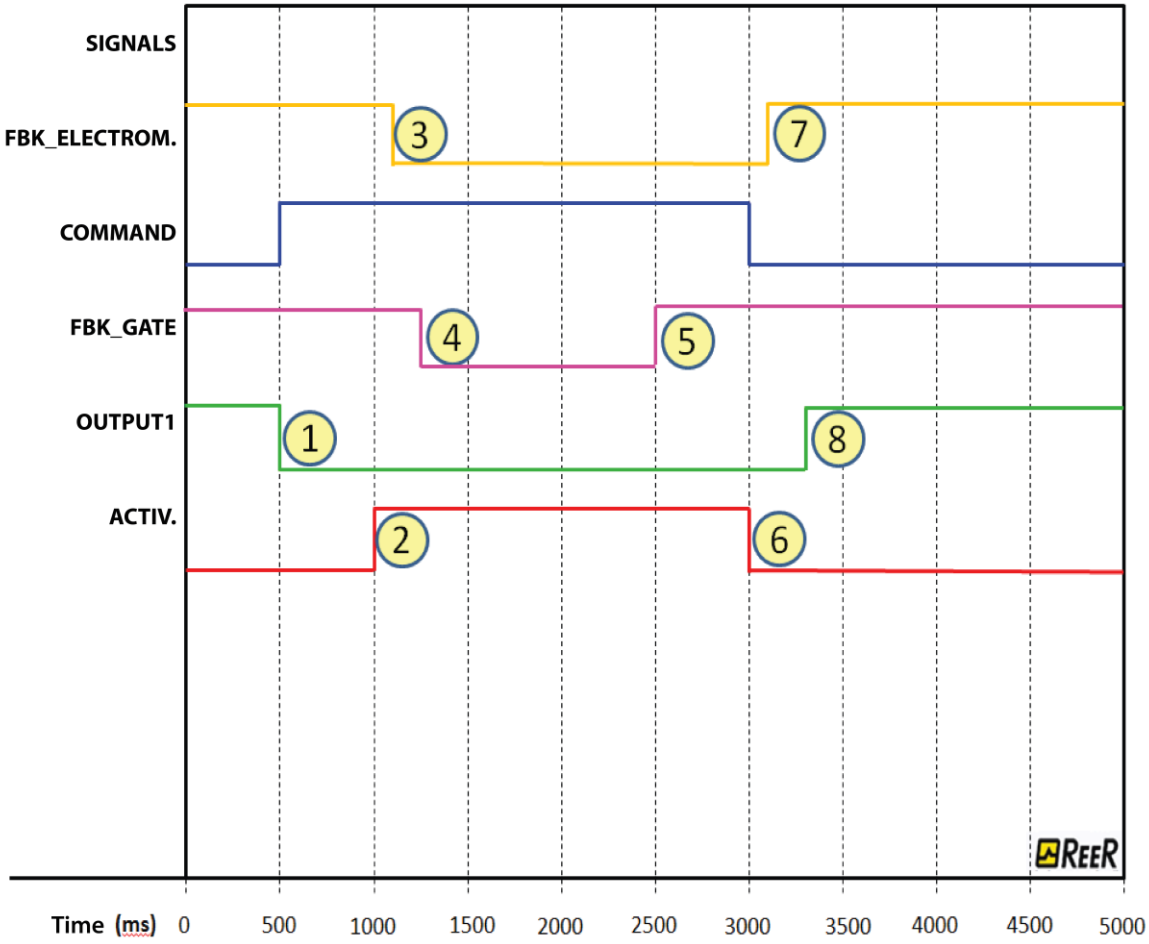


Figure 62 - Traces relative to “Guard Lock” block operation in the “Mandatory gate opening mode”.

In “Mandatory gate opening” mode, the “Guard_lock” operator indicates an error condition if it does not detect that the gate has been opened following a request to unlock the guard lock. This concept is highlighted in the figure below (Figure 63). In this case, the “Enable Error out” option has been selected in the diagram in Figure 61, so that the error is shown in the graph.

As previously described, the operator requests unlocking of the guard lock, but the door is never opened, and this condition is indicated by the "FBK_GATE" signal, which stays at LL1. Thus, when the guard lock unlocking/locking cycle ends, at time "E", the “Guard_Lock” operator switches the status of the “ERROR” signal from LL0 to LL1.

English

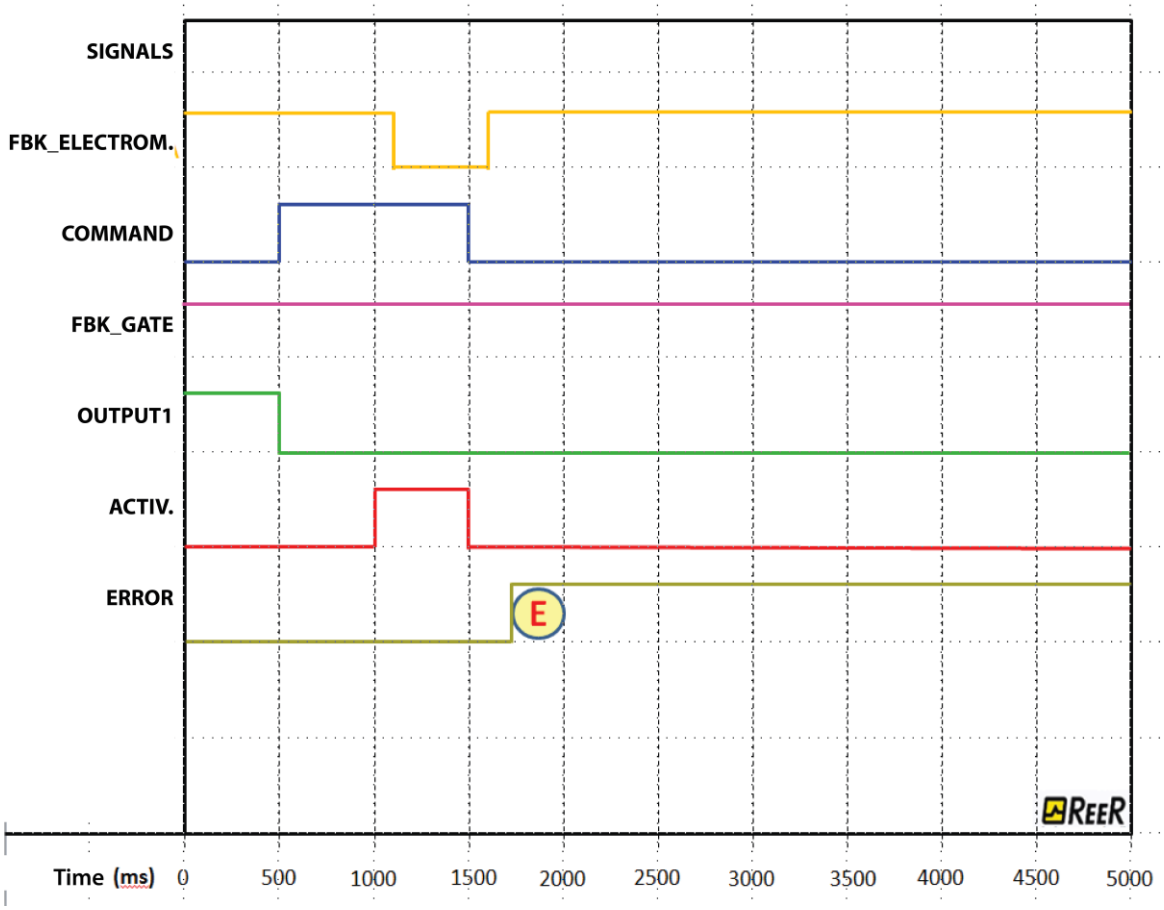
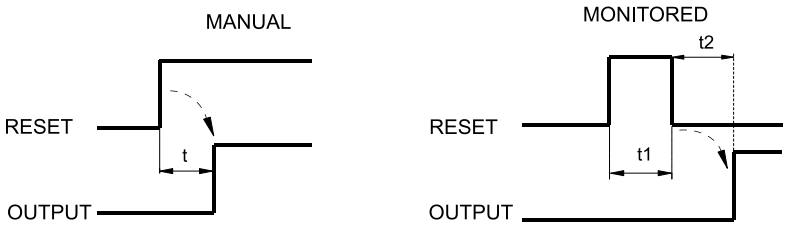


Figure 63 – Example of possible error condition in "Mandatory gate opening" mode. In this case the error condition is generated because the gate has not been opened, even though a request has been sent to unlock/lock the guard lock.

Parameters

Manual Reset:

There are two types of reset: Manual and Monitored. When Manual is selected the system only verifies the signal's transition from 0 to 1. If Monitored is selected the double transition from 0 to 1 and then back to 0 is verified.



Important: for Manual reset always use the input immediately after those used by the function block. E.g.: if inputs 1 and 2 are used for the function block, use input 3 for Reset.

English

Unlock Time (s):
The time that must pass between the **UnLock_cmd** input reaching and the real guard unlock (**Lockout output**).

- 0ms ÷ 1 s Step 100 ms
- 1.5 s ÷ 10 s Step 0.5 s
- 15 s ÷ 25 s Step 5 s

Feedback Time (s):
Maximum delay accepted between **LockOut** output and **Lock_fbk** input (must be the one shown on the lock data sheet with appropriate gap decided by the operator).

- 10ms ÷ 100 s Step 10 ms
- 150ms ÷ 1 s Step 50 ms
- 1.5 s ÷ 3 s Step 0.5 s

Mandatory gate opening: Only with door opening and subsequent confirmation of input GATE, the cycle proceeds.

Gate not present: If selected, enables configuration without Gate but only with LOCK FEEDBACK (feedback coil lock).

Interlock Spring: The guard is locked passively and released actively, i.e. the mechanical force of the spring keeps it locked. *The guard thus continues to be locked even when the power supply is disconnected.*

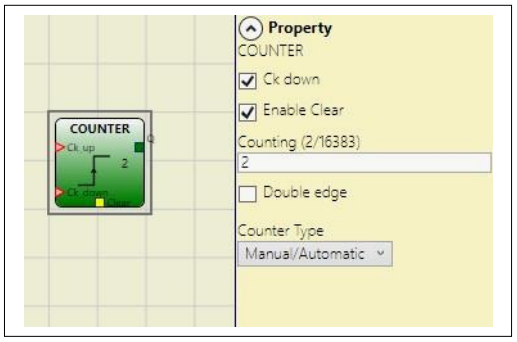
Enable error out: This can be selected to enable a signal (Error Out) to indicate a lock malfunction. When Error Out = 1 (TRUE) there is a fault in the lock.

English

COUNTER OPERATORS

COUNTER operator is a pulse counter that sets output Q to 1 (TRUE) as soon as the desired count is reached.

COUNTER (max number = 16)



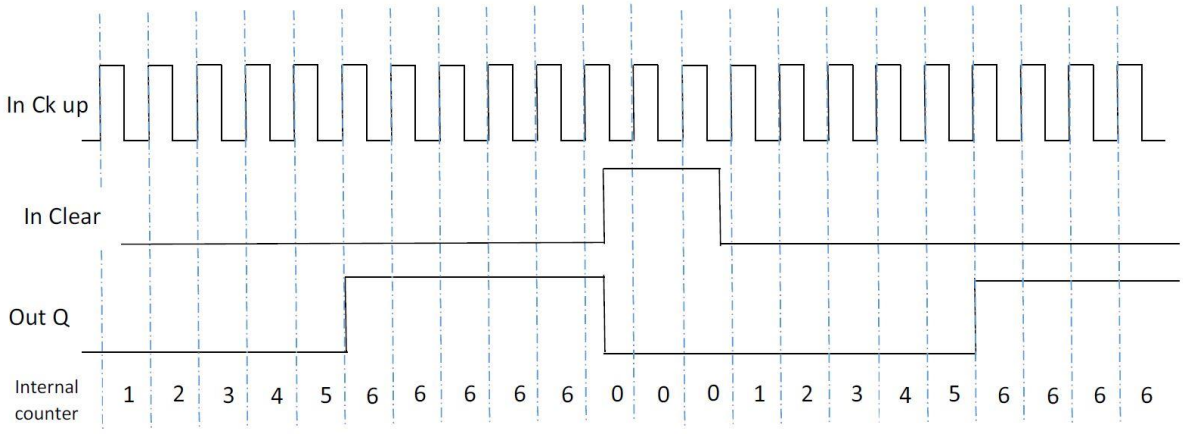
The operator COUNTER is a pulse counter.
There are 3 operationg modes:

1) AUTOMATIC
2) MANUAL
3) AUTOMATIC + MANUAL

Counter value is 6 for all examples:

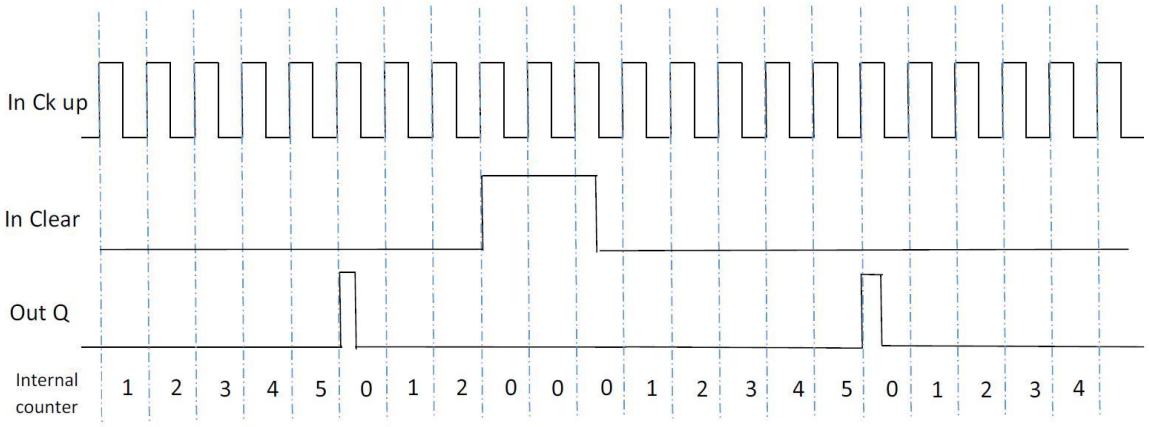
1) The counter generates a pulse duration equal to 2 x Tcycle (indicated in the REPORT) as soon as the set count is reached. If the CLEAR pin is not enabled this is the default mode.

2) The counter leads to 1 (TRUE) the output Q as soon as it reaches the set count. The output Q goes to 0 (FALSE) when the signal CLEAR is activated.



English

3) The counter generates a pulse duration equal to the system response time as soon as the set count is reached. If the CLEAR signal is activated, the internal count goes back to 0.



Parameters

Clear Enable: If selected this enables the request to clear in order to restart the counter setting output Q to 0 (FALSE). It also offers the possibility of enabling or not enabling (*Automatic Enable*) automatic operation with manual reset.

If this is not selected operation is automatic. Once the set count is reached output Q is set to 1(TRUE) and stays in this condition for 2 x Tcycle (indicated in the REPORT) after which it is resetted.

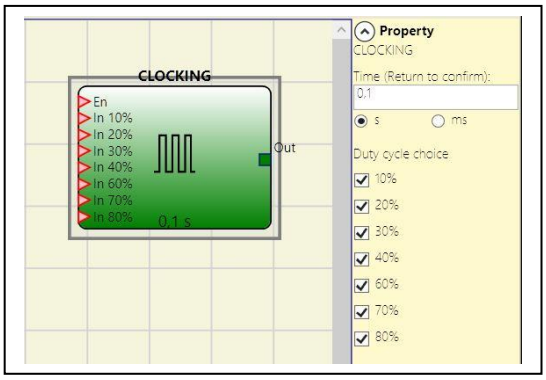
Ck down: Enables counting down.
Two-way: If selected it enables counting on both the rising and falling edges.

English

TIMER OPERATORS (max number = 32)

TIMER operators allow you to generate a signal (TRUE or FALSE) for a user-definable period.

CLOCKING



The CLOCKING operator generates a clock signal output with the set period if the IN input is 1 (TRUE). Clocking has up to 7 inputs to control output Duty Cycle.

Parameters

Time: The period can be set to between 10 ms and 1098.3 s.

Duty cycle selection: Up to 7 inputs can be selected for 7 different output signal duty cycles.

Depending on the active input, the OUT clock signal has its corresponding duty cycle.

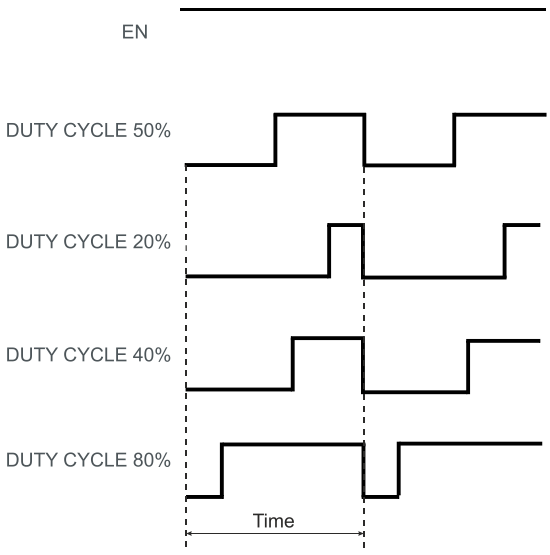
EN input must always be high level (TRUE).

Refer to the table below to check operator functioning.

EN	10%	20%	30%	40%	50%	60%	70%	80%	OUT
0	0	0	0	0	0	0	0	0	0
1	0	0	0	0	0	0	0	0	**50%**
1	**1**	0	0	0	0	0	0	0	**10%**
1	0	**1**	0	0	0	0	0	0	**20%**
1	0	0	**1**	0	0	-	0	0	**30%**
1	0	0	0	**1**	0	-	0	0	**40%**
1	0	0	0	0	**1**	-	0	0	**50%**
1	0	0	0	0	0	**1**	0	0	**60%**
1	0	0	0	0	0	0	**1**	0	**70%**
1	0	0	0	0	0	0	0	**1**	**80%**
1	**1**	0	0	0	0	0	0	**1**	**90%**

➔ The circuit upstream of the CLOCKING operator must guarantee the presence of a single input signal other than the EN enable (apart from the pair 10% 80%).

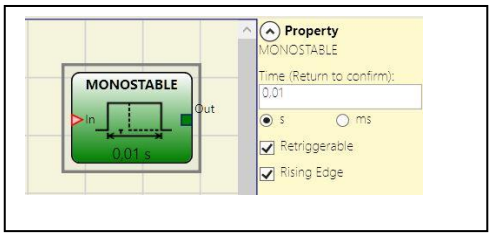
➔ The presence of the EN input together with > 1 high level (TRUE) inputs, generates an output signal with a duty cycle = 50%.



English

MONOSTABLE

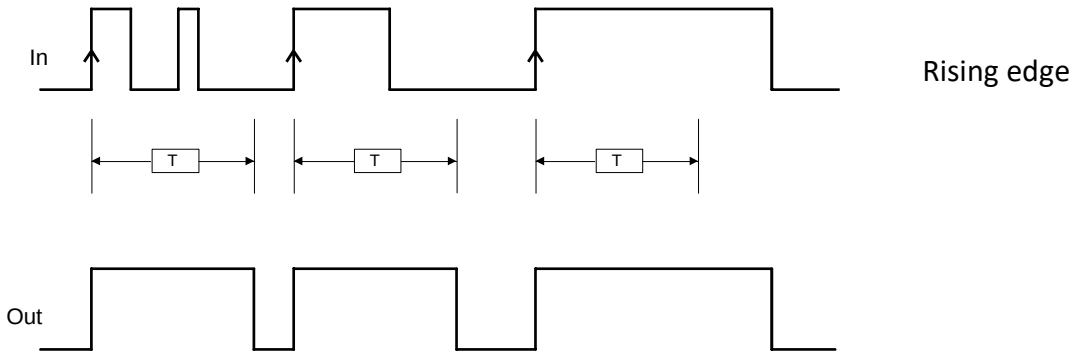
The MONOSTABILE operator generates a level 1 (TRUE) output activated by the rising edge of the input and remains in this condition for the set time.



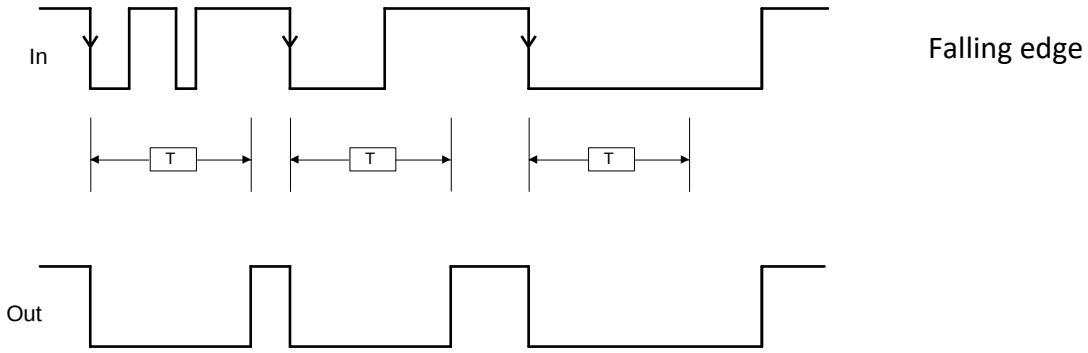
Parameters

Time: The delay can be set to between 10 ms and 1098.3 s.

Rising edge: If selected, the output is set to 1 (TRUE) on the input signal's rising edge where it remains for the set time, which can be extended for as long as the input stays at 1 (TRUE).



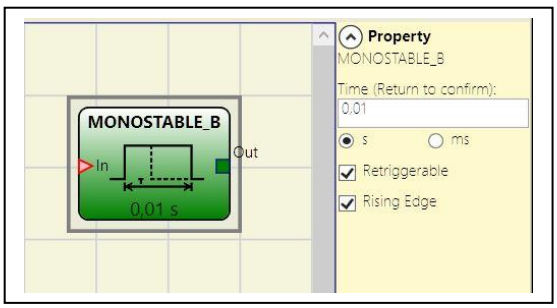
If not selected the logic is inverted, the output is set to 0 (FALSE) on the input signal's falling edge, where it remains for the set time, which can be extended for as long as the input stays at 0 (FALSE).



Retriggerable: If selected the time is reset each time the input status changes.

MONOSTABLE_B

This operator generates a level 1 (TRUE) output activated by the rising/falling edge of the input and remains in this condition for the set time *t*.



Parameters

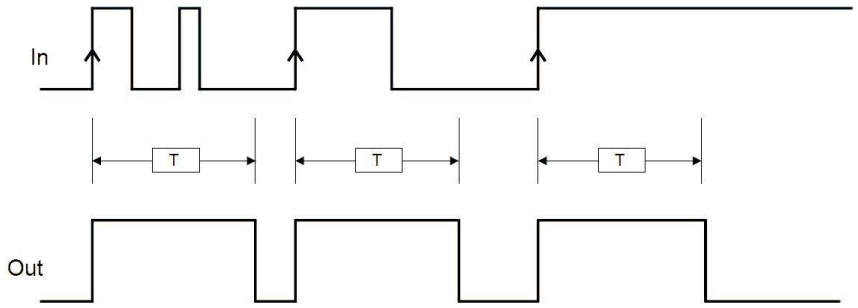
Time: The delay can be set to between 10 ms and 1098.3 s.

English

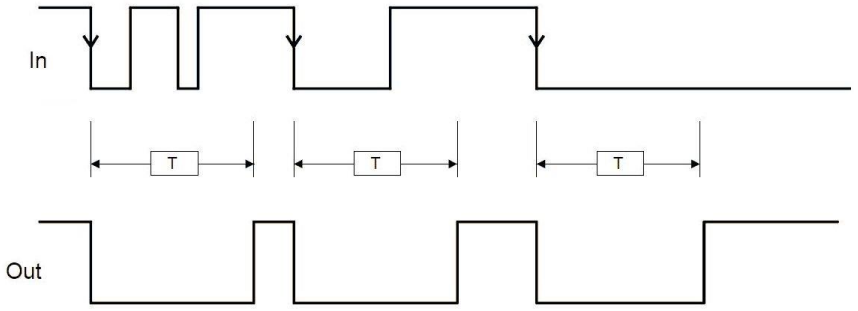
Rising edge:

- If selected provides a level 1 (TRUE) in the OUT output if a **rising edge** is detected on the IN input.
- If not selected the logic is inverted, the OUT output is set to 0 (FALSE) on the IN signal's falling edge, where it remains for the set time.

➔ Unlike the MONOSTABLE operator, the Out output of MONOSTABLE_B does not maintain a level 1 (TRUE) for a time which exceeds the set period *t*.



Rising edge

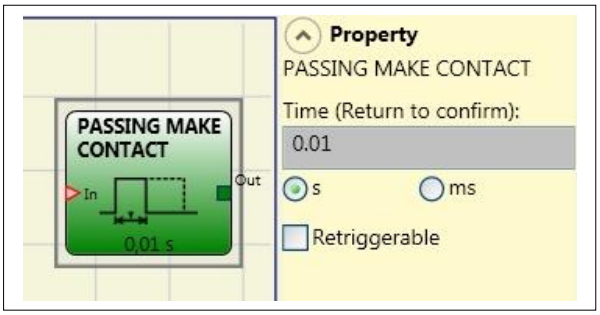


Falling edge

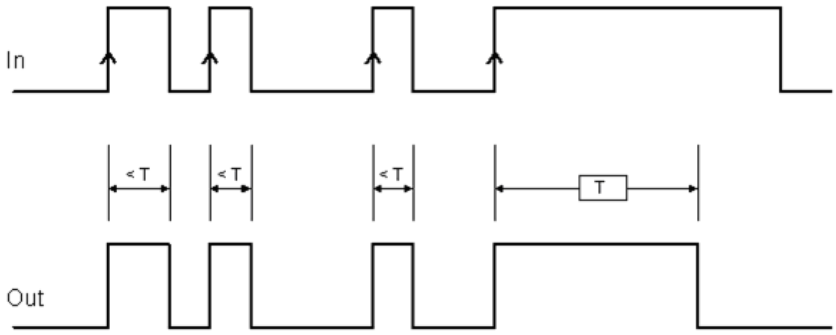
Retriggerable: If selected the time is reset each time the input status changes.

PASSING MAKE CONTACT

In the PASSING MAKE CONTACT operator the output follows the signal on the input. However, if this is 1 (TRUE) for longer than the set time, the output changes to 0 (FALSE). When there is an input falling edge, the timer is cleared.



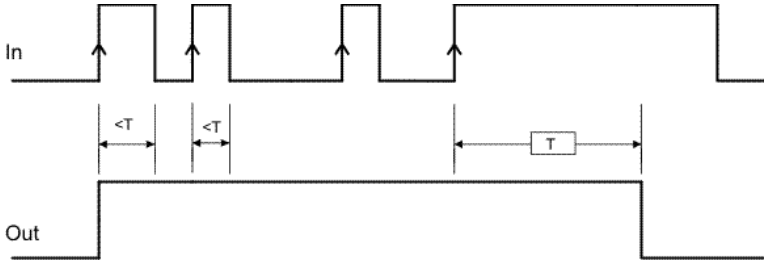
English



Parameters

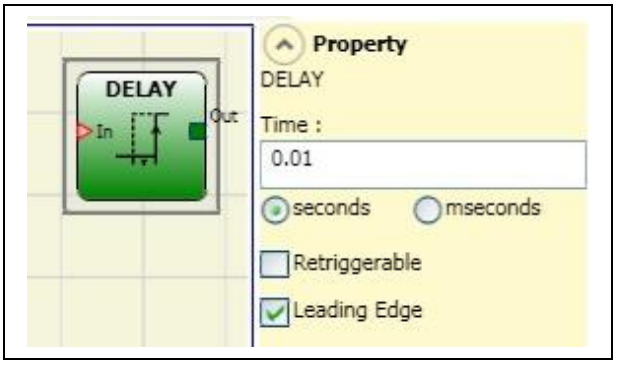
Time: The delay can be set to between **10 ms and 1098.3 s**.

Retriggerable: If selected the time is not reset when there is an input falling edge. The output stays 1 (TRUE) for all the selected time. When there is a new input rising edge, the timer restart again.



DELAY

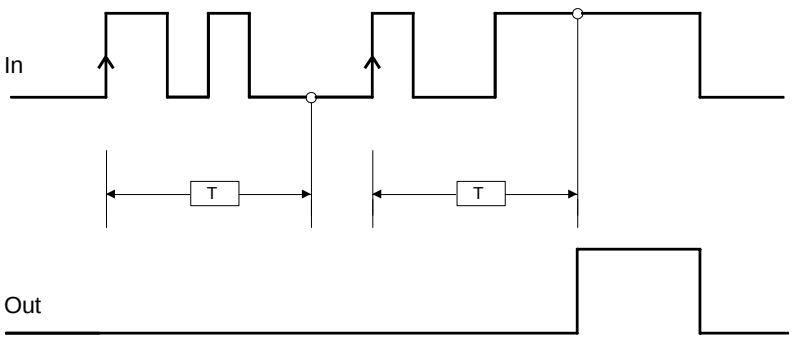
DELAY operator applies a delay to a signal by setting the output to 1 (TRUE) after the set time, against a change in the level of the input signal.



Parameters

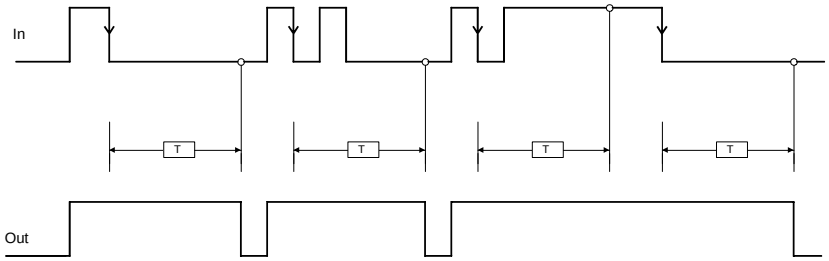
Time: The delay can be set to between **10 ms and 1098.3 s.**

Rising edge: If selected, the delay starts on the input signal's rising edge at the end of which the output changes to 1 (TRUE) if the input is 1 (TRUE) where it remains for as long as the input stays at 1 (TRUE).



English

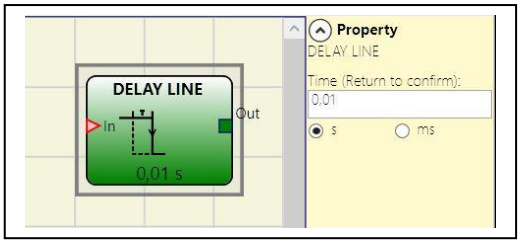
If not selected the logic is inverted, the output is set to 1 (TRUE) on the input signal's rising edge, the delay starts on the input signal's falling edge, at the end of the set time the output changes to 0 (FALSE) if the input is 0 (FALSE) otherwise it remains 1 TRUE.



Retriggerable: If selected the time is reset each time the input status changes.

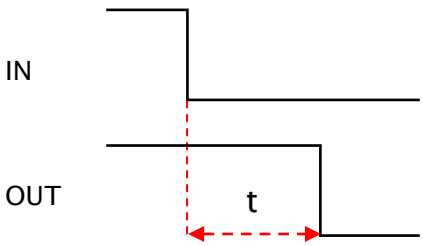
DELAY LINE

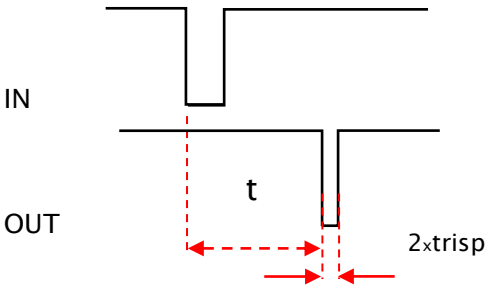
This operator applies a delay to a signal by setting the OUT output to 0 after the set time, set at a falling edge of the IN signal.
If IN returns to 1 before the end of the set time, the OUT output still generates an LL0 impulse lasting approximately twice the response time and delayed by the set time.



Parameters

Time: Enables the insertion of the desired delay time by selecting the preferred unit of measurement. The delay can be set to between 10 ms and 1098.3 s.





➔ Unlike the DELAY operator, the DELAY LINE operator does not filter any interruptions in the IN input which are shorter than the set time.

➔ This operator is recommended when using delayed OSSD (the OSSD must be programmed with RESTART MANUAL).

English

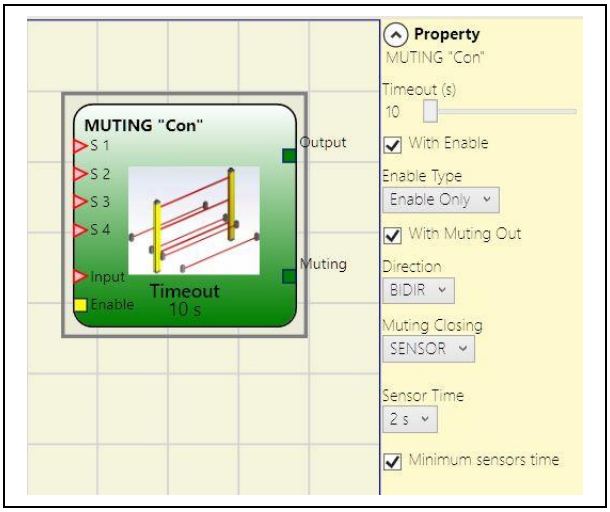
MUTING FUNCTION

The Muting function generates a temporary, automatic interruption of safety device operation in order to permit normal transit of material through the guarded opening.
In other words, when the system recognizes the material and distinguishes between this and any operator (in a potentially dangerous situation), it is enabled to bypass the safety device temporarily, allowing the material to pass through the guarded opening.

MUTING OPERATORS (max number = 4)

"Concurrent" MUTING

The activation of the Muting function occurs following interruption of the sensors S1 and S2 beam (the order does not matter) within a time range from 2s and 5s decided by the operator (or S3 and S4 with material that is moving in the direction opposite).



The MUTING operator with "Concurrent" logic performs muting of the input signal through sensor inputs S1, S2, S3 and S4.

➔ Preliminary condition: The Muting cycle can only start if all the sensors are 0 (FALSE) and inputs are 1 (TRUE) (barrier free).

Parameters

Timeout (sec): Sets the time, between 10 secs and unlimited, within which the Muting cycle must end. If the cycle is not complete at the end of this time, Muting is immediately discontinued.

Enable: If selected it enables the possibility of enabling or not enabling the Muting function. Otherwise the Muting function is always enabled.
There are two Enable modes: Enable/Disable and Enable Only. If Enable/Disable is selected the Muting cycle cannot start if Enable is fixed at 1 (TRUE) or 0 (FALSE) but is only activated with a rising edge. To disable muting, set Enable to 0 (FALSE). In this mode the falling edge disables Muting regardless of the condition. If Enable Only is selected Muting cannot be disabled but Enable must be set to 0 (FALSE) in order to enable a new rising edge for the next Muting cycle.

Direction: The order in which the sensors are occupied can be set. If set to BIDIR they can be occupied in both directions, from S1&S2 to S3&S4 and from S3&S4 to S1&S2, if set to UP they can be occupied from S1&S2 to S3&S4 and if set to DOWN from S3&S4 to S1&S2.

Muting Close: There are two types, CURTAIN and SENSOR. If you select CURTAIN muting closes when the input signal rises, if you select SENSOR it closes when the third sensor has been cleared.

English

Select CURTAIN

S1	S2	Input	S3	S4	Muting	
0	0	1	0	0	0	
1	0	1	0	0	0	
1	1	1	0	0	1	Muting active
1	1	X	0	0	1	
1	1	X	1	1	1	
0	0	0	1	1	1	
0	0	1	1	1	0	
0	0	1	0	0	0	

Select SENSOR

S1	S2	Input	S3	S4	Muting	
0	0	1	0	0	0	
1	0	1	0	0	0	
1	1	1	0	0	1	Muting active
1	1	X	0	0	1	
1	1	X	1	1	1	
0	0	0	1	1	1	
0	0	1	1	1	1	
0	0	1	0	1	0	
0	0	1	0	0	0	

Blind Time: ***Only with Muting Close=Curtain***, *blind time* is enabled if you know that after the complete transition of the pallet (muting cycle close) some protruding objects could still occupy the light curtain and send the input to 0 (FALSE). During blind time the input remains 1 (TRUE). Blind Time can range from 250 msecs to 1 second.

Sensors Time: Sets the ***maximum time*** (between 2 and 5 seconds) between activating two muting sensors.

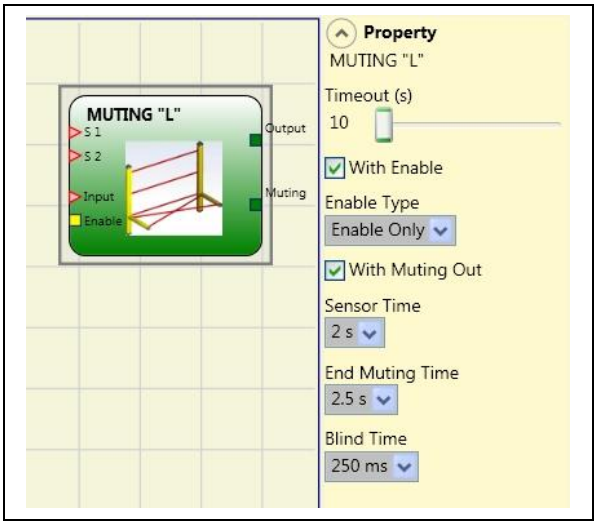
Minimum sensors time: If selected, allows the activation of Muting cycle only if a time ≥150ms elaps between the activation of the sensor 1 and sensor 2 (or sensor 4 and 3).

MUTING "L"

The activation of the Muting function occurs following interruption of the sensors S1 and S2 beam (the order does not matter) within a time range from 2s and 5s decided by the operator.
The state of the Muting ends after the liberation of the guarded opening.

The MUTING operator with "L" logic performs muting of the input signal through sensor inputs S1 and S2.

➔ Preliminary condition: The Muting cycle can only start if S1 and S2 are 0 (FALSE) and the inputs are 1 (TRUE) (barrier free).



Parameters

Timeout (sec): Sets the time, between 10 secs and unlimited, within which the Muting cycle must end. If the cycle is not complete at the end of this time, Muting is immediately discontinued.

Enable: If selected it enables the possibility of enabling or not enabling the Muting function. Otherwise the Muting function is always enabled.

English

There are two Enable modes: Enable/Disable and Enable Only. If Enable/Disable is selected the Muting cycle cannot start if Enable is fixed at 1 (TRUE) or 0 (FALSE) but is only activated with a rising edge. To disable muting, set Enable to 0 (FALSE). In this mode the falling edge disables Muting regardless of the condition. If Enable Only is selected Muting cannot be disabled but Enable must be set to 0 (FALSE) in order to enable a new rising edge for the next Muting cycle.

Sensors Time: Sets the ***maximum time*** (between 2 and 5 seconds) between activating two muting sensors.

End of Muting time: sets the maximum time (from 2.5 to 6 seconds) that must elapse between the release of the first sensor and the release of guarded opening. The end of this time determines the end of the Muting function.

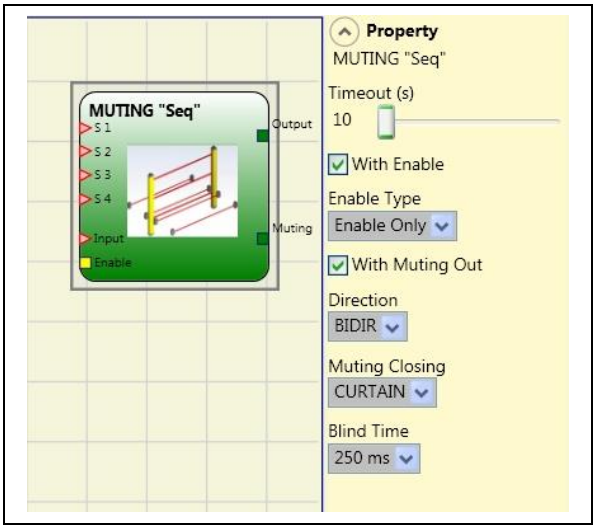
Blind Time: enabled if you know that after the complete transition of the pallet (muting cycle close) some protruding objects could still occupy the light curtain and send the input to 0 (FALSE). During blind time the input remains 1 (TRUE). Blind Time can range from 250 msecs to 1 second.

"Sequential" MUTING

The activation of the Muting function occurs following sequential interruption of the sensors S1 and S2, subsequently S3 and S4 sensors (without time limit). If the pallet proceeds in the opposite direction the correct sequence is: S4, S3, S2, S1.

The MUTING operator with "Sequential" logic performs muting of the input signal through sensor inputs S1, S2, S3 and S4.

➔ Preliminary condition: The Muting cycle can only start if all the sensors are 0 (FALSE) and the inputs are 1 (TRUE) (barrier free).



Parameters

Timeout (sec): Sets the time, between 10 secs and unlimited, within which the Muting cycle must end. If the cycle is not complete at the end of this time, Muting is immediately discontinued.

Enable: If selected it enables the possibility of enabling or not enabling the Muting function. Otherwise the Muting function is always enabled.
There are two Enable modes: Enable/Disable and Enable Only. If Enable/Disable is selected the Muting cycle cannot start if Enable is fixed at 1 (TRUE) or 0 (FALSE) but is only activated with a rising edge. To disable muting, set Enable to 0 (FALSE). In this mode the falling edge disables Muting regardless of the condition. If Enable Only is selected Muting cannot be disabled but Enable must be set to 0 (FALSE) in order to enable a new rising edge for the next Muting cycle.

Direction: The order in which the sensors are occupied can be set. If set to BIDIR they can be occupied in both directions, from S1 to S4 and from S4 to S1, if set to UP they can be occupied from S1 to S4 and if set to DOWN from S4 to S1.

English

Muting Close: There are two types, CURTAIN and SENSOR. If you select CURTAIN muting closes when the input signal rises, if you select SENSOR it closes when the third sensor has been cleared.

Select CURTAIN

S1	S2	Input	S3	S4	Muting	
0	0	1	0	0	0	
1	0	1	0	0	0	
1	1	1	0	0	1	Muting active
1	1	X	0	0	1	
1	1	X	1	0	1	
1	1	X	1	1	1	
0	1	X	1	1	1	
0	0	0	1	1	1	
0	0	1	1	1	0	
0	0	1	0	1	0	
0	0	1	0	0	0	

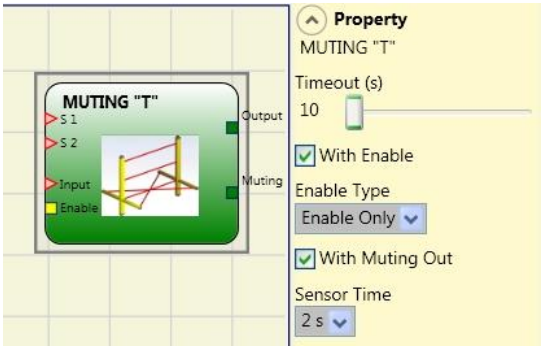
Select SENSOR

S1	S2	Input	S3	S4	Muting	
0	0	1	0	0	0	
1	0	1	0	0	0	
1	1	1	0	0	1	Muting active
1	1	X	0	0	1	
1	1	X	1	0	1	
1	1	X	1	1	1	
0	1	X	1	1	1	
0	0	0	1	1	1	
0	0	1	1	1	1	
0	0	1	0	1	0	
0	0	1	0	0	0	

Blind Time: ***Only with Muting Close=Curtain***, *blind time* is enabled if you know that after the complete transition of the pallet (muting cycle close) some protruding objects could still occupy the light curtain and send the input to 0 (FALSE). During blind time the input remains 1 (TRUE). Blind Time can range from 250 msecs to 1 second.

MUTING "T"

The activation of the Muting function occurs following interruption of the sensors S1 and S2 beam (the order does not matter) within a time range from 2s and 5s decided by the operator.
The state of the Muting ends after the liberation of at least one of the two sensors.



The MUTING operator with "T" logic performs muting of the input signal through sensor inputs S1 and S2.

➔ Preliminary condition: The Muting cycle can only start if S1 and S2 are 0 (FALSE) and the inputs are 1 (TRUE) (barrier free).

English

Parameters

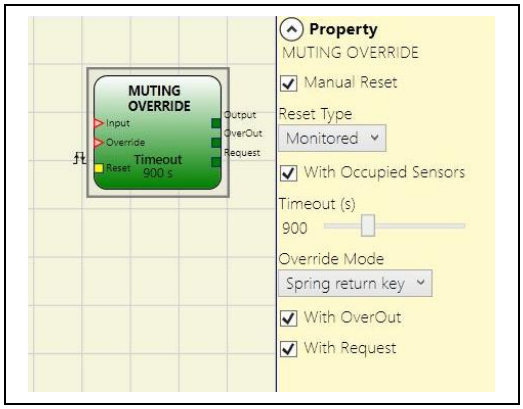
Timeout (sec): Sets the time, between 10 secs and unlimited, within which the Muting cycle must end. If the cycle is not complete at the end of this time, Muting is immediately discontinued.

Enable: If selected it enables the possibility of enabling or not enabling the Muting function. Otherwise the Muting function is always enabled.
There are two Enable modes: Enable/Disable and Enable Only. If Enable/Disable is selected the Muting cycle cannot start if Enable is fixed at 1 (TRUE) or 0 (FALSE) but is only activated with a rising edge. To disable muting, set Enable to 0 (FALSE). In this mode the falling edge disables Muting regardless of the condition. If Enable Only is selected Muting cannot be disabled but Enable must be set to 0 (FALSE) in order to enable a new rising edge for the next Muting cycle.

Sensors Time: Sets the ***maximum time*** (between 2 and 5 seconds) between activating two muting sensors.

MUTING OVERRIDE (max number = 4)

The OVERRIDE function must be used when the machine stops due to incorrect Muting activation sequences with the material obstructing the guarded opening.
This function activates the OSSD outputs making it possible to remove the material that is obstructing the guarded opening.



The operator must be connected after the Muting operator (Muting OUTPUT directly to the Override INPUT).
The operator permits override of the directly connected Muting Input.
Override can be activated only if Muting is not active (INPUT=0) and at least one Muting sensor is occupied (or the light curtain is occupied).
Override ends when the light curtain and sensors are cleared and the OverOut switches to logical "0" (FALSE).
Override can be set to pulsed or maintained action mode.

Override with maintained action control.

This function must be activated maintaining the Override command active (OVERRIDE=1) during all subsequent operations. However, a new Override can be activated, de-activating ad re-activating the command.

When the light curtain and sensors are cleared (gap free) or on expiry of the timeout, Override ends without the need for further commands.

Override with pulsed action

This function is enabled activating the Override command (OVERRIDE=1).

Override ends when the light curtain and sensors are cleared (gap free) or on expiry of the timeout. The function can be restarted only if the Override command is re-activated (OVERRIDE=1).

Parameters

With sensors occupied: Must be selected with "T" sequential, simultaneous muting; with "L" muting, must not be selected.

English

➔ Otherwise, a Warning is displayed in the compilation phase and in the report.

➔ The user must adopt additional safety measures during the Override phase.

Conditions to be checked for activation of Override

"With sensors occupied " selected	sensor occupied	light curtain occupied	Input	Override request	Override output
X	X	-	0	1	1
-	-	X	0	1	1
	X	-	0	1	1
	X	X	0	1	1

Timeout (sec): Used to set the time, between 10 sec and infinity, by which the Override function must end.

Override mode: Used to configure the type of Override (pulsed or maintained action).

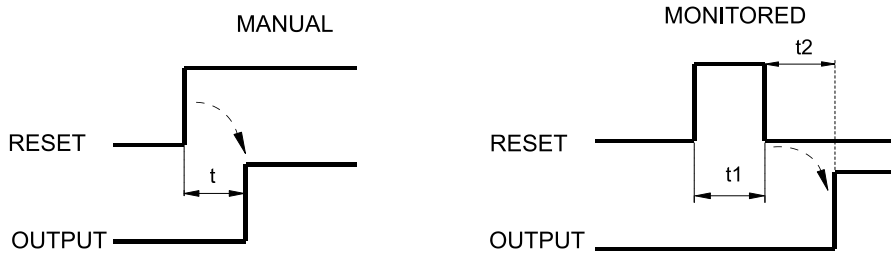
With OverOut: Used to activate an Override active Signaling output (active when high).

With Request: Used to activate a Signaling output (active when high) indicating that the Override function can be activated.

Manual Reset:

- Should the INPUT be active (TRUE), the reset enables the output of the function block.
- Should the INPUT be not active (FALSE), the output of the function block follows the OVERRIDE request.

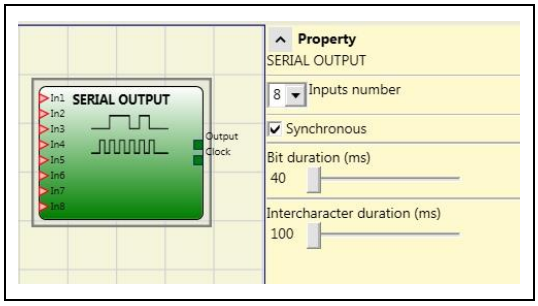
There are two types of reset: Manual and Monitored. When Manual is selected the system only verifies the signal's transition from 0 to 1. If Monitored is selected the double transition from 0 to 1 and then back to 0 is verified.



English

MISCELLANEOUS FUNCTION BLOCKS

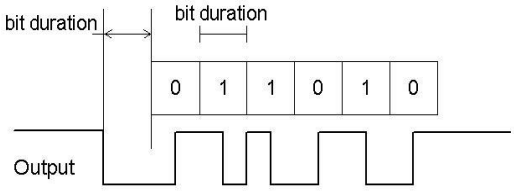
SERIAL OUTPUT (max number = 4)



The **Serial Output** operator outputs the status of up to 8 inputs, serialising the information.

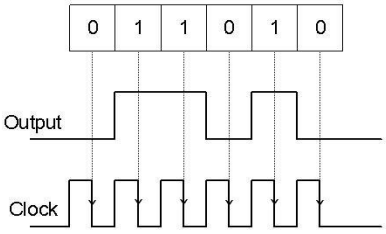
Operating principles.
This operator outputs the status of all the connected inputs in two different ways:

Asynchronous serialisation:
1) The status of the line in the idle condition is 1 (TRUE);
2) The start data transmission signal is 1 bit = (FASLE);
3) Transmission of *n* bits with the status of the connected inputs encoded using the *Manchester* method:
   - Status 0: rising edge of the signal at the centre of the bit
   - Status 1: falling edge of the signal at the centre of the bit
4) Intercharacter interval is 1 (TRUE) to allow synchronisation of an external device.



Therefore, with the Asynchronous method the *Clock* output is not present.

Synchronous serialisation:
1) The output and the clock in the idle condition are 0 (FASLE);
2) Transmission of *n* bits with the input status using OUTPUT as data, CLOCK as the timing base;
3) Intercharacter interval is 0 (FALSE) to allow synchronisation of an external device.



Parameters

Number of inputs: Defines the number of inputs of the function block, which may be 2÷8 *(asynchronous) or 3÷8 (synchronous).*

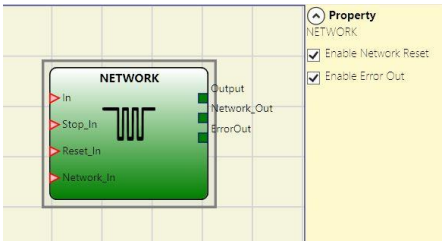
Bit length (ms): Enter the value corresponding to the length of each single bit (input n) in the pulse train that makes up the transmission.
- 40 ms ÷ 200 ms (Step 10 ms)
- 250 ms ÷ 0.95 s (Step 50 ms)

Intercharacter interval (ms): Enter the time that must pass between the transmission of one pulse train and the next.
- 100 ms ÷ 2.5 s (Step 100 ms)
- 3 s ÷ 6 s (Step 500 ms)

English

NETWORK (max number = 1)

The **Network** operator is used to distribute Stop and Reset commands via a simple local network. Use **Network_in** and **Network_out** to exchange *START*, *STOP* and *RUN* signals between the different nodes.



Operating principles.
This operator allows stop and reset commands to be distributed simply in a local Mosaic network.

The Network operator requires the following:

1) the **Network_In** input connected to a single or double input must be connected to the **Network_Out** output of the preceding unit in the local network.
2) the **Network_Out** output connected to a STATUS signal or OSSD output, must be connected to the **Network_in** input of the next unit in the local network.
3) the **Stop_In** and **Reset_In** inputs must be connected to input devices that act as Stop (e.g. E-STOP) and Reset (e.g. SWITCH), respectively.
4) the **In** input can be connected freely in the diagram (e.g. input function blocks or results of logical combinations).
5) **Output** can be connected freely in the diagram. **Output** is 1 (TRUE) when the IN input is 1 (TRUE) and the function block has been restarted.

Parameters

Enable Reset Network: when selected this allows the distribution network to reset the function block. If not enabled, the function block can only be reset via the local **Reset_In** input.

Enable error out: if selected this enables the presence of the **Error_Out** status signal.

The RESET commands must be installed outside all the danger areas of the network in positions where the danger areas and the entire work areas are clearly visible.

➔ The maximum number of MASTER modules that can be connected in network configuration is equal to 10.

➔ Each Master module can have a maximum of 9 expansion modules connected.

Condition 1:
With reference to the Figure 66 and Figure 67, at power-on:

1. *The Net_out of the various nodes are in the 0 (FALSE) condition;*
2. *The STOP signal is sent via the Net_out line;*
3. When the RESET command is pressed on one of the nodes *all the nodes that are present are started when the START signal is sent*;
4. *As the end result, the Net_out of all the connected nodes is in condition 1 (TRUE) if the various Net_in inputs are in condition 1 (TRUE);*
5. *The RUN signal is sent via the network of the 4 nodes present.*

Condition 2:
With reference to the Figure 66 and Figure 67, when the emergency stop is pressed in one of the four nodes:

1. *The Net_out moves to condition 0 (FALSE);*
2. *The STOP signal is sent via the Net_out line;*
3. *The next node receives the stop code and deactivates the output;*
4. *The stop command generates the stop code for all Net_in and Net_out lines;*
5. *As the end result, the Net_out of all the connected nodes is in condition 0 (FALSE).*
6. *When the emergency stop is restored to the normal position, all the nodes can be restarted by sending the START signal with a single reset. The latter condition does not occur when ENABLE RESET NETWORK is not enabled. In that case, the local reset method must be used. The system will employ about 4s to restore all the outputs of the blocks that make up the network.*

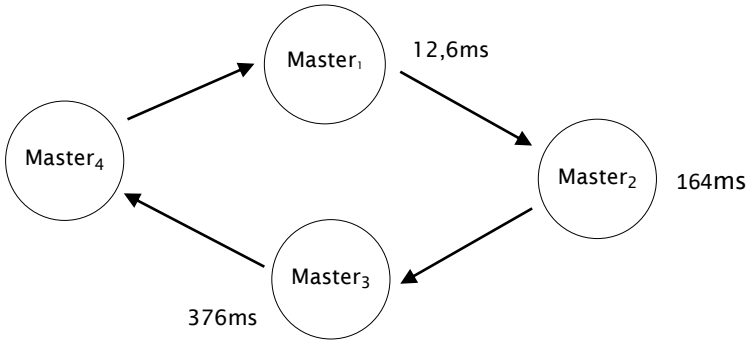
English

Response Time
The max response time of the network starting from emergency stop is given by the formula:

$$t_r = [(212\ ms \times n^{\circ}Master) - 260ms]$$

The max number of connected Master must be 10.

Emergency Stop Pressing	MASTER n°1	MASTER n°2	MASTER n°3	MASTER n°4
	$t_{rMASTER1}$	$t_{rMASTER2}$	$t_{rMASTER3}$	$t_{rMASTER4}$
	12,6ms	164ms	376ms	488ms



Condition 3:
With reference to the Figure 64 and Figure 65, when the IN input of the NETWORK function block of one of the 4 nodes moves to condition 0 (FALSE):

1. *The local OUTPUT moves to condition 0 (FALSE);*
2. *The RUN signal continues to be sent via the Network_out lines;*
3. *The states of the remaining nodes remain unchanged;*
4. *In that case, local reset must be used. The Reset-in LED flashes to indicate this condition. This condition is signaled by the corresponding LED flashing Reset_In entrance.*
   The affected node will be restarted with its own reset.

The **Reset_in** and **Network_in** inputs and the **Network_out** output can only be mapped to the I/O pins of the MASTER.

Master M1 signals with Network operative

		NETWORK FUNCTIONAL BLOCK SIGNALS				
		Network in		Network out (OSSD)	Network out (STATUS)	Reset in
	LED	FAIL EXT	IN (1)	OSSD (2)	STATUS	IN (3)
STATUS	STOP	OFF	OFF	RED	OFF	OFF
	CLEAR	OFF	BLINKING	RED/GREEN (BLINKING)	BLINKING	BLINKING
	RUN	OFF	ON	GREEN	ON	ON
	FAIL	ON	BLINKING	-	-	-

(1) Corresponding to the input where is wired Network IN
(2) Corresponding to the input where is wired Network OUT
(3) Corresponding to the input where is wired Reset IN

English

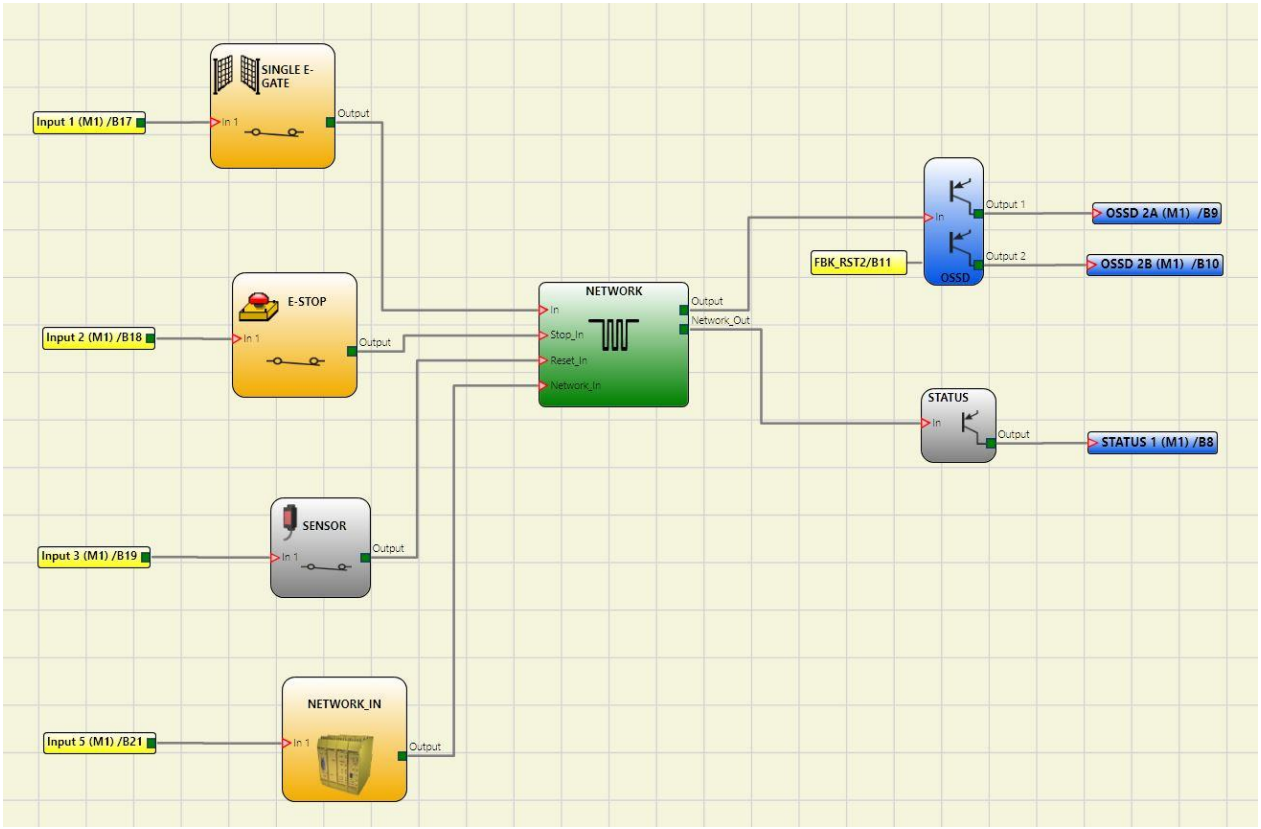


Figure 64 - NETWORK function block scheme example (Category 2)

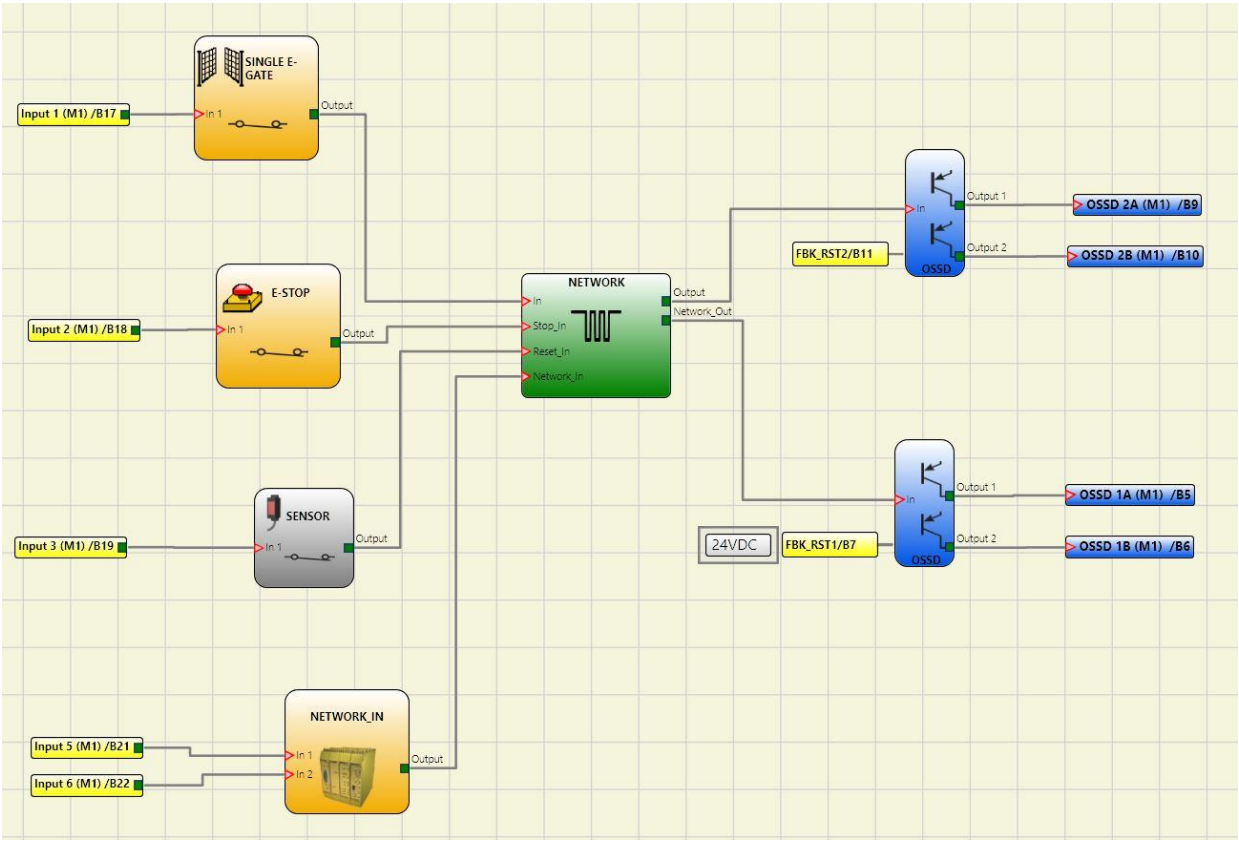
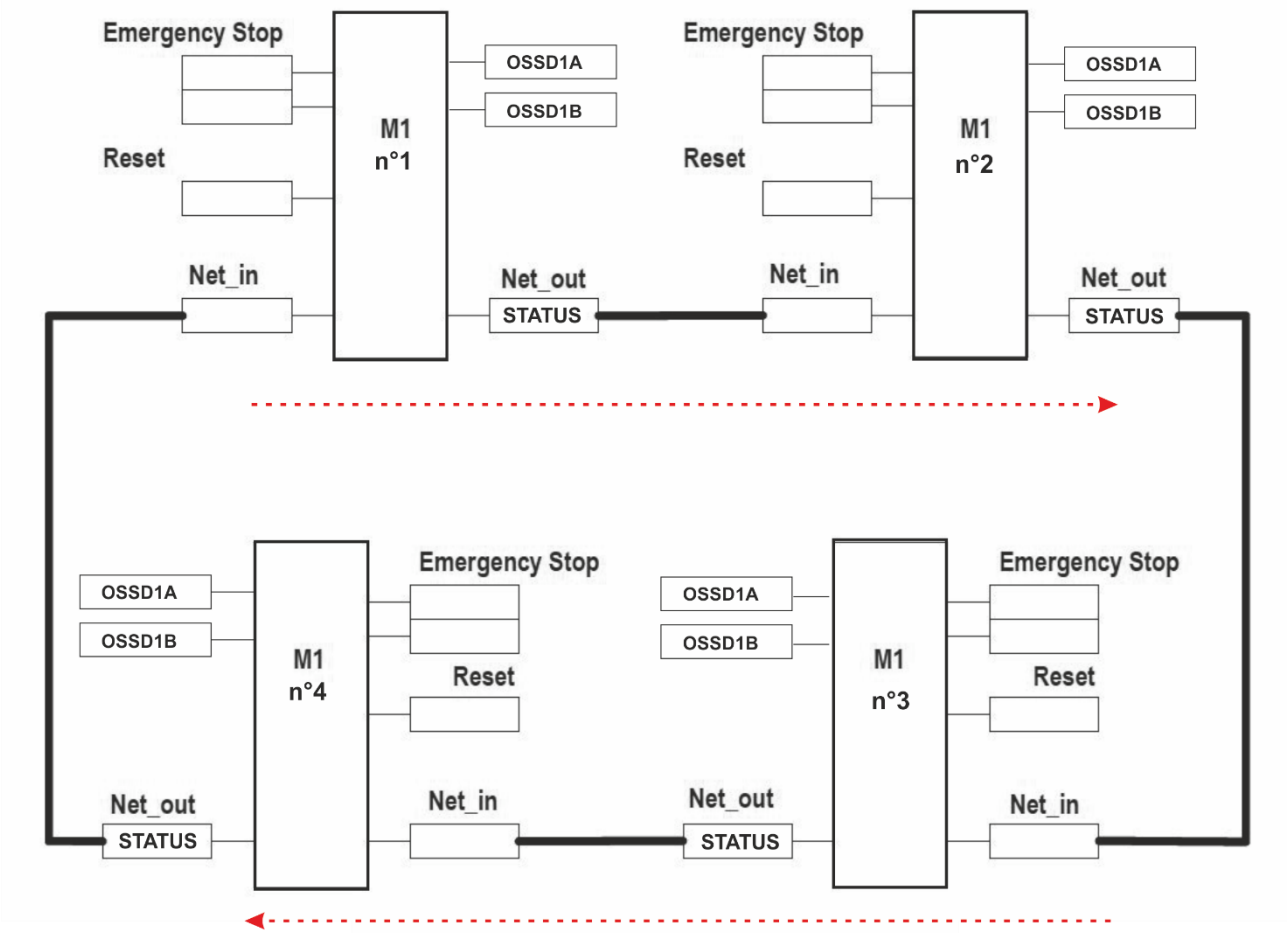


Figure 65 - NETWORK function block scheme example (Category 4)

English

Example of application in Category 2 according to ISO 13849-1:



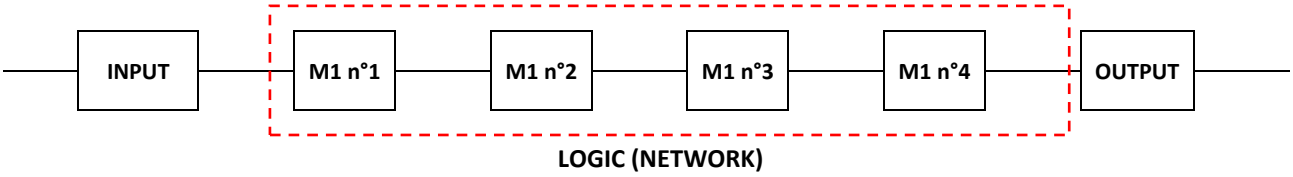
Network data flow

Figure 66

Network parameters for the PL calculation

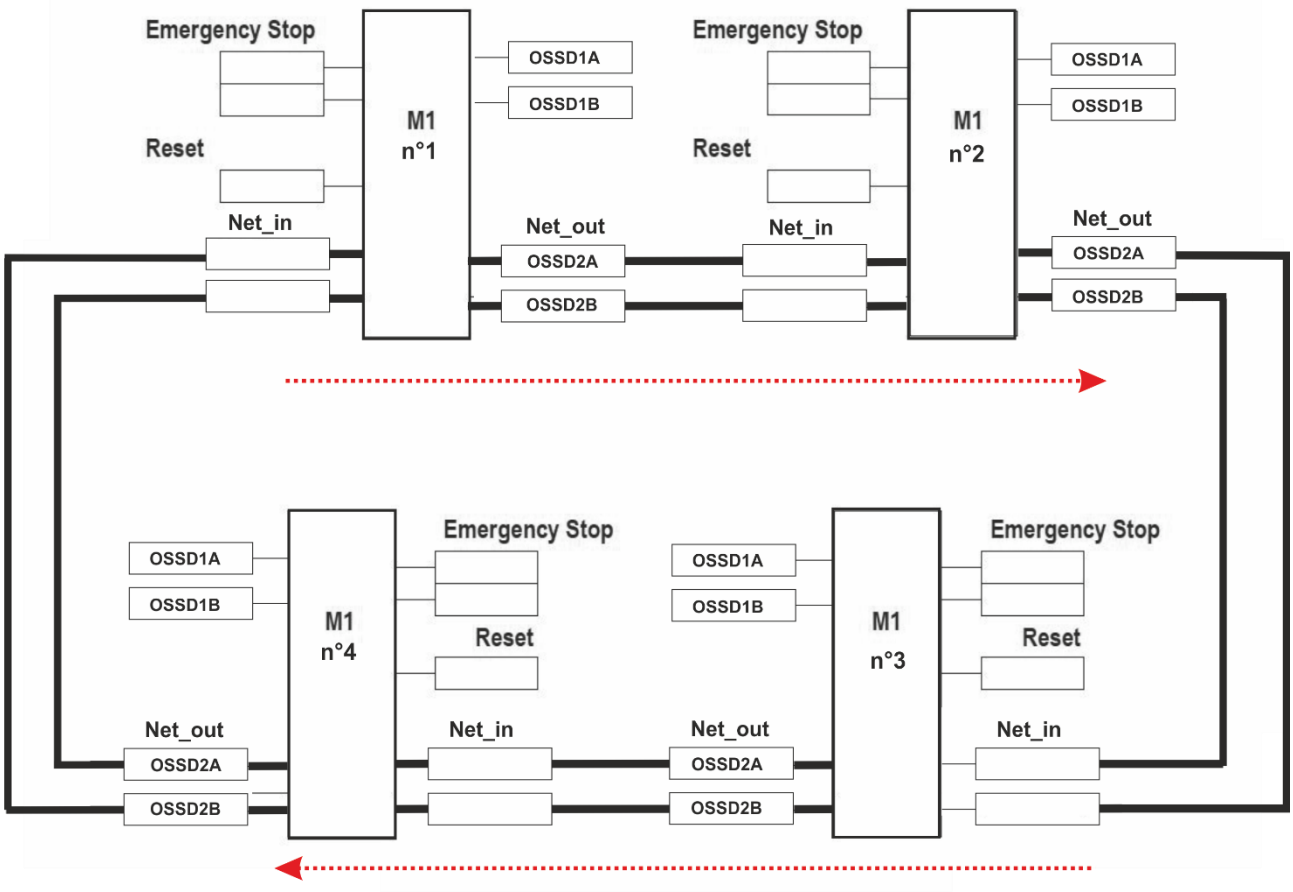
Architecture:	Cat.2
Diagnostic coverage:	DC = 90%
Reliability of Module M1:	$MTTF_d$ = 437 *(years)*

Logical block diagram of a safety function using the network



Example of application in Category 4 according to ISO 13849-1:

English



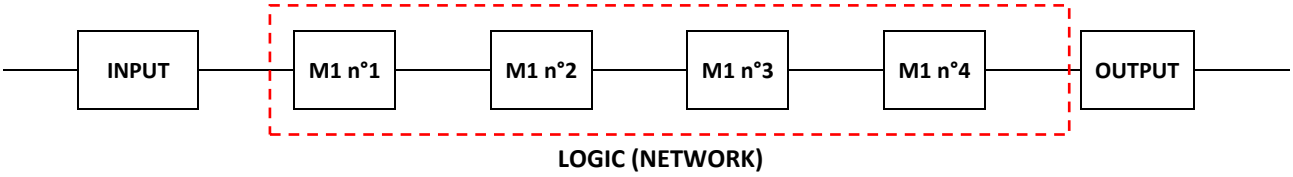
Network data flow

Figure 67

Network parameters for the PL calculation

Architecture:	Cat.4
Diagnostic coverage:	DC = 99%
PFH Module M1:	PFHd = 6,86E-09 *(hour^{-1})*

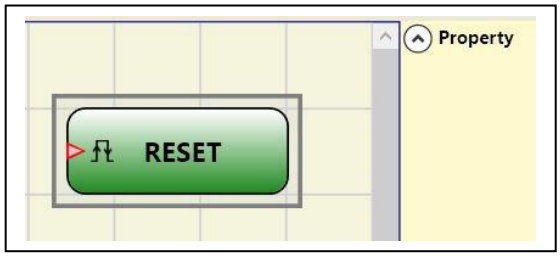
Logical block diagram of a safety function using the network

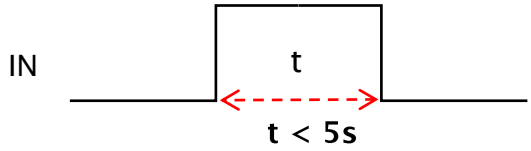


English

RESET M1

This operator generates a system Reset when there is a double OFF-ON-OFF transition on the corresponding input which lasts less than 5 s.





➔ If > 5s, RESET is not generated.

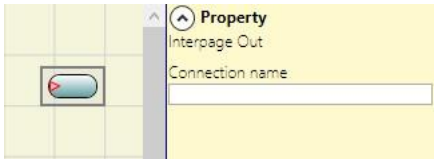
➔ It can be used to reset faults without disconnecting system power.

INTERPAGE IN/OUT

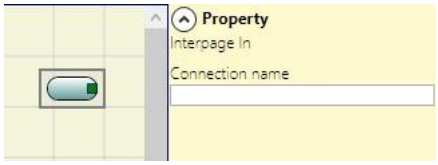
If the scheme is very complicated and requires a connection between two elements very far, use the "Interpage" component.

INTERPAGE OUT

(scheme side SX)



INTERPAGE IN



(scheme side SX)

The element "*Interpage out*" must have a name which, invoked by the corresponding "*Interpage in*", allows the desired link.

TERMINATOR

This operator can be connected to Input block OUTPUT only to allow this Input to be inserted without schematic connections.

The Input connected to Terminator appears in the Input map list and it's state is transferred to BUS.

English

SPECIAL APPLICATIONS

Output delay with manual

If the operator needs to have two OSSD output with one of them delayed (in MANUAL mode) use the following scheme:

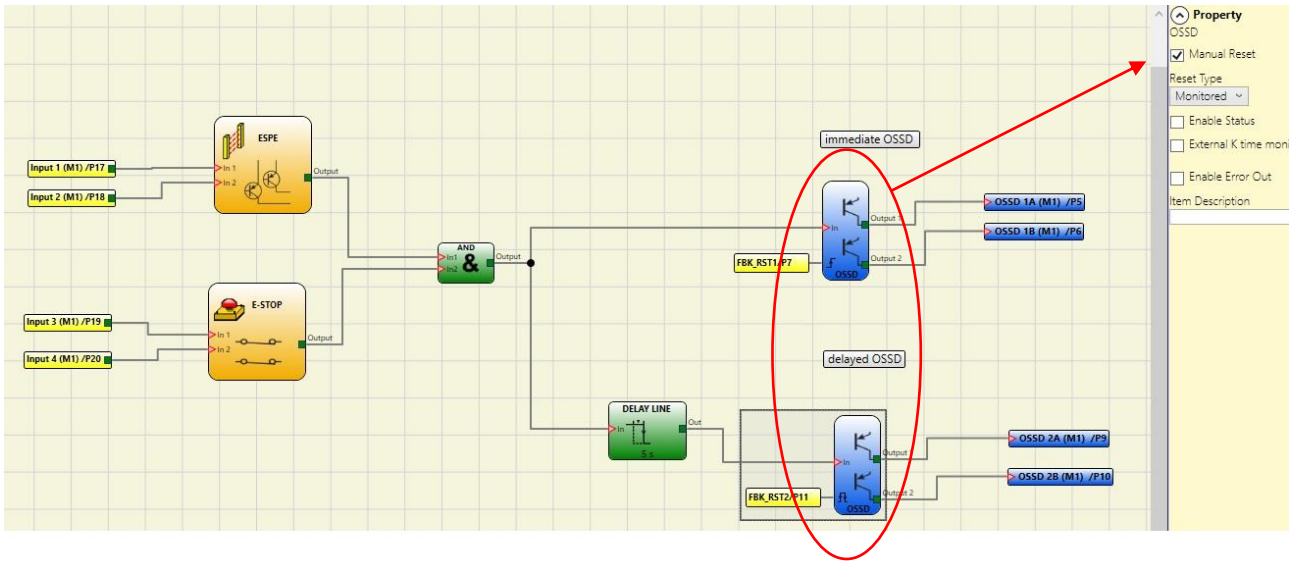


Figure 68 - Two outputs with one delayed (in MANUAL mode)

English

SIMULATOR FEATURE

- This simulator is only designed to assist in the design of safety functions.
- The results of the simulation do not constitute validation of the project.
- The resulting safety function must always be validated, from the point of view of both hardware and software, under actual usage conditions in accordance with the applicable regulations, such as ISO/EN 13849-2: validation or IEC/EN 62061: Chapter 8 - Validation of the safety-related electrical control system.
- Mosaic configuration safety parameters are provided in the MSD software report.

The top toolbar features two new green icons (with firmware M1 version 3.0 or higher):

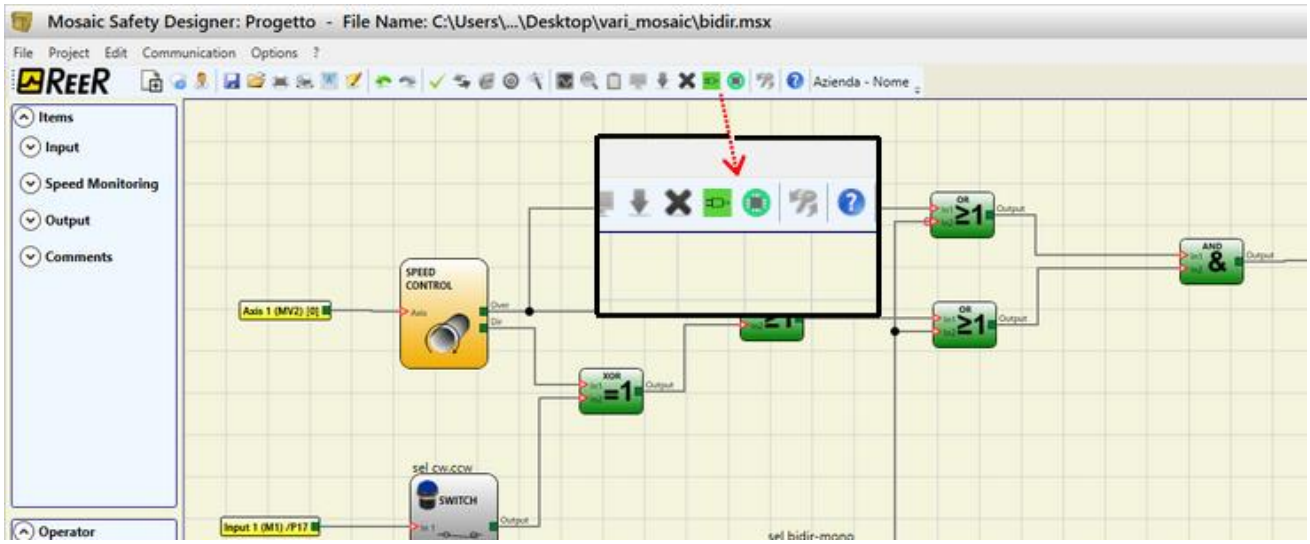


Figure 69 – Simulator icons

These icons refer to the new Simulator function.

- The first icon indicates "Schematic Simulation". It enables the schematic simulator (both static and dynamic) in which you can activate the input to verify the diagram that is loaded.
- The second icon indicates "Graphic Simulation". It enables the simulator guided by the stimuli file which also allows the desired traces to be displayed in a specific graph.

➔ THE SIMULATION ICONS ARE ONLY AVAILABLE WITH NODE M1 DISCONNECTED.

English

Schematic Simulation

Click on the  icon to start the schematic simulation.

Schematic simulation can be used to check/guide the output signals of the various function blocks in real-time, even during the actual simulation. You may choose the block outputs you wish to control and check the response of the various elements of the schematic model according to the colour of the different lines.

As with the monitor function, the colour of the line (or of the actual key) indicates the signal status: green means the signal is set to LL1, red means the signal is set to LL0.

With "Schematic Simulation", some new keys appear in the toolbar. These can be used to control the simulation: the "Play" and "Stop" keys to start and stop the simulation, the "PlayStep" key for step-by-step operation and the "Reset" key. When the simulation is reset, the Time value is reset to 0 ms.
When you press "Play" to start the simulation, the amount of time that has elapsed is displayed next to the word "Time". This time is measured in "Step" units of time multiplied by the user-defined "KT" factor.

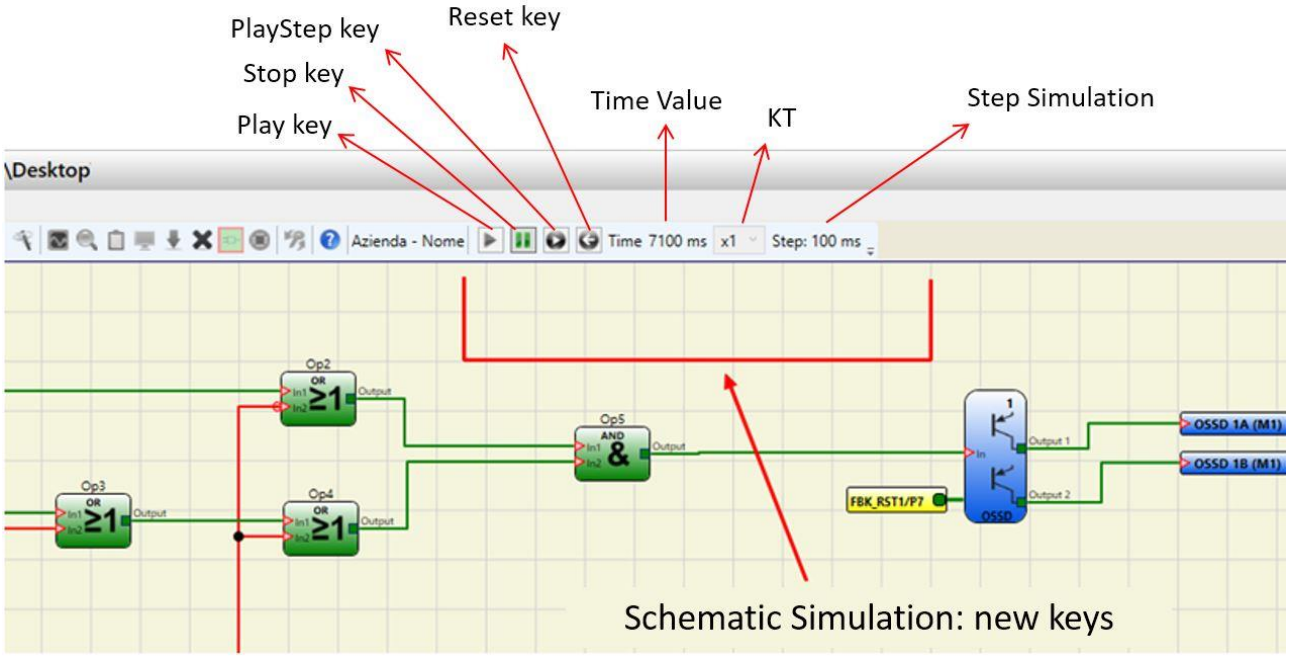
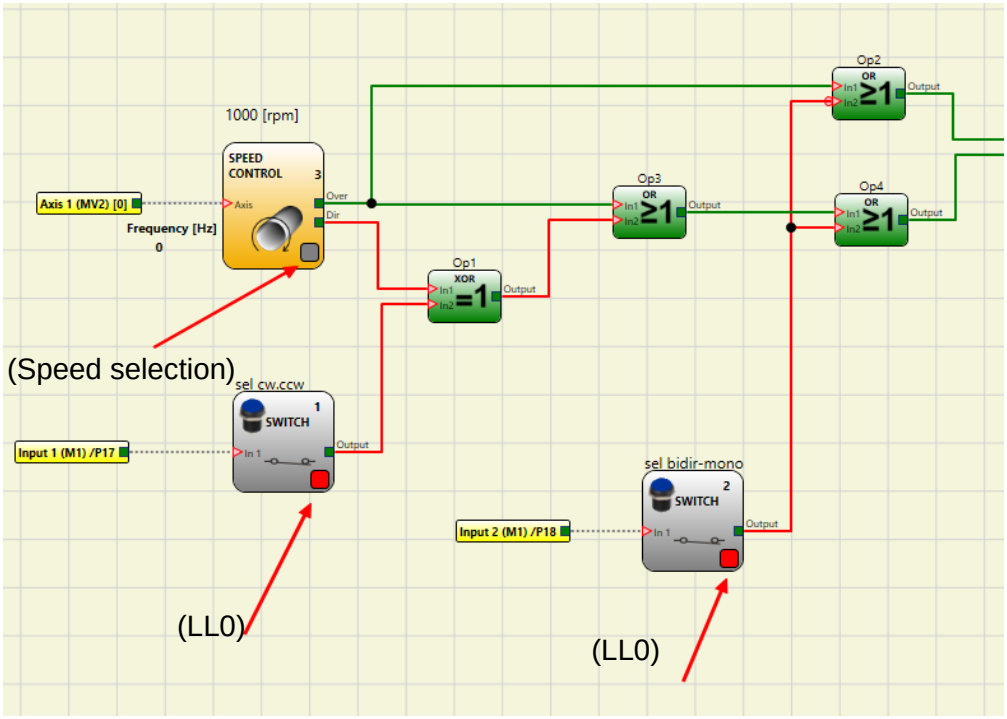


Figure 70 – Schematic Simulation

Click on the bottom right key of each input block to activate the respective output status (even when the simulator is not running, i.e. when the time is not elapsing: in this case the simulation is "static"). If the key turns red when you click on it, the output will be set to level LL0. If it turns green, the output will be set to level LL1.
In some function blocks, such as "speed control" or "lock_feedback", for example, the key is grey. This indicates that the value must be entered manually in a specific pop-up window. The type of value to be entered differs according to the type of function block (e.g., in a "speed control" block you will need to enter the frequency).

English



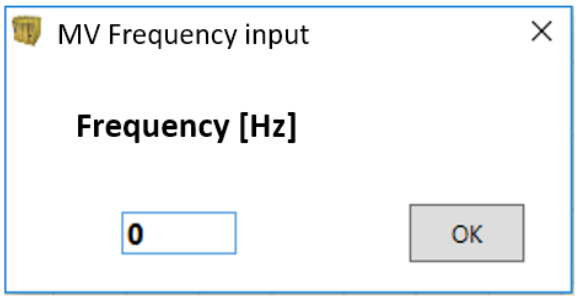


Figure 71 – MV frequency input

➔ The keys for enabling block outputs are shown at the top, an example of a pop-up window for entering, in this case, the frequency in a "speed control" block is shown at the bottom

How to use graphic simulation

Click on the icon to start the graphic simulation.

Graphic simulation can be used to display the signal pattern over time in a graph. First you must define the stimuli in a specific text file: this means defining the trend over time in the waveforms used as inputs (stimuli). Based on the stimuli file created, the simulator injects these into the diagram and displays the traces required in order to perform the simulation.

When the simulation is complete, a graph like the one shown below is automatically displayed. From the graph you can print the traces displayed ("Print"), save the results in order to load them again later (Save) or display other traces ("Change visibility"). The names of the traces match the description of the function blocks.

English

Click the "X" key (top right) to exit the graphic simulation environment.

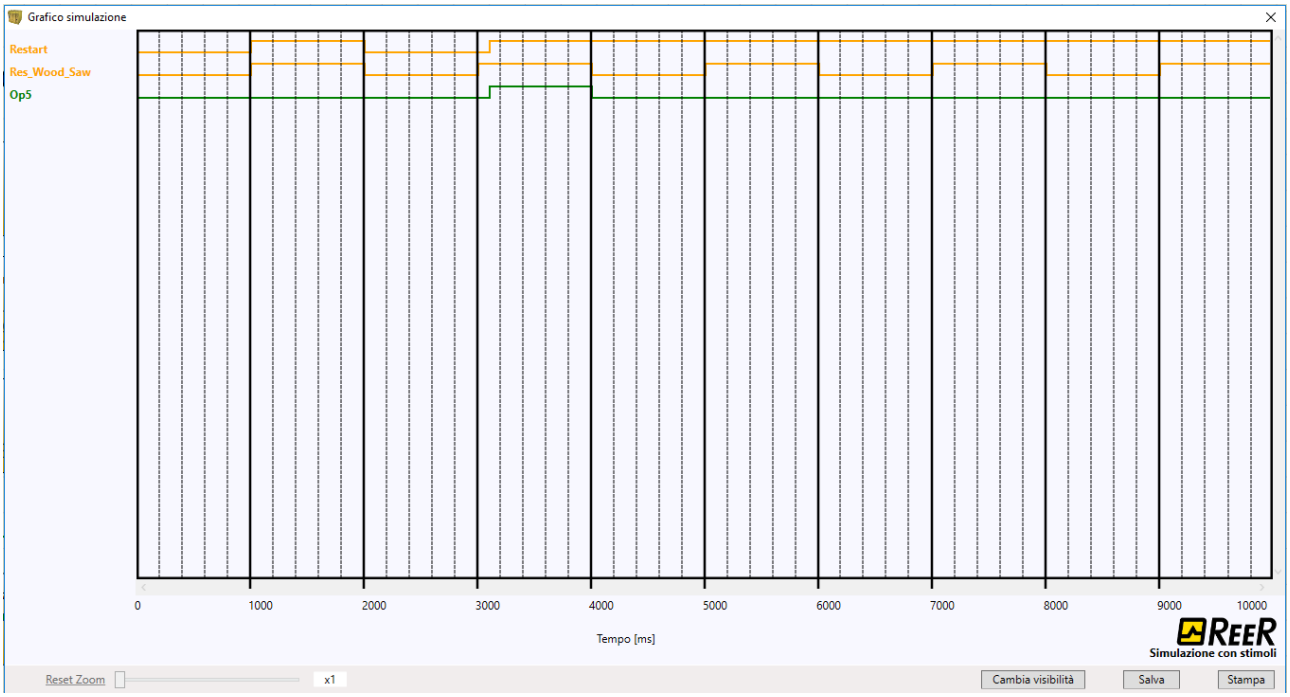


Figure 4 – Example of a result of the graphic simulation.

➔ It shows the traces and the three keys in the bottom right corner for selecting the traces, saving and printing.

The simulation can only be carried out after performing at least the following steps.

1. Create a stimuli file to suit your needs.
2. Upload the stimuli file and wait until the simulation finishes.

Click on the  icon to display the page shown below.

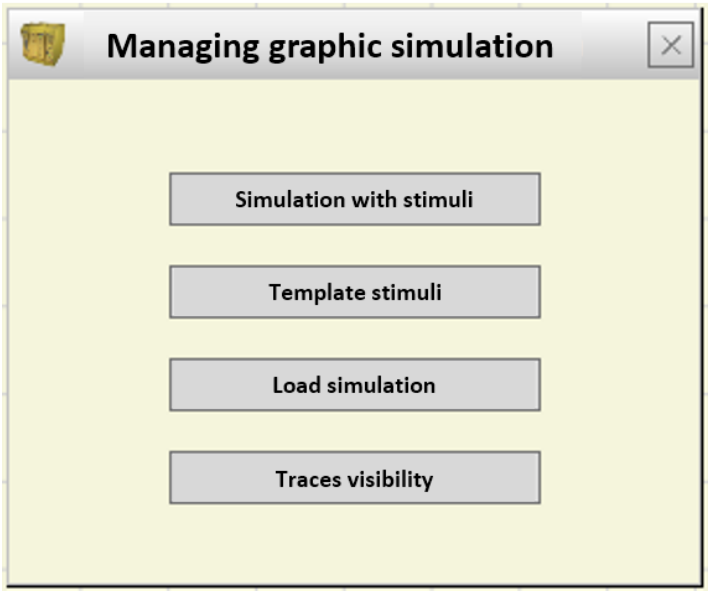


Figure 72 – Menu for selecting the graphic simulation mode

English

The functions of each key in the menu shown in Figure 72 will now be described:

Template Stimuli: used to save the template file with the desired name and disk location. This file will contain the names of the signals as shown in the diagram, Figure 73 Now you may use a text editor to enter the status of the input signals at a given moment in time as well as the duration of the simulation and the time step to be used, Figure 74.

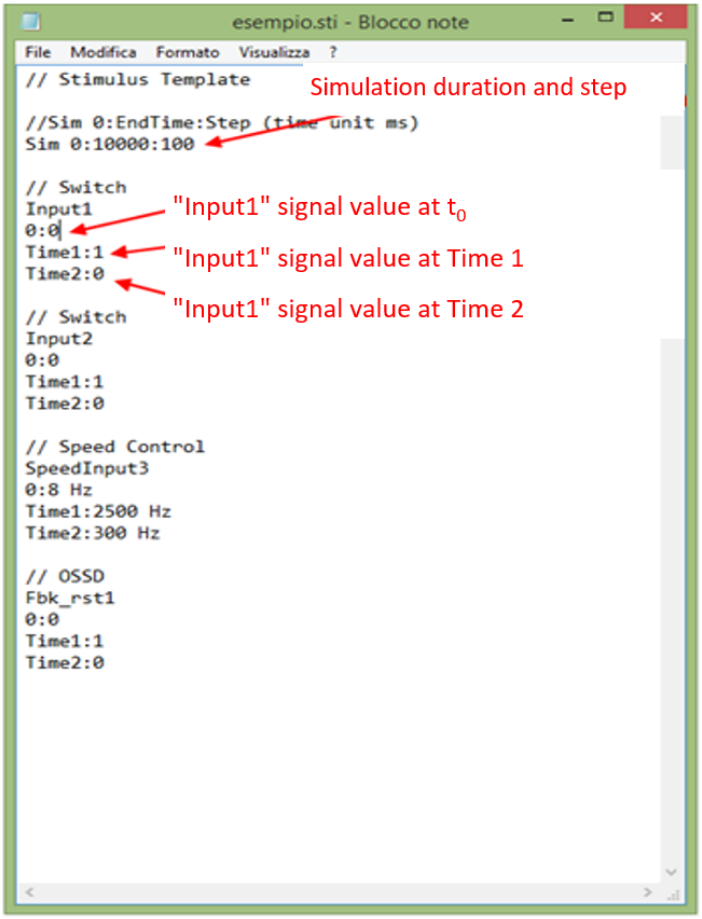


Figure 73 – Template file immediately after saving

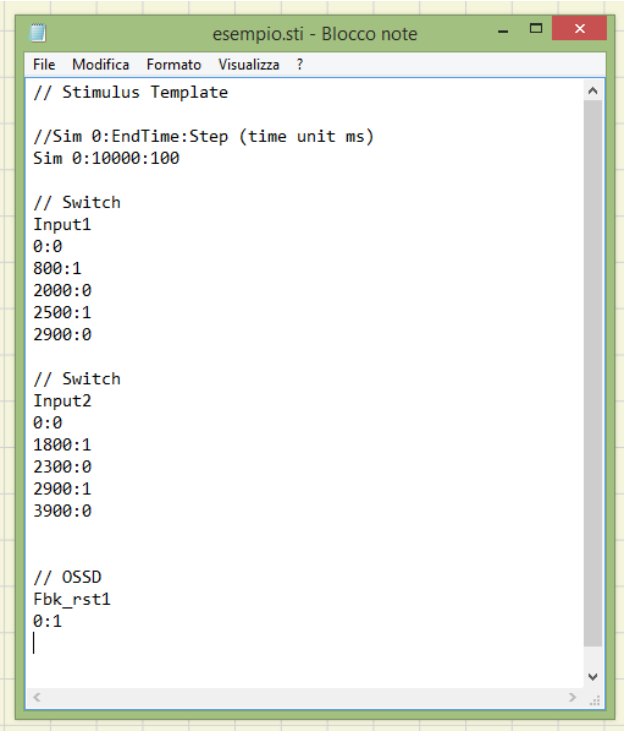


Figure 74 –Example of complete template file

Simulation with Stimuli: used to load a template file (suitably completed) and, once loaded, to immediately start the simulation.
At the end of the simulation, a graph is displayed with the resulting signals.

Load simulation: used to load a previously completed simulation, provided at least one has been saved.

English

Traces visibility: used to select the traces (signal waveforms) to be displayed in the graph. When you press this key, it opens a pop-up window as shown in Figure 75 from which you can add or remove traces to or from the graph.

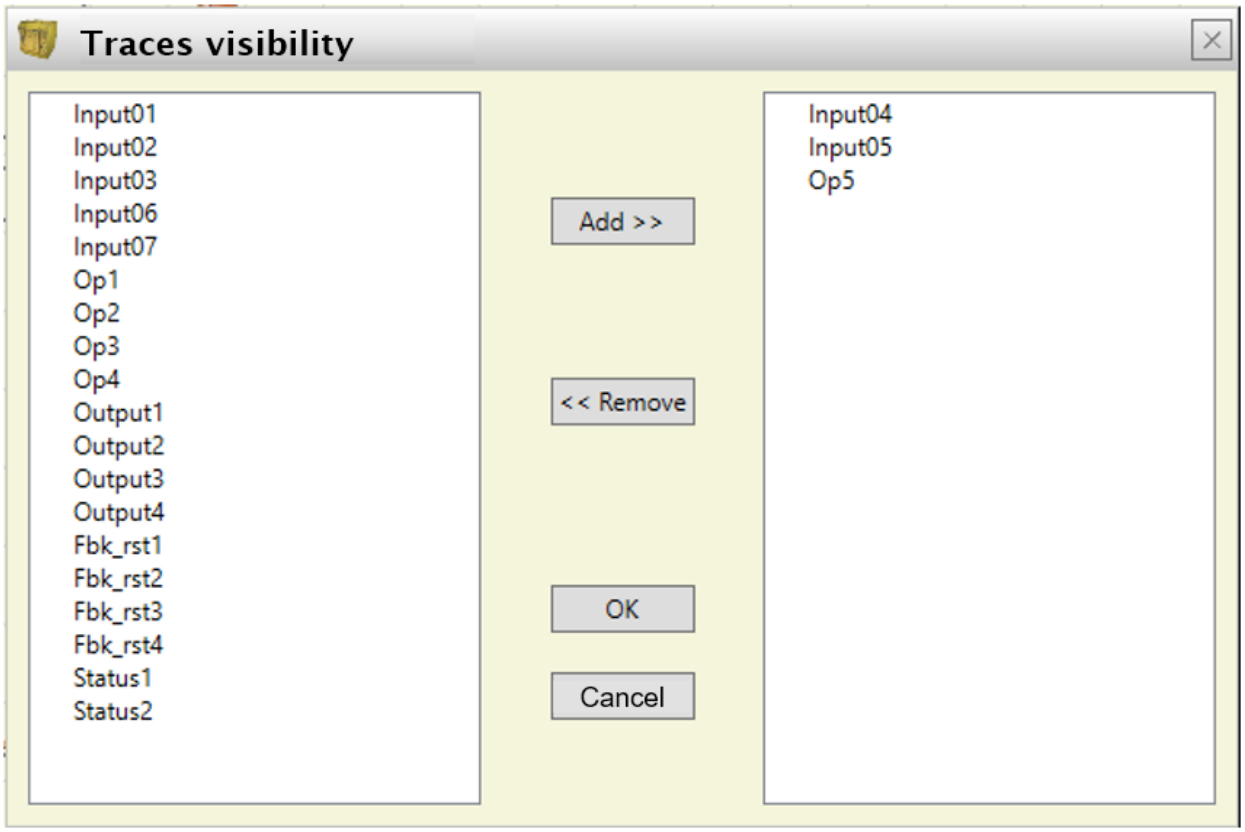


Figure 75 - Traces visibility.

➔ The traces that can be added to the graph are shown in the box on the left. The traces currently displayed and which can be removed from the graph are shown in the box on the right.

English

Application example of graphic simulation

The following example refers to the use of a press located inside a safety area. The motor of the press can only be started when two conditions are simultaneously true: the safety area gate is closed and the command to start the motor is sent. The motor will start two seconds after the start signal is sent.

Diagram

In the diagram the input elements are the safety area gate and the motor start command. These two signals are used as the input for an AND logic operator the result of which will be delayed by two seconds by a retarder block. The delayed signal will then energise the relay which will, in turn, allow the press motor to be started.

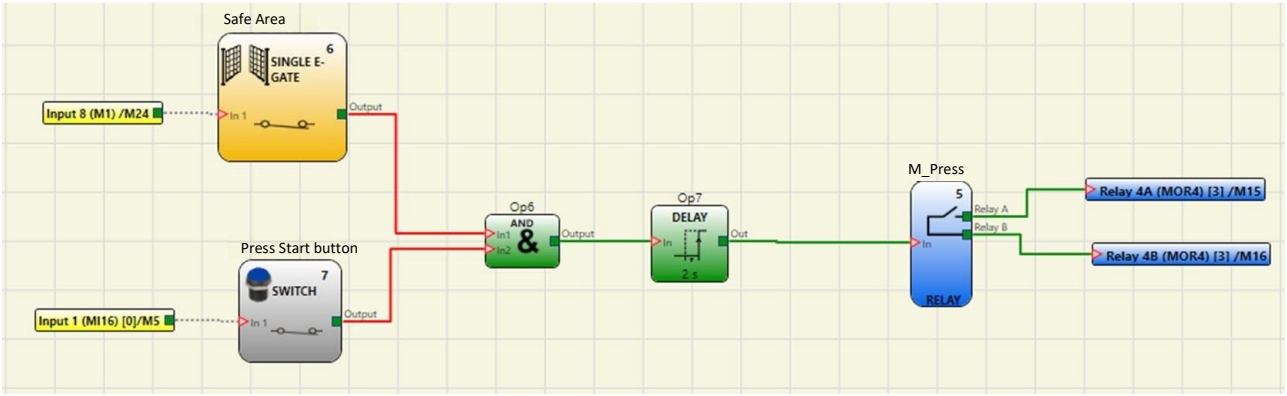


Figure 76 - Diagram referring to the application example

Stimuli file

The stimuli file provide the closure of the gate when 2000 ms have elapsed (signal set to LL1) and the start command sent by the operator when 3000 ms have elapsed (signal set to LL1).

```
1  // Stimulus Template
2
3  //Sim 0:EndTime:Step (time unit ms)
4  Sim 0:10000:100
5
6  // Single E-Gate  - Safe Area Gate
7  Input6
8  0:0
9  2000:1
10 10000:0
11
12 // Switch  Press Start button
13 Input7
14 0:0
15 3000:1
16 10000:0
```

comments entered by the user

Figure 77 - Stimuli file referring to the application example

Result of the simulation

The graph shows the signals relating to the simulation, in this case:

- when 2000 ms have elapsed the “Safety area" signal rises to logic level 1, which indicates closing of the gate.
- when 3000 ms have elapsed the “Start_Press" signal rises to logic level 1, which indicates the request to start sent by the operator
- The AND operator output signal “Op6” rises to logic level 1 when 3000 ms have elapsed, i.e., when the two “Safety area” and “Start_Press” inputs rise to logic level 1.
- The AND operator output signal is delayed by 2000 ms by the delay operator.
- The "Op7" retarder output signal sends the command to close the relay when 5000 ms have elapsed, at which time the "M-press" relay is activated.

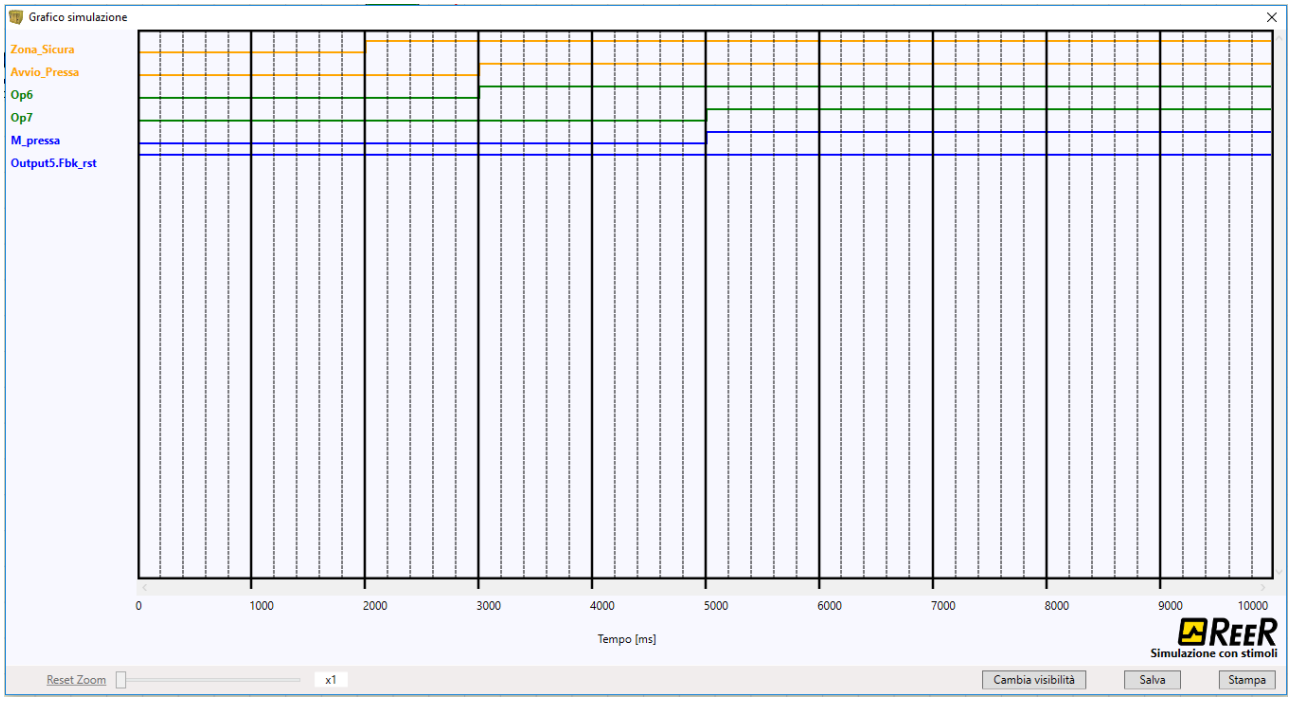


Figure 78 - Graph produced by the simulation of the application example

English

MOSAIC FAIL CODES

In case of malfunction the Mosaic system transmits to the MSD software a code corresponding to the error detected by the master M1.
To read the code, proceed as follows:

- connect the Master M1 (indicating FAIL by led) to the PC using the USB cable;
- launch the software MSD;
- use the icon for the connection; a window appears to request the password; enter the password; a window appears with the error code occurred.

The following table lists all possible errors detected and their solution.

CODE	FAIL	RESOLUTION
19D, 20D	*The two M1microcontrollers do not see the same hw/sw configuration*	CHECK CORRECT INSERTION OF M1 AND EXPANSION MODULES CONNECTORS MSC. POSSIBLY REPLACE THE CONNECTORS. IF MCT IS PRESENT, CHECK CONNECTION
66D	*2 or more same expansion modules with the same node number*	CHECK THE CONNECTIONS PIN 2, 3 EXPANSION MODULES
68D	*Exceeded max expansion modules number*	DISCONNECT THE MODULES IN EXCESS (MAX14)
70D	*One or more modules have detected a change in the node number*	CHECK THE CONNECTIONS OF PIN 2, 3 EXPANSION MODULES
73D	*A slave module has detected an external error*	CHECK THE ERROR CODE ON MODULE FOR MORE INFORMATION
96D ÷ 101D	*Errors related to memory MCM*	REPLACE MCM MEMORY
137D	*from a MOR4 MOR4S8 - EDM error on the couple RELAY1 and 2 used in Category 4*	CHECK THE CONNECTION OF THE EXTERNAL FEEDBACK CONTACTORS
147D	*from MOR4 MOR4S8 - EDM error on the Relay 2 and 3 used in Category 4*	CHECK THE CONNECTION OF THE EXTERNAL FEEDBACK CONTACTORS
157D	*from a form or MOR4 MOR4S8 - EDM error on the Relay 3 and 4 used in Category 4*	CHECK THE CONNECTION OF THE EXTERNAL FEEDBACK CONTACTORS
133D (Proxi1) 140D (Proxi2)	*From a module MV2, MV1 or MV0: over-frequency detected on Proximity input*	THE INPUT FREQUENCY MUST BE $\leq$ 5KHz
136D (Encoder1) 143D (Encoder2)	*From a module MV2, MV1 or MV0: encoder input signals not Standard (duty cycle, phase displacement)*	THE DUTY CYCLE MUST BE: 50% $\pm$33% OF THE PERIOD (HTL, TTL). THE PHASE DISPLACEMENT MUST BE: 90°$\pm$45° (HTL, TTL) (not applicable to SIN / COS)
138D (Encoder1) 145D (Encoder2)	*From a module MV2, MV1 or MV0: over-frequency detected on Encoder input*	THE INPUT FREQUENCY MUST BE: $\leq$ 500KHz (TTL, SIN/COS); $\leq$ 300KHz (HTL).
194D 197D 198D 199D 201D 202D 203D 205D	*Errors solid state output OSSD1*	CHECK THE OSSD1 CONNECTIONS RELATIVE TO THE MODULE IN ERROR
208D 211D 212D 213D 215D 216D 217D 219D	*Errors solid state output OSSD2*	CHECK THE OSSD2 CONNECTIONS RELATIVE TO THE MODULE IN ERROR
222D 225D 226D 227D 229D 230D 232D 233D	*Errors solid state output OSSD3*	CHECK THE OSSD3 CONNECTIONS RELATIVE TO THE MODULE IN ERROR
236D 239D 240D 241D 243D 244D 245D 247D	*Errors solid state output OSSD3*	CHECK THE OSSD3 CONNECTIONS RELATIVE TO THE MODULE IN ERROR

All other codes are related to errors or an internal malfunction. Please replace the module that gave the error or return to ReeR for repair and/or debugging and inform REER at the time of shipment.

CODE	FAIL	SOLUTION
1D ÷ 31D	*Microcontroller Error*	TRY TO RESTART SYSTEM. IF ERROR PERSISTS, SEND UNIT TO REER LABORATORY FOR REPAIR.
32D ÷ 63D	*Mainboard error*	
64D ÷ 95D	*Communication error between units*	
96D ÷ 127D	*MCM memory card error*	REPLACE MCM MEMORY CARD
128D ÷ 138D	*Error module MOR4 relay 1*	TRY TO RESTART SYSTEM. IF ERROR PERSISTS, SEND UNIT TO REER LABORATORY FOR REPAIR.
139D ÷ 148D	*Error module MOR4 relay 2*	
149D ÷ 158D	*Error module MOR4 relay 3*	
159D ÷ 168D	*Error module MOR4 relay 4*	
128D ÷ 191D	*Error units MV encoder interface*	TRY TO RESTART SYSTEM. IF ERROR PERSISTS, SEND UNIT TO REER LABORATORY FOR REPAIR.
192D ÷ 205D	*OSSD1 Error*	
206D ÷ 219D	*OSSD2 Error*	
220D ÷ 233D	*OSSD3 Error*	
234D ÷ 247D	*OSSD4 Error*	

English

ACCESSORIES AND SPARE PARTS

MODEL	DESCRIPTION	CODE
M1	MOSAIC main unit (8 inputs / 2 double OSSD)	1100000
MI8O2	MOSAIC I/O expansion unit (8 inputs / 2 double OSSD)	1100010
MI8	MOSAIC input expansion unit (8 inputs)	1100020
MI16	MOSAIC input expansion unit (16 inputs)	1100021
MI12T8	MOSAIC input expansion unit (12 input, 8 test output)	1100022
MO2	MOSAIC output expansion unit (2 double OSSD)	1100030
MO4	MOSAIC output expansion unit (4 double OSSD)	1100031
MR2	MOSAIC safety relay unit (2 relays)	1100040
MR4	MOSAIC safety relay unit (4 relays)	1100041
MOR4	MOSAIC safety relay expansion unit (4 relays)	1100042
MOR4S8	MOSAIC safety relay expansion unit (4 relays, 8 test outputs)	1100043
MOS8	MOSAIC output expansion unit (8 test outputs)	1100091
MOS16	MOSAIC output expansion unit (16 test outputs)	1100092
MBP	MOSAIC PROFIBUS DP interface unit	1100050
MBD	MOSAIC DeviceNet interface unit	1100051
MBC	MOSAIC CANopen interface unit	1100052
MBEC	MOSAIC ETHERCAT interface unit	1100053
MBEI	MOSAIC ETHERNET/IP interface unit	1100054
MBEP	MOSAIC PROFINET interface unit	1100055
MBMR	MOSAIC MODBUS RTU interface unit	1100082
MBEM	MOSAIC MODBUS TCP interface unit	1100083
MBEI2B	MOSAIC ETHERNET/IP 2 PORT interface unit	1100085
MCT2	MOSAIC BUS TRANSFER interface unit (2 channels)	1100058
MCT1	MOSAIC BUS TRANSFER interface unit (1 channel)	1100057
MCM	MOSAIC external configuration memory	1100060
MSC	MOSAIC connector for 5-way communication	1100061
CSU	MOSAIC USB cable for connection to PC	1100062
MV1T	MOSAIC TTL expansion unit	1100070
MV1TB	MOSAIC TTL expansion unit	1100086
MV1H	MOSAIC HTL expansion unit	1100071
MV1S	MOSAIC SIN/COS expansion unit	1100072
MV2T	MOSAIC TTL expansion unit (2 encoders)	1100073
MV2TB	MOSAIC TTL expansion unit (2 encoders)	1100087
MV2H	MOSAIC HTL expansion unit (2 encoders)	1100074
MV2S	MOSAIC SIN/COS expansion Unit (2 encoders)	1100076
MV0	MOSAIC proximity expansion unit	1100077

WARRANTY

ReeR warrants that all of its MOSAIC units shall be free from defects in material or workmanship for a period of 12 (twelve) months from the date of shipment. This warranty applies to the products under normal conditions of use.
If the product proves to be defective during the warranty period, ReeR will repair or replace any faulty parts without any charge for material or labour.
ReeR S.p.A. may, at its discretion, replace the defective equipment with the same type of equipment or with equipment having the same characteristics, rather than repair it.

This warranty is subject to the conditions listed below:
The customer must inform ReeR of the fault within twelve months from the date of delivery of the product.
The equipment and all components must be in the condition as they were at the time of delivery by ReeR.
The fault or defect must not been caused either directly or indirectly by:

- Improper use;
- Failure to comply with the instructions for use;
- Carelessness, misuse, incorrect maintenance;
- Repairs, modifications, adaptations not performed by ReeR, tampering, etc.;
- Accidents or collisions (also during transportation and as a result of force majeure);
- Other causes for which ReeR cannot be held liable.

The defective equipment must be delivered or shipped to ReeR's works to be repaired: the warranty does not cover costs of transport or the risk of damage to or loss of the equipment during shipment, which shall be borne by the customer.
All products and components that are replaced become the property of ReeR.
ReeR shall not be held liable under any other warranties or rights except for those expressly indicated above. ReeR shall not therefore accept claims to pay damages for expenses, interruption of work or other factors or circumstances in any way related to failure of the product or any parts thereof.

Please, visit the website www.reer.it for the list of the authorised representative of each Country.

Precise, complete compliance with all standards, instructions and warnings in this handbook is essential for the correct operation of the device. ReeR therefore declines any responsibility for all and anything resulting from failure to comply with all or some of the aforesaid instructions.

English

CE

Dichiarazione CE di conformità

EC declaration of conformity

Torino, 28/06/2016

REER SpA
via Carcano 32
10153 – Torino
Italy

dichiara che il controllore integrato MOSAIC costituisce un dispositivo di sicurezza realizzato in conformità alle seguenti Direttive Europee:
declares that the integrated controller MOSAIC is a safety device complying with the following European Directives:

2006/42/EC	"Direttiva Macchine" *"Machine Directive"*
2014/30/EU	"Direttiva Compatibilità Elettromagnetica" *"Electromagnetic Compatibility Directive"*
2014/35/EU	"Direttiva Bassa Tensione" *"Low Voltage Directive"*

ed è conforme alle seguenti norme:
and complies with the following standards:

EN 61131-2 (2007)	Controllori programmabili - Parte 2: Specifiche e prove delle apparecchiature. *Programmable controllers - Part 2. Equipment requirements and tests.*
EN ISO 13849-1 (2008)	Sicurezza del macchinario: Parti dei sistemi di comando legate alla sicurezza. Parte 1: Principi generali per la progettazione. *Safety of machinery:- Safety-related parts of control systems - Part 1: General principles for design.*
EN 61496-1 (2013)	Sicurezza del macchinario: Dispositivi Elettrosensibili di protezione, Parte 1: Requisiti generali e tests. *Safety of machinery : Electro sensitive protective equipment, Part 1: General requirements and tests.*
EN 61508-1 (2010)	Sicurezza funzionale di impianti elettrici/elettronici/programmabili legati alla sicurezza: Requisiti generali. *Functional safety of electrical/electronic programmable electronic safety related systems: General requirements.*
EN 61508-2 (2010)	Sicurezza funzionale di impianti elettrici/elettronici/programmabili legati alla sicurezza: Requisiti per impianti elettrici/elettronici/programmabili legati alla sicurezza. *Functional safety of electrical/electronic/programmable electronic safety related systems: Requirements for electrical/electronic/programmable electronic safety-related systems.*
EN 61508-3 (2010)	Sicurezza funzionale di impianti elettrici/elettronici/programmabili legati alla sicurezza: Requisiti Software. *Functional safety of electrical/electronic programmable electronic safety related systems: Software requirements.*
EN 61508-4 (2010)	Sicurezza funzionale di impianti elettrici/elettronici/programmabili legati alla sicurezza: Definizioni e abbreviazioni. *Functional safety of electrical/electronic programmable electronic safety related systems: Definitions and abbreviations.*
IEC 61784-3 (2008)	Reti di comunicazione industriali - Profili - Parte 3: Sicurezza funzionale dei bus di campo - Norme generali e profilo definizioni. *Industrial communication networks - Profiles - Part 3: Functional safety fieldbuses - General rules and profile definitions.*
EN 62061 (2005)	Sicurezza del macchinario. Sicurezza funzionale dei sistemi di comando e controllo elettrici, elettronici e programmabili correlati alla sicurezza. *Safety of machinery - Functional safety of safety-related electrical, electronic and programmable electronic control systems.*

raggiungendo il livello di sicurezza pari a: SIL 3 / SILCL 3 / PL e/ Cat. 4 / Tipo 4 (v. standard corrispondenti)
reaching a safety level corresponding to: SIL 3 / SILCL 3 / PL e / Cat. 4 / Type 4 (see related standards)

ed è identico all'esemplare esaminato ed approvato con esame di tipo CE da:
and is identical to the specimen examined and approved with a CE - type approval by:

TÜV SÜD Product Service GmbH – Zertifizierstelle – Ridlerstraße 65 – 80339 – München – Germany
N.B. number: 0123 – Certificate No. Z10 14 05 24820 049

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English